

1 Precision ecology for targeted conservation action

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21 **Abstract**

22 Addressing the coupled threats of catastrophic climate change and biodiversity loss requires
23 implementation of conservation and restoration actions globally. However, on-the-ground
24 action is hindered by context dependency: the ubiquitous challenge that implementation
25 outcomes vary from place to place due to complex dependencies among social and ecological
26 drivers. Policymakers and practitioners recognise the need to tailor solutions to contexts, and
27 target actions to places where they will work effectively. To provide information for decision
28 making, applied ecologists can learn from medicine and marketing, which aim to provide
29 healthcare tailored to individual patients, and advertisements targeting individual tastes.
30 These disciplines exploit big data and rapidly developing computational advances to predict
31 treatment effects for individual units. Here we argue why and how ecological disciplines can
32 begin to capitalise on these rich advances, to equip ecologists with a potentially powerful
33 toolkit for applying big data to site-specific interventions, allowing effective conservation
34 over large extents. We review approaches that hold promise for applied ecology, identify
35 hurdles that must be overcome, and propose a roadmap for establishing the conditions that
36 will permit adoption of precision ecology.

37

38 *Keywords:* Conditional average treatment effect, context dependence, heterogeneous
39 treatment effects, individual treatment effect, propensity score, uplift modelling

40 **Introduction**

41 Environmental sustainability transformations are needed on a global scale¹. Implementing
42 ecological transformations happens at the local scale, by restoring, conserving, and managing
43 individual ecosystems. Decision-makers are faced with difficult choices of how and where to
44 invest limited resources. Scientists, policymakers and practitioners have long-recognised the
45 futility of silver bullet, ‘one-size-fits-all’ strategies², the need to embrace complexity and
46 context³, the desirability of targeting actions to contexts where they will be most effective,
47 and of developing place-based action plans tailored to individual sites⁴. For example,
48 international tree planting initiatives often emphasise the need to plant ‘the right tree in the
49 right place’ to achieve Net Zero⁵, because the wrong trees planted in the wrong place may fail
50 to establish, or worse, lead to net carbon emissions that persist for decades⁶.

51 Effective targeting is challenging to achieve in practice because nature is complex. Applied
52 ecologists aiming to develop guidance for policymakers must deal with ‘context
53 dependence’: the unavoidable geographical and temporal variability in ecological responses
54 to restoration, conservation, and management actions (hereon ‘treatments’), according to
55 local social-environmental conditions. For example, impacts of organic farming on
56 biodiversity depend on surrounding landscape structure⁷, while relationships between
57 biodiversity and ecosystem function depend on global-change drivers such as drought⁸.
58 Successful targeting and tailoring of treatments requires predictions of treatment effects on
59 biodiversity and ecosystem functions, accounting for the environmental characteristics of
60 these sites.

61 Applied ecologists do not currently generate causal predictions of treatment effects
62 conditional on their site-level conditions, tending instead to focus either on making causal
63 estimates of average treatment effects across all sites in a sample, or on site-level estimates of
64 effects that are not conditioned on site-level covariates (e.g., by estimating random effects for
65 sampled sites in multilevel models). However, if treatment effects vary in both magnitude
66 and direction across all sampling units, average treatment effects are not actionable, nor are
67 site-level estimates unlinked to site conditions. In human-centred disciplines such as
68 medicine, behavioural sciences, and marketing, practitioners ask “what works, for whom, and
69 under what conditions?”^{9,10}. In questions of applied ecology, policymakers and practitioners
70 ask, “what works, where does it work, and under what conditions?”, or “where should I
71 intervene in order to have greatest effect for least resource expenditure”, for example: “Will *this*

72 treatment improve carbon sequestration in *this* woodland, or, *which* woodland sites would
73 sequester the greatest amount of carbon, if treated in this way?”¹¹.

74 Crucially, such lines of questioning ask about treatment effects for specific units, not about
75 estimates of the average treatment effect across all units in a population¹², nor about unit-
76 specific predictions of outcomes under a single treatment level (i.e., without intervention).
77 Human-centred disciplines have begun to transform unit-specific prediction of treatment
78 effects into thriving areas of research, notably in precision medicine¹³ and marketing¹⁴, to
79 predict treatment effects on the health of patients, and advertising effects on the purchasing
80 behaviour of potential customers. Given the urgent need to achieve nature recovery, here we
81 argue that the time is ripe to adapt this approach to applied ecology, where it can serve to
82 narrow the enduring gap between scientific knowledge and policy needs (Table 1). Unit-
83 specific treatment effects can be used to tailor a medical drug therapy for particular patients,
84 or to personalise advertising for targeted consumers. For applied ecology, each sampling unit
85 is not a person but a location relevant to a particular grain (‘site’ from hereon), such as a
86 forest stand, lake, grassland, or arable field. Unit-specific treatment effects could target
87 restoration actions such as tree planting or assisted regeneration to sites where, for example,
88 the most carbon would be sequestered, or where the treatment would contribute most to
89 biodiversity conservation. Unit-specific treatment effects would also help to forecast how
90 particular types of ecosystems in different areas are likely to respond to disturbances, such as
91 fire and pest outbreaks, as they increase in frequency and intensity with global environmental
92 change¹⁵. Several hurdles remain to be overcome, both general and ecology-specific, to
93 optimise methodologies for predicting unit-specific treatment effects. In this Perspective, we
94 review approaches that hold promise for applied ecology, identify issues and caveats that
95 must be confronted prior to their adoption, and propose a roadmap for establishing the
96 prospects for precision ecology.

97 Table 1. **Prediction of unit-specific treatment effects are currently a focus of investigation in**
 98 **medicine and marketing, and hold great potential for applied ecology.** Here we compare two
 99 examples from medicine¹⁶ and marketing¹⁷ with two potential applications from aquatic and
 100 terrestrial applied ecology.

	Medicine	Marketing	Potential application in ecology	
Context and reason for unit-specific treatment effect prediction	It is important to understand the heterogeneity in survival benefits of ventricular assistance devices in order to improve the current transplant priority allocation scheme ¹⁶ .	Advertising resources are wasted on individuals who will never buy a product, or who will buy regardless of advertising. Targeting advertisements to individual consumers will increase return on investment ¹⁷ .	Vegetation buffer zones are costly and vary in their effectiveness at maintaining aquatic biodiversity in catchments with surface water pollution. Where they are ineffective, alternate measures should be implemented.	Maintaining or increasing soil carbon by restoration could have many benefits for climate change mitigation, adaptation, and biodiversity conservation, yet restoration effects are highly variable. Areas where restoration actions result in large losses should be avoided.
Sampling units in sample	Patient awaiting heart donation	Potential customer	Lake	Forest stand
Data source	The United Network for Organ Sharing (UNOS) dataset	Marketing dataset obtained from Kevin Hillstrom's MineThatData blog ¹⁸	National or citizen-science monitoring schemes Nutrient loading data.	Remote sensing National or citizen-science monitoring schemes
Reference sample	Patients	Customers	Lakes distributed across broad geographic extent	Forest stands distributed across a heterogeneous covariate landscape
Outcome	5-year survival probability of patients awaiting a heart donor	Amount of money spent purchasing products	Eutrophic status or presence of indicator taxa	Soil organic carbon tonnes/ha
Treatment (X)	Fitted with a Left Ventricular Assistance Device	Receives email from an internet-based retailer campaign	Planting of vegetation buffer zones	Restoration by stand thinning
Example covariates (Z) that influence treatment outcomes or assignment	Age; sex; comorbidities (e.g., diabetes); body mass index.	Amount of money spent in the previous year; date of last purchase; rural, suburban, urban zip code.	Size; depth; composition and configuration of catchment-level land uses; topography; climate; atmospheric deposition of pollutants.	Soil type and drainage; stand density; climate; topography; previous management; stand density; proportion of basal area contributed by different species.
Target	Current patients requiring transplant	Individual customers from reference sample	Currently untreated individual lakes in sample and out of sample	Currently untreated individual stands in sample and out of sample

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103 **Treatment effects: from estimating population averages to**
104 **predicting individual, site-specific outcomes**

105 Questions about treatment effects require causal-inference methods that have roots in the
106 ‘potential outcomes framework’, in which treatment effects are derived from counterfactual
107 comparisons of outcomes that would result from alternative treatment levels (labelled
108 treatment and control). Suppose we are interested in the causal effect of forest thinning on
109 soil carbon in the i th forest stand (Figure 1, top). In this example, the causal treatment can
110 take only two values: an unthinned control ($X_i = 0$, where X corresponds to the treatment) or
111 a thinned treatment ($X_i = 1$). When the plot is a control, its soil carbon outcome is $Y_i^{X=0}$.
112 When the same plot is treated, its outcome is $Y_i^{X=1}$. Both $Y_i^{X=0}$ and $Y_i^{X=1}$ are called potential
113 outcomes because either one is potentially observable. The difference between these potential
114 outcomes is the plot-level causal effect of thinning, i.e., the individual treatment effect for
115 plot i .

116 The Fundamental Problem of Causal Inference¹⁹ is that we can never observe both potential
117 outcomes, nor the associated treatment effect, for any individual unit (here a plot). To address
118 this missing data problem, the potential outcomes framework typically considers how to
119 estimate average effects. In a randomised controlled trial (RCT), because of random
120 assignment, we can get an unbiased estimate of the average of these individual treatment
121 effects, called the **Average Treatment Effect (ATE)**. Thus, RCTs often focus on estimating
122 the ATE, and are widely used when testing agricultural intervention effectiveness²⁰, and in
123 fields including medicine, political science²¹ and ecology²². However, because the sample in
124 the RCT is never truly a random sample of any specific target population, generalising this
125 ATE to other units outside of the RCT is much harder. That is, while the ATE estimate is
126 unbiased for the units within the sample, it may be a biased estimate of the ATE for a broader
127 population of units outside of the sample.

128 This generalisability problem arises when treatment effects vary across individuals. Unit-
129 specific effects can differ in both magnitude and sign from the population ATE (Figure 1).
130 The distribution of a treatment effect across sampling units is shifted and shaped by baseline
131 differences and variability in the direction and magnitude of treatment effects across
132 individual sampling units. Accordingly, several scientific fields attempt to estimate
133 **Conditional Average Treatment Effects (CATEs)**, the expected treatment effect for a
134 sampling unit, conditional on the average covariate profile for the unit’s subgroup¹³, i.e., the

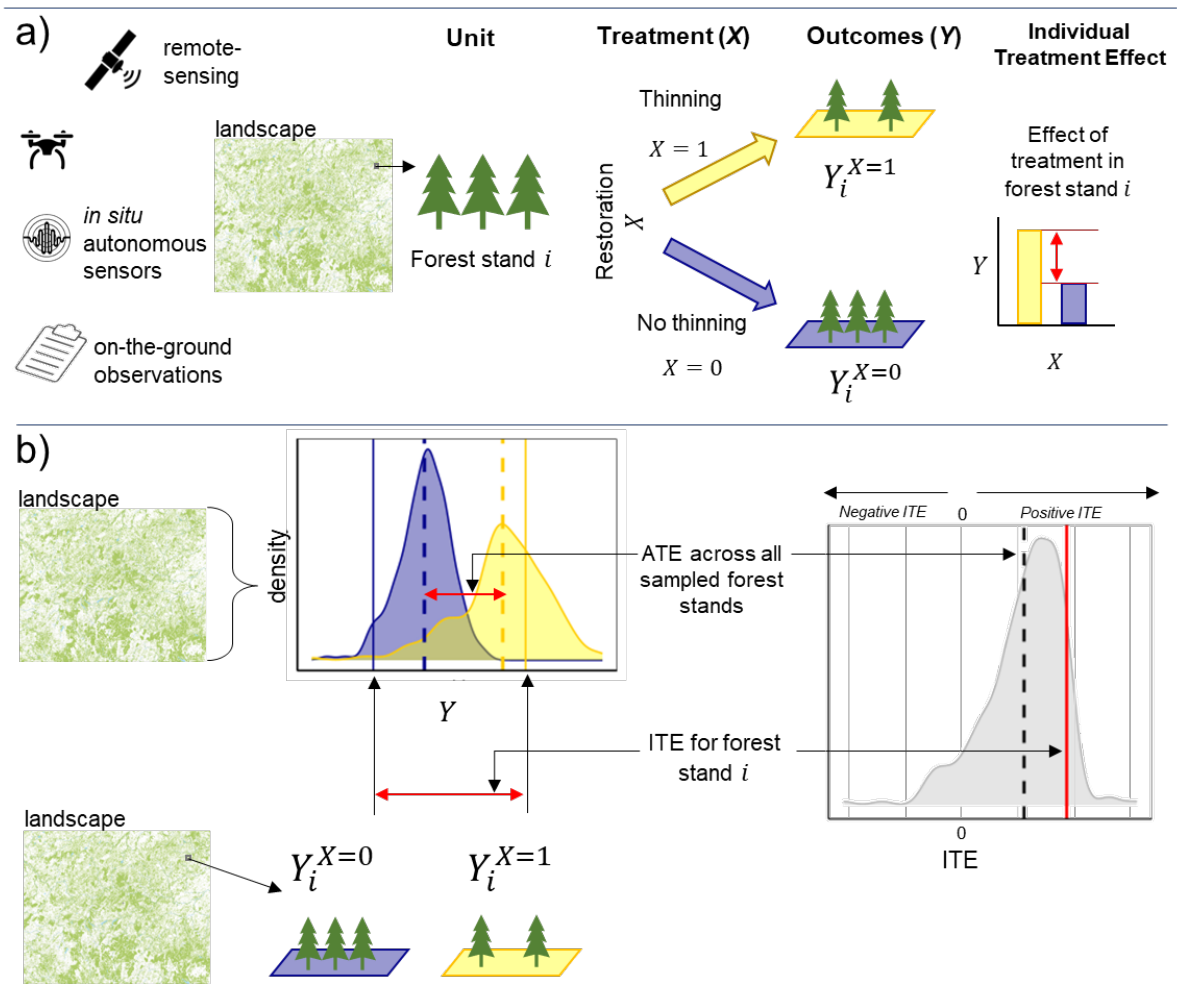
135 treatment effect among individuals with the same vector of covariates values. As an estimate,
136 CATE relies on each treatment level-by-population subgroup having sufficient cases to
137 reliably estimate the effect, which is often unachievable. The CATE nevertheless holds
138 special interest for researchers because it enables an understanding of how treatment effects
139 vary depending on the observed characteristics of each sampling unit, allowing treatments to
140 be targeted effectively to units.

141 The simplest methods for estimating CATEs include stratification into subgroups or fitting
142 models containing statistical interactions²³. If the number of covariates is small, and all
143 covariates are discrete (e.g., tree species, the presence of a ditch) stratification can be
144 effective. But if covariates are numerous and continuous (e.g., rainfall, forest age), they are
145 often either made discrete and estimated using stratification, or are (parametrically) interacted
146 with the treatment effect in pre-specified regression models, e.g., generalised linear
147 (multilevel) models. Multi-level models (and meta-regression) can estimate effects for
148 clusters of sampling units within a sample, yet unless the sample is a random sample from the
149 target population, this approach does not work for predicting effects in the target. For
150 interactions, the researcher must make choices and assumptions about which covariates to
151 include, their functional forms, and how to specify treatment-by-covariate interactions²⁴.
152 Often, researchers using these approaches focus on hypothesis testing, not prediction, though
153 these same methods could be used for predictive purposes. If so, they would be contingent
154 upon the model selected (by the analyst) and the parametric assumptions of that model.

155 CATEs only partly address the generalisability problem. They provide a means to estimate
156 subgroup ATEs within the sample included in the RCT. But for policymaking and decision
157 making – e.g., which medical intervention to use, which advertisement should be used for
158 different individuals, or which forests to target for restoration actions – the goal is not one of
159 estimation within the sample, but instead one of predicting unit-specific treatment effects
160 (often referred to as individual treatment effects: henceforth ‘ITEs’) *outside the sample*. The
161 prediction of treatment effects for individual units – what is called ‘causal prediction’ – is a
162 relatively new field and combines causal inference approaches with predictive methods.
163 Causal prediction is a harder problem than either the ATE or CATE prediction of outcomes
164 alone, because it is impossible to observe the individual treatment effects that are desired.
165 Nonetheless, flexible methods of predicting ITEs are under rapid development in fields
166 including precision medicine and marketing, which use large datasets and non-parametric
167 models that make no assumptions about the parametric form of the relationship between

168 treatment effects and covariates. Among the nonparametric approaches available, the
169 machine learning toolbox for ITE prediction is expanding rapidly^{13,25,26}.

170 Here we limit our discussion to binary treatments (e.g., intervention and control), noting that
171 multiple treatment arms and continuous treatments are conceptually possible within the
172 potential outcomes framework. Nevertheless, methods for binary treatments remain the most
173 developed²⁷, with less emphasis on unit-specific prediction for continuous treatment effects
174 from observational data²⁸. In applied ecology, continuous treatments might include thinning
175 intensity, fire intensity, riparian buffer width, etc.



176

177 **Fig. 1. Individual treatment effects can differ in magnitude and sign from the average treatment**
 178 **effect.** Here shown is a hypothetical field experiment, in which a binary treatment X (forest thinning vs
 179 no thinning) is applied to forest stands across a heterogeneous covariate landscape. a) Data from
 180 multiple sources characterise forest stands across a broad geographic extent (left). For a specific
 181 stand i , we can consider the potential outcomes (Y) without ($Y_i^{X=0}$; blue) and with restoration thinning
 182 treatments ($Y_i^{X=1}$; yellow). Outcomes might relate to soil organic carbon, biodiversity, or probability of
 183 invasive species establishing. The difference between them corresponds to that stand's unit-specific,
 184 individual treatment effect (ITE). b) The distributions of outcome (Y) show the potential outcomes for
 185 all forest stands with ($X = 0$; blue) or without ($X = 1$; yellow) restorative thinning, and the distributions
 186 of unit-specific ITEs for all forest stands, demonstrating heterogeneity in treatment effects (grey). The
 187 coloured vertical dashed lines show the treatment geometric means for each treatment group; the
 188 difference between them represents the average treatment effect (ATE). The continuous lines show
 189 the potential outcomes after being treated (yellow) or not treated (blue) for one particular forest stand
 190 i , and the resulting unit-specific treatment effect. Here, the ITE for forest stand i (red line) is larger in
 191 magnitude than the ATE (dashed black line). Importantly, there are unit-specific ITE that are opposite
 192 in sign to the ATE.

193

194 **Assumptions required for predicting individual treatment effects**

195 ITE prediction is possible from a dataset of either design-based or observational origin, with
196 covariates Z that present a potential source of confounding variation. In observational studies,
197 Z needs to include all covariates related to the outcome Y and/or the assignment of treatment
198 X .

199 ITE prediction rests on the same three strong assumptions as those of ATE estimation.

200 ‘Unconfoundedness’ (or selection on observables) assumes there are no unobserved
201 confounding variables that determine treatment allocation. ‘Positivity’ (or common support)
202 assumes that every unit has a non-zero probability of being in either treatment group. If not
203 met, differences in covariate overlap between the treatment groups may create regions in the
204 relevant covariate space without appropriate comparators, i.e., where only treated, or only
205 control, units are present. While positivity is implicitly fulfilled by a randomised design,
206 observational studies may not have common support. Positivity can be tested directly with
207 observational data, and induced by weighting on propensity score: the probability of a unit
208 being assigned to a particular treatment level given a set of observed covariates. Finally, the
209 ‘Stable Unit Treatment Value Assumption’ (SUTVA) is met when there is no interference
210 amongst units: one unit’s response to treatment is unaffected by other units’ assignments.
211 While SUTVA might seem restrictive, ecological studies that aim to infer causation are
212 typically designed with SUTVA in mind^{29,30}. For example, researchers might enforce a
213 particular distance or lag between units in recognition of spatial spillover and temporal
214 carryover effects, when units are influenced by neighbouring or prior treatments,
215 respectively, or they may aggregate smaller units into larger units (e.g. quadrats into sites,
216 streams into catchments).

217 For a binary outcome variable, the unit-specific treatment effect can be interpreted as the
218 predicted difference in probability of an outcome for an individual with covariate values z_i
219 under two different treatment conditions. In practice, there may not be sufficient cases with Z
220 $= z_i$ under both treatments to reliably predict unit-specific treatment effects. This brings us to
221 the need for a predictive model to smooth over the gaps in the observed set of all z_i across
222 both treatments.

223 **Approaches to ITE prediction: meta-learner algorithms**

224 A range of ITE prediction approaches has been developed to exploit heterogeneous covariate
225 data for diverse data types including RCTs and observational studies^{31,32}. These prediction
226 approaches are referred to as ‘meta-learner’ algorithms (see Box 1)³³. They can apply any
227 supervised learning or regression method (random forests, Bayesian additive regression trees,
228 neural networks, etc^{33–35}), although most often use machine learning. Here we describe four
229 meta-learners: S-, T- X- and R-learners³³ (Box 1). These algorithms differ in how they handle
230 treatment assignment X , and how they adjust for biases inherent to observational studies.

231 Meta-learners can be classified into the more simple ‘conditional mean regression methods’
232 of S- and T-learners, and the more complex ‘pseudo-outcome’ methods^{24,34,36} of X-, R- and
233 DR-learners. S- and T-learners do not account for selection biases; they predict ITEs
234 indirectly, by first predicting the potential outcomes ($Y_i^{X=1}$ and $Y_i^{X=0}$) separately, and then
235 taking the difference between these response surfaces. In other words, conditional mean
236 regression methods rely on estimating conditional mean functions Y only. Several studies in
237 medicine, marketing and statistics have used simulation to evaluate the relative performances
238 of different meta-learners under various sampling and data conditions^{25,33,36,37}. For
239 conditional mean regression methods, S-learners perform poorly when treatment and control
240 groups have very different covariate distributions causing positivity violations. Moreover, since
241 machine learning models may regularise to omit predictors with little influence, S-learners can bias
242 small-magnitude treatment effects to zero³³. T-learner models should generally perform better
243 than S-learners when the treatment effect is small or when the effects of covariates on
244 outcomes differ between control and treatment groups³⁶. However, a bias–variance trade-off
245 can arise when predicting treatment effects based on two separate outcome models (T-
246 learner); the larger sampling variance induced by data splitting may lead to more
247 misclassifications of binary outcomes than for the single-model S-learner³⁸.

248 The more advanced pseudo-outcome methods including X-, R- and DR-learners predict ITEs
249 directly using combined models with functions that attempt to account for selection bias¹³.
250 These meta-learners involve more steps, and they incorporate information from the
251 propensity score in order to increase statistical efficiency²⁵. Pseudo-outcome methods model
252 intermediate ITE predictions (‘pseudo-outcomes’) as a function of covariates, and thus can
253 remove some of the bias induced by regularisation and overfitting compared to the S-learner
254 and the T-learner. X-learners tend to perform better than conditional mean regression
255 methods in the presence of unbalanced treatment group sizes and sparsity in areas of
256 covariate space³³. The pseudo-outcome of the DR-estimator is ‘doubly-robust’, and it predicts

257 ITEs well provided either of the two outcome models is correctly specified²⁴. DR-learners
258 perform poorly if an important confounder is omitted, or if there are near violations of the
259 overlap assumption. R-learners are less sensitive to extreme propensity scores^{36,39}.

260 **Box 1. Meta-learners for predicting individual treatment effects**

261 Prediction of ITEs is possible when ecologists have site-level data on ecosystem outcomes of interest
262 (Y), related to biodiversity and ecosystem functioning (e.g., species occurrences, lake water quality),
263 information on treatments (X) that sites have been subjected to, and other environmental covariates
264 (Z) that also predict those outcomes. The table (Box 1 Figure 1a) shows an example dataset targeting
265 the effect of forest restoration (thinning) on soil organic carbon (SOC) 10 years after treatment (Y ,
266 tonnes/ha) as a function of covariates Z comprising mean annual rainfall (mm), temperature ($^{\circ}\text{C}$), pre-
267 treatment SOC, initial soil carbon (tonnes/ha), canopy and slope (%).

268 Meta-learners are model-agnostic algorithms that decompose the task of ITE prediction for binary
269 treatments into multiple sub-regression problems that can be solved using any modelling method,
270 such as supervised learning or regression. Of the several learners that have been developed, here we
271 describe four: S-, T-, X- and R-learners.

272 **S-learners (single-model learners)**

273 S-learners^{40,41} (Box 1 Figure 1b) are the simplest algorithms, similar to those currently used in
274 ecological modelling to predict outcome Y . S-learners predict ITEs indirectly by training a single
275 outcome model, M_s , to predict outcomes Y as a function of covariates Z , handling treatment X like any
276 other covariate in vector Z . The same model is used to predict outcomes for individual sampling units
277 i , forcing control ($X=0$) and treatment ($X=1$) conditions. For site i , the ITE is the difference in
278 predictions between the treatment and control, while holding all other covariate values fixed for the
279 individual site in question.

280 **T-learners (two-model learners)**

281 T-learners^{32,42,43} (Box 1 Figure 1c), or ‘two-model learners’ predict ITE indirectly by training two
282 outcome models, M_1 and M_0 to predict outcomes Y separately for treatment and control datasets,
283 respectively. Both models are used to predict outcomes for individual sampling units i , with the ITE as
284 the difference between these predicted outcomes.

285 **X-learners (cross-learners)**

286 X-learners³³ (Box 1 Figure 1d), predict ITEs directly, and are designed for observational studies where
287 positivity assumptions might otherwise be violated. Like T-learners, two outcome models are initially
288 fitted (M_1 and M_0) to predict outcomes Y separately for treatment and control datasets, respectively. A
289 propensity score model (M_{ps}) is also fitted, predicting the treatment probability ($X=1$) given Z . These
290 outcome models and propensity score models are often referred to as ‘nuisance functions’ in the
291 machine learning literature. Intermediate treatment effects are imputed from M_0 and M_1 , using Y and Z
292 for treated and control datasets respectively (hence the crossing over, Box 1 Figure 1d). A second
293 pair of models is fitted to predict these intermediate treatment effects. Finally, the predicted treatment
294 effects are adjusted by the propensity scores to predict ITEs. The adjustment puts more weight on
295 treatment effects that have been estimated more precisely, i.e. the ones coming from the larger
296 treated or control sample, respectively.

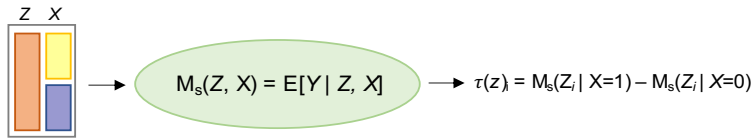
297 **R-learners (residualisation learners)**

298 Like the X-learner, the R-learner approach³⁹ (Box 1 Figure 1e) is also designed for observational
299 studies with selection bias, and so begins by fitting nuisance functions before training a model to
300 predict ITEs directly. The ‘R’ denotes the residualisation approach, and also recognises the
301 foundational work by Robinson (1988)⁴⁴. The R-learner first trains two models: a single outcome
302 model, M_r , to predict outcomes Y as a function of covariates Z (excluding the treatment indicator X),
303 and a propensity score model M_{ps} . It then residualises the outcome Y and treatment X by the
304 predictions of the M_r and M_{ps} , respectively, to construct a modified outcome (ϕ_i). In the second step,
305 the R-learner trains a modified outcome model on the covariates Z , weighted by the squared
306 residualised treatment to predict ITEs⁴⁵.

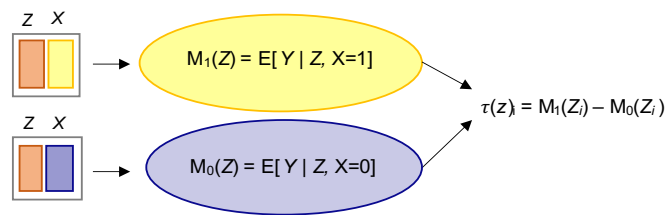
a) Example input dataset for meta-learner models

rainfall	temp	initial_ SOC	slope	treatment	SOC_ treated	SOC_ control
Z_1	Z_2	Z_3	Z_4	X	$Y_i^{X=1}$	$Y_i^{X=0}$
67	7.5	71	5	1	54	—
68	8.1	65	7	1	48	—
72	8.2	85	7	0	—	84
65	6.5	67	11	0	—	65

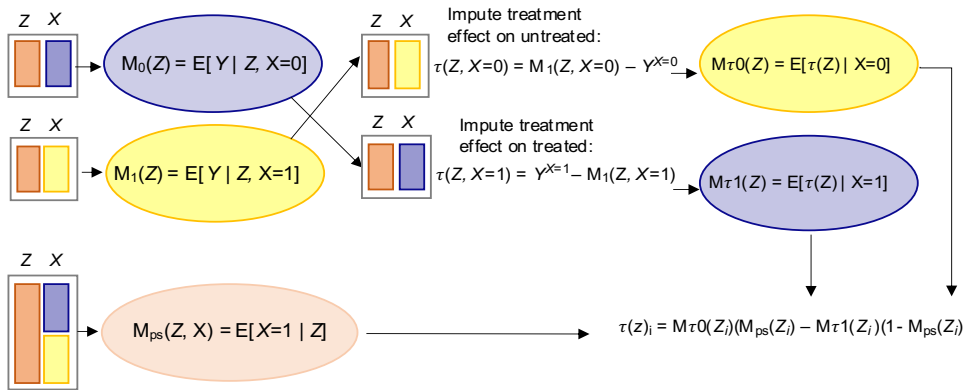
b) S-learner model



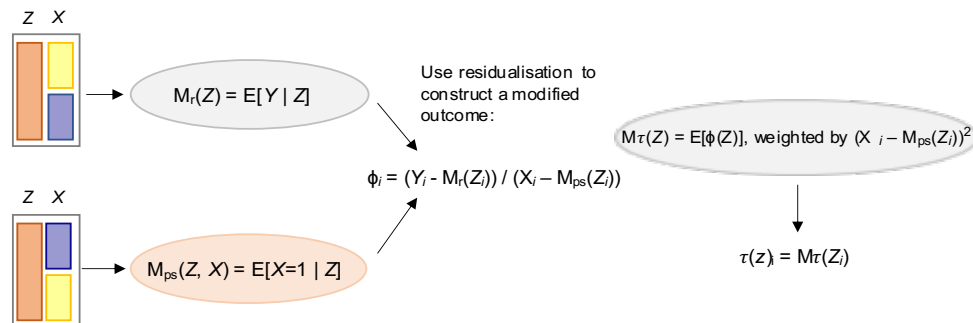
c) T-learner model



d) X-learner model



e) R-learner model



307

308 **Box 1 Figure 1. Alternative meta-learner models.** An example dataset (a) used to train different
 309 types of meta-learner models (b-e).

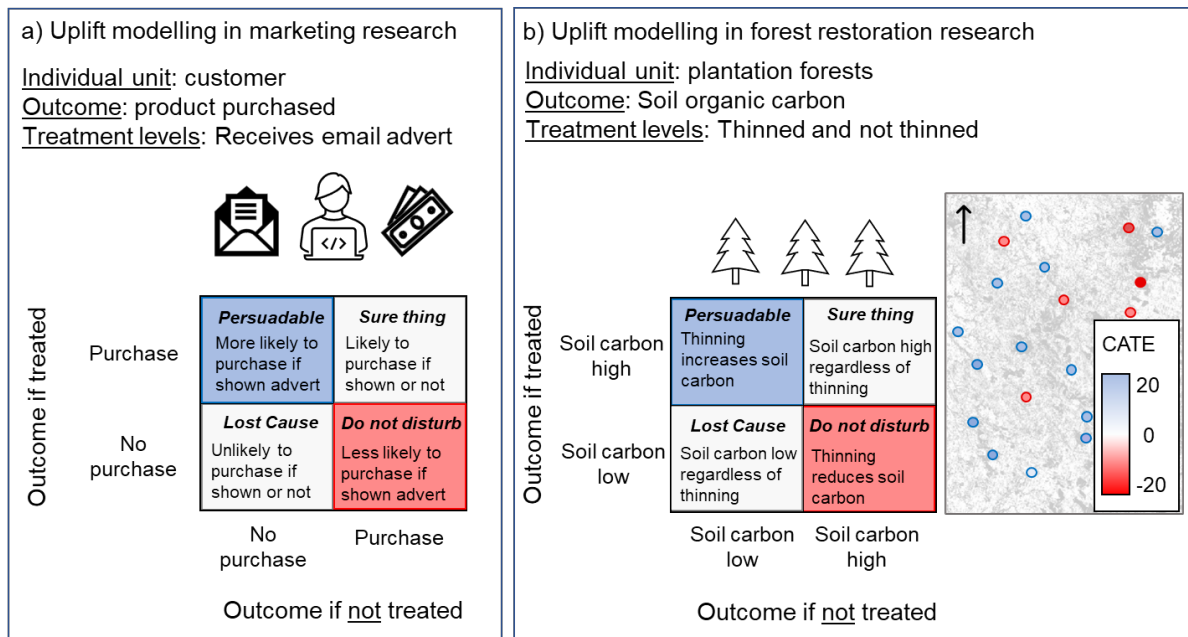
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311 **Unit-specific treatment effects enable tailoring and targeting of**
312 **interventions to specific locations**

313 A shift in applied ecology's focus to ITE predictions would provide options for improving the
314 efficacy of conservation, restoration, and management interventions. ITEs could support
315 decision-making at two scales. Firstly, at the site level (e.g., a forest stand within a protected
316 area), predicting treatment effects for *at least two different treatments* (i.e., management
317 actions), specific to the covariate profile of the site would enable selection of the treatment
318 that yields the greatest desired effect. Secondly, across broad extents (e.g. forest stands across
319 a nation), predictions of unit-specific treatment effects for *multiple sites* would allow policy-
320 makers with a fixed budget to prioritise the delivery of treatments to sites with the largest
321 ITEs for a given treatment (i.e., the top *N*th percentile of unit-specific treatment effects).
322 Finally, if unit-specific predictions for a given treatment are available for multiple *outcome*
323 variables (e.g., carbon storage, tree health, biodiversity), predictions could help to quantify
324 the trade-offs among these outcomes⁴.

325 ITE prediction could facilitate targeted action by classifying units according to the direction
326 and magnitude of the ITE. For example, uplift modelling, a family of techniques used in
327 marketing, seeks to predict 'uplift', the incremental impact of a treatment (a marketing
328 action) on an individual's behaviour. Uplift modelling classifies individual units (customers)
329 according to a binary treatment (whether shown an advert or not) and a binary outcome
330 (whether they purchase a product or not). Advertising resources are wasted on *Lost Causes*
331 and *Sure Things* and should be targeted to *Persuadables*: individuals that would buy only if
332 shown an advert; *Do Not Disturbs* should be avoided (Figure 2A).

333 The same principles translate to applied ecology for identifying currently unmanaged units
334 that should or should not be targeted for a specific management intervention. For example, a
335 clearcutting and restocking intervention has an outcome of change in total forest soil carbon
336 that varies spatially, according to a range of climatic, soil and topographic covariates. If the
337 objective of management is to increase soil carbon, action should be targeted to stands where
338 clearcutting/restocking increases soil carbon (*Persuadables*; Figure 2B).



339

340 **Figure 2. The principles of uplift modelling, used in marketing, apply also to ecology to**
 341 **identify currently unmanaged units that should or should not be targeted for a specific**
 342 **management intervention.** a) In marketing, uplift modelling classifies individual customers according
 343 to differences in purchasing behaviour after being shown or not shown an advertisement. It is most
 344 cost effective to target advertisements at individual customers who are *Persuadable* - those
 345 individuals that would buy a product only if shown an advert. b) Uplift modelling applied to total soil
 346 carbon (tonnes/ha) in forest stands. Stands with lower soil carbon following thinning treatment should
 347 not be disturbed, while *Persuadable* stands that have greater soil carbon following treatment should
 348 be targeted. The map shows hypothetical individual treatment effects (difference in tonnes C/ha)
 349 predicted for untreated forest stands within the sample.

350

351 **A roadmap to establishing prospects for precision ecology**

352 Several generic issues remain outstanding for widening applications of ITE prediction within
 353 medicine and marketing and across other disciplines. These relate particularly to risks of
 354 biases in sample selection and confounding of cause with correlation. As for all statistical
 355 analysis, they require a causal understanding of mechanisms underpinning heterogeneity in
 356 treatment effects⁴⁶. For ITE prediction, the covariates that matter, and therefore the ones to
 357 test with sufficient power to detect effects, are those that contribute most to explaining
 358 variation in treatment effects⁴⁷. The problem of how to identify them *a priori* may be best
 359 addressed again through theoretical understanding of mechanisms, as well as evidence from
 360 past empirical research. It is well established that causal models should not condition on
 361 ‘post-treatment variables that vary as a function of treatment (see⁴⁸). Other general challenges
 362 include expansion to nonbinary treatments, which is an ongoing enterprise in precision
 363 medicine.

364 Ecology-specific issues for ITE prediction, of defining the observational unit for ITE, and
365 risks of carryover and spillover effects amongst sample plots, have only recently been
366 explored in other precision disciplines^{49,50}, and they remain as hurdles to the adoption of ITE
367 prediction for applications to precision ecology. All are well-known issues of spatial analysis
368 for conventional ATE estimation, however, and the same principles of data-collection design
369 will apply to ITE. Where sampling units such as lakes or forest stands vary in size, the spatial
370 extent of the sampling unit may need to be included in the predictive model as a conditioning
371 covariate. A key ITE-specific challenge is the potential for heterogeneous treatment
372 implementation. For example, for studies quantifying effects of field-margin presence on
373 pollinator abundance, field-margin size, quality and maintenance might vary among fields,
374 and might be systematically confounded with environmental covariates (e.g., farm economic
375 size), yielding biased ITEs. Implementation heterogeneity is also problematic in medical drug
376 trials, for example when patients do not comply with treatment recommendations.

377 For all of these general and ecology-specific challenges, simulations offer opportunities to
378 explore costs and benefits of alternative sampling strategies, within an idealised
379 environment^{33,36,51}. Synthetic datasets with real covariates, for which both potential outcomes
380 are simulated and hence known, are ideal for investigating how ITE prediction accuracy is
381 influenced by sampling and modelling parameters⁵¹. Importantly, simulation studies have
382 found that meta-learners vary in their predictive accuracy under different data conditions, and
383 no one learner works uniformly best.³⁶ In the same way, ecologists can adopt a ‘virtual
384 ecologist’ approach⁵² as follows. First, ecologists can use process-based models to generate
385 spatially-explicit virtual representations of ecosystems and their assignment to treatments
386 across heterogeneous landscapes. A range of process-based models are increasingly being
387 used to model how species and ecosystems are likely to respond to environmental changes
388 and to potential management options^{53–55}. Crucially, both potential outcomes of a treatment
389 variable of interest can be simulated, to overcome the fundamental problem of causal
390 inference and generate known ITEs for each virtually sampleable unit. Second, such virtual
391 landscapes can be sampled using designs common to ecology (e.g., a citizen-science project
392 or national monitoring programme) to generate datasets. Third, the resulting datasets can be
393 subjected to different modelling approaches (e.g., meta-learner algorithms) to predict unit-
394 specific treatment effects. Fourth, researchers can measure and compare the accuracy,
395 precision and utility of ATE and ITE predictions by evaluating predictions against ‘true’ (i.e.,
396 simulated) treatment effects.

397 Within this virtual ecologist approach, researchers can compare performances of the different
398 meta-learners for different sampling processes, and they can systematically vary response
399 detectability by environmental variables (e.g., of birds in shrubland vs. open grass⁵⁶). The
400 unique advantage of simulation, which no empirical approach can better, is that the
401 researcher has full knowledge of the sampled population, against which to quantify sampling
402 biases in estimation or prediction by statistical analysis⁵². The hurdles to simulation
403 principally concern the level of achievable realism in representing empirical landscapes or
404 sampling processes.

405 We identify the following four key questions that will determine the future prospects for ITE
406 prediction in applied ecological research.

407 **1. What types of study question can precision ecology answer?**

408 Precision ecology applies to any question about changes in a parameter of interest across a
409 suite of heterogeneous covariate influences, be they observed across time or space, and it
410 provides context-dependent answers. ITE prediction of intervention effects attempts to
411 answer the what, how, where and when questions asked by conservation managers and policy
412 makers, which conventional ATE estimation cannot adequately address for anything but
413 homogeneous environments. Stakeholders in management- or policy-relevant outcomes
414 should be involved in setting research questions.

415 As with ATE estimation, ITE prediction requires observations from individual units for
416 treatments, outcomes, and covariates that influence treatment assignments or outcomes. ITE
417 prediction, however, requires more parameters than ATE. For example, X- and R-learners
418 must learn ‘nuisance functions’ including those that estimate propensity scores and
419 intermediate treatment effects (Box 1). ITE prediction is correspondingly more data-hungry,
420 potentially demanding larger training datasets and more covariates, although two-model
421 meta-learners (e.g., T- and X-learners) reduce training sample sizes to their treatment groups.
422 A growing number of high-resolution and large-scale datasets on biodiversity and ecosystem
423 functioning are becoming available from multiple sources, including *in-situ* and remote
424 sensors, eDNA, citizen scientists and monitoring networks. The rising availability and
425 integration of data products will increasingly facilitate the parameterisation of ITE prediction
426 models, by supplying conditional covariates related to topography, climate, and historical
427 land uses. In addition, remote-sensing technology has expanding applications to data on
428 treatment effects. For example, satellite data can be used to characterise the incidence of

429 forest loss through clearance, fire, pest outbreaks etc, as well as outcomes related to forest
430 biodiversity, productivity and condition⁵⁷.

431 **2. What design of sampling strategy will yield unbiased individual treatment effects?**

432 Data-collection designs that plan for ITE prediction at the outset will depend on the exact
433 question and target population. It is important to note that sampling methods that optimise
434 statistical power for the ATE do not necessarily optimise predictive validity of the ITEs of
435 interest – especially when the interest is in ITE prediction for units with relatively unique
436 covariate profiles⁵⁸. Sampling designs for causal prediction should be informed by a ‘theory
437 of treatment effect heterogeneity’⁴⁷, wherein researchers identify important subgroups and
438 hypotheses regarding moderating covariates *a priori*, rather than *post hoc*. Hypothetically
439 important moderators could then be used to stratify populations for sampling, and could aid
440 in identifying how existing monitoring programmes might need strategic augmenting to
441 maximise ITE prediction⁴⁷.

442 **3. What biases and caveats are introduced by analysing pre-existing data?**

443 The rapidly expanding range of big data available from monitoring programmes, citizen
444 science initiatives and remote and near-Earth sensing, which typically cover heterogeneous
445 landscapes of covariates, open up new opportunities for ITE prediction. Such datasets,
446 however, are inherently susceptible to different forms of sample-selection bias. Patterns in the
447 availability of biodiversity data, for example, are affected by the original motivations for, and
448 constraints on, data-collection and reporting⁵⁶. The meta-learner algorithms introduced in
449 Box 1 offer some of the most promising available approaches to smoothing over the resulting
450 gaps in observed data that raise vulnerabilities to sample-selection bias or underpowered
451 analysis. The challenge is to decide which algorithm and type of model works best for which
452 context, and the virtual ecologist has an important role to play here⁵². A model might be
453 vulnerable to overfitting (mistakenly fitting sample-specific noise as if it were signal⁵⁹), or an
454 algorithm might overperform on simulated data due to specificities of the data-generating
455 process, requiring comparison of ITE accuracy from the crossing of alternative data-
456 generating mechanisms⁵¹, sampling designs and model decisions. Knowledge of how
457 sampling and modelling characteristics influence predictive accuracy will arm ecologists with
458 an informed understanding of when precision approaches can and cannot work under what
459 conditions, their underpinning assumptions, and when to anticipate biases.

460 Although spatial data now exist that permit quantification of spatial composition, pattern, and
461 position of landscape features from local to continental scales,⁶⁰ researchers must consider
462 whether they capture habitat features most relevant to the effects of interest⁵⁴. Given the
463 measurement error inherent to many ecological covariates and outcomes, for example
464 depending on species' detection probabilities and accuracy of land cover maps, precision
465 analyses will need to develop methods for translating measurement error into ITE prediction
466 uncertainty.

467 **4. How can precision outputs best inform managers and policy makers?**

468 ITEs offer intuitively appealing predictions with directly actionable site-level predictions.
469 Applied ecologists have scope to develop innovative and imaginative visualisations⁶¹,
470 maximising the actionability of predictions for diverse audiences of policymakers,
471 practitioners, and other scientists. Mapping uncertainties in the treatment effect, or in
472 covariate measurements or their interactions, could usefully identify future data-collection
473 needs, or sites that might warrant alternative interventions such as adaptive management.
474 Stakeholders should be involved in co-design of tools for visualising statistical outputs.

475 **Conclusion**

476 Medicine and marketing have pioneered unit-specific prediction, motivated by the potentially
477 catastrophic consequences of ineffectual decisions from ATEs for a medical patient's
478 survival and for a production company's returns on investment. As climate change and
479 biodiversity loss drive applied ecology towards crisis management, national-scale policies on
480 nature also need to be actionable at local scales. Ecology needs to explore the full scope and
481 limits of its potential for thinking globally, acting locally¹. Applied ecologists must capitalise
482 wisely on the deluge of open-source data, to inform local-level management decisions about
483 global-scale problems, armed with the knowledge of which approaches can and cannot work
484 under what conditions, the necessary assumptions that must hold, and when biases will most
485 likely be encountered. The process of predicting unit-specific treatment effects forces the
486 analyst to evaluate numerous assumptions about the validity of predicting treatment effects at
487 specific sites, and in turn, it marries internal with external validity. In so doing, it contributes
488 to narrowing the science-policy gap. Moving on from estimating sample-average effects to
489 predicting unit-specific treatment effects will be key to effectively supporting restoration and
490 management of Earth's species, habitats, and ecosystems.

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499 **Contributions**

500 R.S. conceived the idea and developed a first draft with C.P.D. Contributions from E.E.J.,
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502 **Competing interests**

503 The authors declare no competing interests.

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