

Attainability by simply connected domains of optimal bounds for the polarization tensor

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The notion of polarization tensor is employed for the derivation of the leading-order boundary perturbations in the steady-state voltage potentials that are due to the presence of conductivity inclusions of small diameter. Recently, Capdeboscq and Vogelius obtained optimal bounds of Hashin-Shtrikman type for the trace of the polarization tensor, showing that every pair satisfying these optimal bounds arises as the eigenvalues of a polarization tensor associated with a coated ellipse. In this paper, we give numerical evidence of the fact that the set of possible polarization tensor eigenvalue pairs can also be obtained using simply connected domains. Our numerical computations are based on a boundary integral method.

1 Introduction

This paper is concerned with the notion of polarization tensor (PT) associated with a bounded Lipschitz domain and an isotropic constant conductivity. The notion of PT appeared in problems of potential theory related to certain questions arising in hydrodynamics, in electrostatics, and in low-frequency scattering [14, 21, 22]. The PT is a key mathematical concept in efficiently imaging small conductivity inclusions from boundary measurements and also in calculating effective electrical properties of composite materials consisting of inclusions of one material of known shape embedded homogeneously into a continuous matrix of another having electrical properties different from its own. It is now known that the leading-order term in the boundary perturbations due to the presence of an inclusion inside a conductor as well as in the asymptotic expansion of the effective conductivity of a dilute composite material in terms of the volume fraction of the inclusions can be expressed by means of the PT of the inclusions shape [1, 4, 6, 8, 11, 13, 15, 16, 20]. The asymptotic expansion of the effective conductivity is motivated by the practically important inverse problem of determining the volume fraction of a suspension of complicated shaped particles from boundary measurements of voltage potentials. Therefore, in

both applications, it is important from an imaging point of view to precisely characterize the class of PTs and extract from the (detected) PT some important information, such as the size and the orientation of the inclusion. Indeed, it is important to obtain bounds for the matrix-elements of the PT since a better bound for the PT yields a better estimate for the size of the inclusion [1, 11].

Recently, based on variational techniques originally described in Kohn & Milton [17], Capdeboscq & Vogelius [11] obtained geometry independent optimal bounds of the Hashin-Shtrikman (HS) type for the trace of the PT. These bounds had already been derived, by an alternative approach, by Lipton [19]. Throughout this paper, these bounds are called the HS bounds. To mathematically state the main estimates provided in Capdeboscq & Vogelius [11], let M denote the PT associated with the bounded domain $D \subset \mathbb{R}^d$ whose volume $|D| = 1$ and the constant conductivity $0 < k \neq 1 < +\infty$. Then, for $d = 2, 3$, these bounds are as follows:

$$\text{Trace}(M) \leq (k-1) \left(d-1 + \frac{1}{k} \right), \quad (1.1.1)$$

and

$$\text{Trace}(M^{-1}) \leq \frac{d-1+k}{k-1}. \quad (1.1.2)$$

In particular, in the two-dimensional case, if λ_1 and λ_2 are two eigenvalues of M , then

$$\lambda_1 + \lambda_2 \leq \frac{(k-1)(k+1)}{k}, \quad (1.1.3)$$

and

$$\frac{1}{\lambda_1} + \frac{1}{\lambda_2} \leq \frac{k+1}{k-1}. \quad (1.1.4)$$

Figure 1 shows these bounds graphically, where the region A is the upper part of the HS bounds, namely the set of all (λ_1, λ_2) satisfying

$$\lambda_1 + \lambda_2 < \frac{(k-1)(k+1)}{k}, \quad \frac{1}{\lambda_1} + \frac{1}{\lambda_2} \leq \frac{k+1}{k-1}, \quad \lambda_1 \leq \lambda_2,$$

and the region B is the set of all (λ_1, λ_2) satisfying

$$\lambda_1 + \lambda_2 < \frac{(k-1)(k+1)}{k}, \quad \frac{1}{\lambda_1} + \frac{1}{\lambda_2} \leq \frac{k+1}{k-1}, \quad \lambda_1 \geq \lambda_2.$$

The question we deal with in this paper is whether each point inside the HS bounds is a pair of eigenvalues of a PT associated with a domain of unit area in $\mathbb{R}^2$. This question was positively answered by Capdeboscq & Vogelius [12]. These authors showed that each point inside the HS bounds is attained as a PT associated with a coated ellipse, or a washer of elliptic shape. In fact, every point on the lower bound $1/\lambda_1 + 1/\lambda_2 = (k+1)/(k-1)$ corresponds to an ellipse, and as ellipses get thinner, corresponding points on the lower bound move to the upper or lower corner. If we start from an ellipse corresponding to a

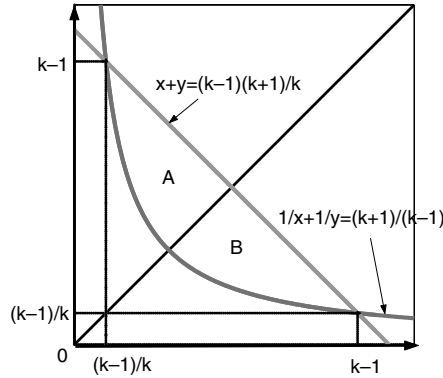
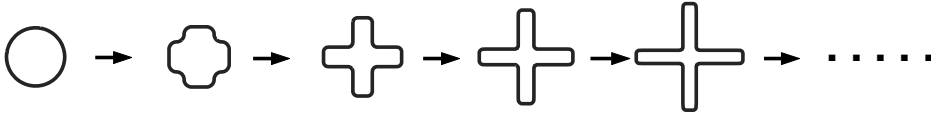
FIGURE 1. The optimal bounds for the polarization tensor in $\mathbb{R}^2$.

FIGURE 2. The variation of cross-domains starting from the unit disk.

point on the lower bound, and make confocal washers of elliptic shape, then corresponding points move toward the upper bound following a certain curve as the washers get thinner and larger. These curves make foliations and cover all regions inside the bounds except the upper bound.

Our goal in this paper is to give numerical evidence of the fact that this optimal set can also be obtained using simply connected domains. Our approach is to compute numerically the polarization tensors corresponding to a radial interpolation between ellipses of unit area and crosses with right angles, equal legs, and smooth corners. It turns out that if we start from the unit disk and vary the domain to make a thin and long cross as shown in Figure 2, the corresponding eigenvalues move from the intersection point of the lower hyperbola and the line $\lambda_1 = \lambda_2$ toward the intersection point of the upper bound and the line $\lambda_1 = \lambda_2$ following the line $\lambda_1 = \lambda_2$. Note that the intersection point of the lower hyperbola and the line $\lambda_1 = \lambda_2$ is the pair of eigenvalues of the PT associated with the unit disk. We also note that the cross-shaped domain in Figure 2 is invariant under rotation by $\pi/2$, and hence the corresponding PT is of the form λI for some λ where I is the 2×2 identity matrix. Thus, by interpolating a cross-shape domain and an ellipse, we can obtain foliation of the bounds (1.1.3) and (1.1.4). This is the basic idea of our work. Based on this idea, we will show, by numerical computations, that each point inside the HS bounds is attained by cross-shaped domains whose sides are different (see §3 for precise parameterizations of domains). We will also present a method to find a domain whose PT has a given pair of eigenvalues. We emphasize that the result of this paper is numerical and analytic computations of the PTs associated with the domains we construct in this work, for arbitrary aspect ratios, seem unlikely. However, we will show that it is possible to compute the eigenvalues of mixtures of ellipses and cross-shape domains in the high aspect ratio limit.

The paper is organized as follows. In §2, we review the definition of the PT and its representation in terms of boundary integrals. This boundary integral representation is used for our numerical computations throughout this paper. In §3 §4, we parameterize the domains we consider using two parameters, one being the ellipticity of the ellipses (or the length over width ratio of the crosses' legs) and the second being the proportion of ellipses and crosses, to show numerical evidence of the fact that the corresponding PTs make foliation of the HS bounds. In §5 we first provide the asymptotic behavior of the PT associated with crosses as crosses get thinner and longer. We then show that this results validates the numerical results presented in §4 for thin an long inclusions – which are the most difficult to accurately simulate numerically.

In §6, we present a method to identify a parameterized domain whose PT has a given pair of eigenvalues. We derive an approximate formula to extrapolate from the computed eigenvalue pairs data the shape of the domain. We use a combination of least square fitting with Lagrange interpolation. The robustness of this extrapolation, compared to the direct simulation, is accurately tested.

In concluding this introduction, we briefly mention a conjecture of Pólya-Szegő. Observe that among the points in HS-bounds, the intersection point of the lower bound and the line $\lambda_1 = \lambda_2$, $(2(k-1)/(k+1), 2(k-1)/(k+1))$, has the minimal trace, and this is the eigenvalue of the PT associated with the disk of unit area. Pólya & Szegő [21] conjectured that the disk (or the sphere for three dimensions) is a unique domain with minimal trace. This conjecture has not yet been proved.

2 Preliminaries

Let us recall the definition of PT. Let D be a bounded Lipschitz domain in $\mathbb{R}^2$. The conductivity of $\mathbb{R}^2 \setminus \overline{D}$ and D are assumed to be 1 and $0 < k \neq 1 < +\infty$, respectively. Let $W^{1,2}$ be the collection of all functions ψ such that $\int_{\mathbb{R}^2} |\nabla \psi|^2 < +\infty$ and $\psi(x) = O(|x|^{-1})$. The polarization tensor $M = (M_{ij})_{i,j=1,2}$ associated with the domain D is defined to be the 2×2 matrix given by

$$M_{ij} = (k-1) \left[\delta_{ij} |D| + \int_{\partial D} x_j \frac{\partial \psi_i}{\partial \nu} \Big|_- ds \right], \quad i, j = 1, 2, \quad (2.2.1)$$

where ψ_i , $i = 1, 2$, is the unique solution in $W^{1,2}$ to the following transmission problem:

$$\Delta \psi_i = (1-k) \nabla \cdot (\chi(D) (\nabla \psi_i + e_i)), \quad (2.2.2)$$

or equivalently,

$$\begin{cases} \Delta \psi_i = 0 & \text{in } (\mathbb{R}^2 \setminus \overline{D}) \cup D, \\ \psi_i|_+ - \psi_i|_- = 0 & \text{on } \partial D, \\ \frac{\partial \psi_i}{\partial \nu} \Big|_+ - k \frac{\partial \psi_i}{\partial \nu} \Big|_- = (k-1) v_i & \text{on } \partial D, \\ \psi_i(x) = O(|x|^{-1}) & \text{as } |x| \rightarrow \infty. \end{cases}$$

Here, $\chi(D)$ is the characteristic function of D , e_i is the standard basis of $\mathbb{R}^2$, the subscripts $+$ and $-$ denote the limits from outside and inside D , respectively, and $v = (v_1, v_2)$ is the

unit outward normal to ∂D . Then one can show [12] that for any $\xi \in \mathbb{R}^2$

$$M_\xi^\xi \cdot \xi = \int_{\mathbb{R}^2} \gamma_D \left| \nabla w + \frac{k-1}{k} \chi(D) \xi \right|^2 + \frac{k-1}{k} |\xi|^2 |D|, \quad (2.2.3)$$

where w is the solution to

$$\Delta w = (1-k) \nabla \cdot (\chi(D) (\nabla w + \xi)).$$

Here and throughout this paper $\gamma_D := 1 + (k-1)\chi(D)$. Moreover, the solution w is the minimizer of the functional

$$\int_{\mathbb{R}^2} \gamma_D \left| \nabla \phi + \frac{k-1}{k} \chi(D) \xi \right|^2 + \frac{k-1}{k} |\xi|^2 |D|$$

over $\phi \in W^{1,2}$. It then follows that

$$\int_{\mathbb{R}^n} \gamma_D \left| \nabla w + \chi(D) \frac{k-1}{k} \xi \right|^2 = - \int_{\mathbb{R}^2} \gamma_D |\nabla w|^2 + \frac{(k-1)^2}{k} |\xi|^2 |D|. \quad (2.2.4)$$

See Capdeboscq & Vogelius [12] for details.

The definition (2.2.1) of PT is proved to be equivalent to the following representation using layer potential techniques [2, 1]. For $\phi \in L^2(\partial D)$, let $\mathcal{K}_D^* \phi$ be defined by

$$\mathcal{K}_D^* \phi(x) = \frac{1}{2\pi} \text{p.v.} \int_{\partial D} \frac{\langle x-y, v_x \rangle}{|x-y|^2} \phi(y) d\sigma(y),$$

where p.v. stands for the Cauchy principal value. Then M can be represented as follows:

$$M_{ij} = \int_{\partial D} y_j (\lambda I - \mathcal{K}_D^*)^{-1}(v_i)(y) d\sigma(y), \quad \lambda := \frac{k+1}{2(k-1)}. \quad (2.2.5)$$

This boundary integral representation of PT is particularly useful for computational purpose and we will use this representation for all the computations provided in this paper.

3 Parameterizations of domains and attainability

In this section, we show numerically that every point inside the bounds (1.1.3) and (1.1.4) is a pair of eigenvalues of a PT associated with a simply connected domain of unit area. The domains varies from ellipses to crosses as shown in the introduction. The crosses to be considered in this section will be slightly different from those considered in the previous section in order to avoid the corners.

Let us briefly explain how we numerically compute the PT M . The domain D to be considered is symmetric with respect to x and y axes, and centered at the origin $(0,0)$. In order to compute M using its definition given in (2.2.5), we compute $(\lambda I - \mathcal{K}_D^*)^{-1}(v_i)(y)$ in the following way. We first choose $2m$ points $x_1, x_2, \dots, x_{2m}$ on ∂D , and find ϕ_i , $i = 1, 2$, satisfying

$$(\lambda I - \mathcal{K}_D^*) \phi_i(x_k) = v_i(x_k), \quad k = 1, 2, \dots, 2m.$$

This equation is solved by making use of the collocation method and trapezoid rule (see, for instance, Kress [18]). Because of the symmetry of D , the discretized operator $(\lambda I - \mathcal{K}_D^*)$

is a matrix of the form $\begin{pmatrix} \mathcal{A} & \mathcal{B} \\ \mathcal{B} & \mathcal{A} \end{pmatrix}$ where $\mathcal{A}$ and $\mathcal{B}$ are $m \times m$ matrices, and the vector $v_i = v_i(x_k)$ for $k = 1, \dots, 2m$, takes the form $\begin{pmatrix} a_i \\ -a_i \end{pmatrix}$. Therefore, the solution $\phi_i = (\phi_i(x_k))_{k=1}^{2m}$ should be of the form $\begin{pmatrix} b_i \\ -b_i \end{pmatrix}$, where the vector $b_i \in \mathbb{R}^m$ is the solution of the algebraic equation

$$(\mathcal{A} - \mathcal{B})b_i = a_i, \quad i = 1, 2. \quad (3.3.1)$$

To solve (3.3.1), we use the decomposition $P(\mathcal{A} - \mathcal{B}) = LU$ where the matrix L , U and P are a lower triangular, an upper triangular, and a permutation matrix, respectively. Once (3.3.1) is solved, we can in a standard way use (2.2.5) to finally calculate M .

As will be shown in the following, the domain D can be a thin long cross. As the cross gets thinner and longer, we need more points on ∂D , and hence the matrix $\mathcal{A} - \mathcal{B}$ becomes larger, causing more difficulties for solving (3.3.1). But, thanks to the symmetry of D , $\mathcal{A} - \mathcal{B}$ is a sparse matrix and then we can decompose it into several symmetric matrices of small sizes.

Note that, because of an obvious symmetry reason, it suffices to consider the region $\lambda_2 \geq \lambda_1$. In fact, we recall that if two domains D and D' are related by $D' = R(D)$ where R is a unitary transformation, then their corresponding PTs, M' and M , satisfy the relation:

$$M' = RMR^T. \quad (3.3.2)$$

For $t \geq 1$, let $E(t)$ be the ellipse of the form

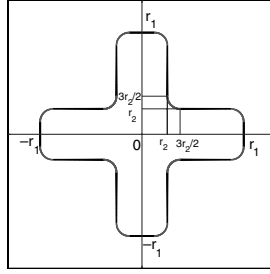
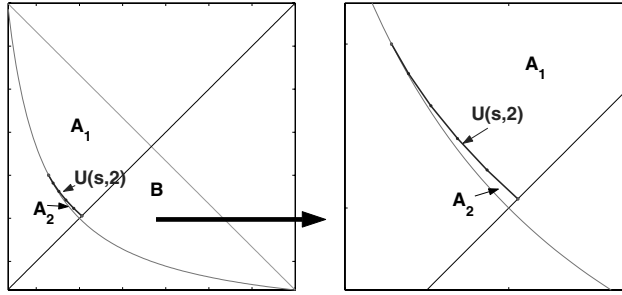
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, \quad a \leq b,$$

where $t := b/a$ and the area $|E(t)| = 1$. The cross-shaped domain $D(t)$, $t \geq 2$, is defined by

$$D(t) := \{(x, y), (x, -y), (-x, y), (-x, -y) | (x, y) \in D\},$$

where $|D(t)| = 1$, and for $x \geq 0$ and $y \geq 0$, $t := r_1/r_2$, and the set D is given by

$$D = \begin{cases} (r_1, y) & \text{for } 0 \leq y \leq \frac{r_2}{2}, \\ \left(r_1 - \frac{r_2}{2} + \frac{r_2}{2} \frac{x}{\sqrt{x^2 + y^2}}, \frac{r_2}{2} + \frac{r_2}{2} \frac{y}{\sqrt{x^2 + y^2}} \right) & \text{for } 0 \leq \tan^{-1} \frac{y}{x} \leq \frac{\pi}{2}, \\ (x, r_2) & \text{for } \frac{3r_2}{2} \leq x \leq r_1 - \frac{r_2}{2}, \\ \left(\frac{3r_2}{2} + \frac{r_2}{2} \frac{x}{\sqrt{x^2 + y^2}}, \frac{3r_2}{2} + \frac{r_2}{2} \frac{y}{\sqrt{x^2 + y^2}} \right) & \text{for } \pi \leq \tan^{-1} \frac{y}{x} \leq \frac{3\pi}{2}, \\ (r_2, y) & \text{for } \frac{3r_2}{2} \leq y \leq r_1 - \frac{r_2}{2}, \\ \left(\frac{r_2}{2} + \frac{r_2}{2} \frac{x}{\sqrt{x^2 + y^2}}, r_1 - \frac{r_2}{2} + \frac{r_2}{2} \frac{y}{\sqrt{x^2 + y^2}} \right) & \text{for } 0 \leq \tan^{-1} \frac{y}{x} \leq \frac{\pi}{2}, \\ (x, r_1) & \text{for } 0 \leq x \leq \frac{r_2}{2}. \end{cases}$$

FIGURE 3. The graph of $D(t)$ for $t = r_1/r_2 = 3$.FIGURE 4. The curve of PT associated with $U(s,2)$ divides A into the upper part A_1 and the lower part A_2 .

The domain $D(t)$ is a cross whose corners are polished to be arcs. We make the corners smooth to make the computations easier. Figure 3 shows the shape of $D(t = 3)$. The classes of domains $E(t)$ and $D(t)$ are the basic building blocks for representing the optimal shapes constructed in this paper.

It is known that the eigenvalue pair of the PT of the ellipse $E(t)$ lies on the lower bound (hyperbola) of the region A . In fact, according to Brühl *et al.* [8], the PT for the ellipse $E(t)$ is given by

$$M = |E| \begin{pmatrix} \frac{(k-1)(a+b)}{a+kb} & 0 \\ 0 & \frac{(k-1)(a+b)}{ka+b} \end{pmatrix}. \quad (3.3.3)$$

Thus the eigenvalue pair of the PT for $E(t)$ is

$$\left(\frac{(k-1)(1+t)}{1+kt}, \frac{(k-1)(1+t)}{k+t} \right).$$

On the other hand, since the domain $D(t)$ is invariant under the rotation by $\pi/2$, by the relation (3.3.2) the eigenvalue pair of its PT lies on the line $\lambda_1 = \lambda_2$. Let

$$U(s,2) = (1-s)D(2) + sE(2), \quad 0 \leq s \leq 1.$$

As shown in Figure 4, the eigenvalue pair of the PT associated with the domain $U(s,2)$ divides the region A into two parts A_1 and A_2 . Therefore, we will use different

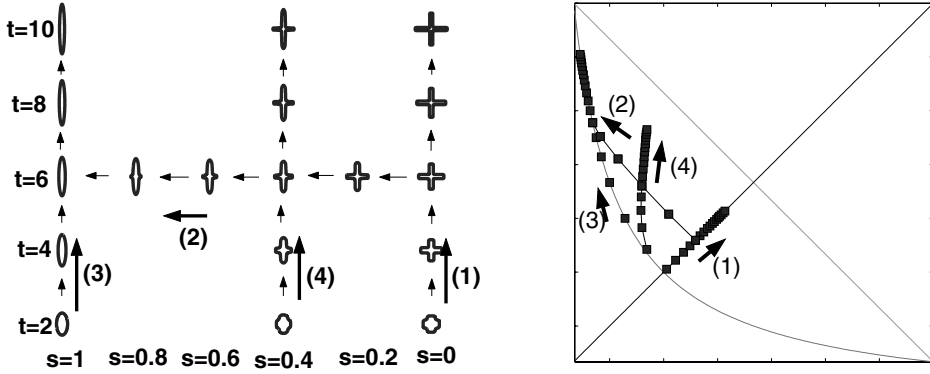


FIGURE 5. The variation of $U(s, t)$ and the corresponding eigenvalue pairs. As $t \rightarrow \infty$, the cross and ellipse become thinner and longer, and corresponding eigenvalues move toward the upper bound. As $s \rightarrow 1$, the cross becomes an ellipse and corresponding eigenvalues move toward the lower hyperbola.

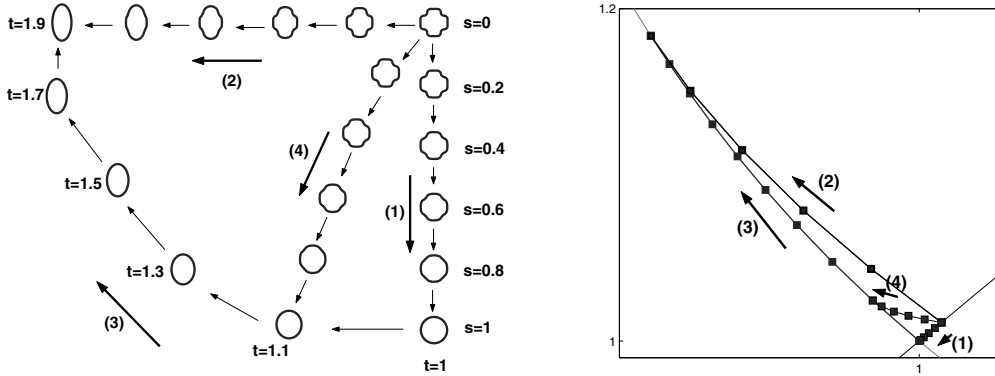
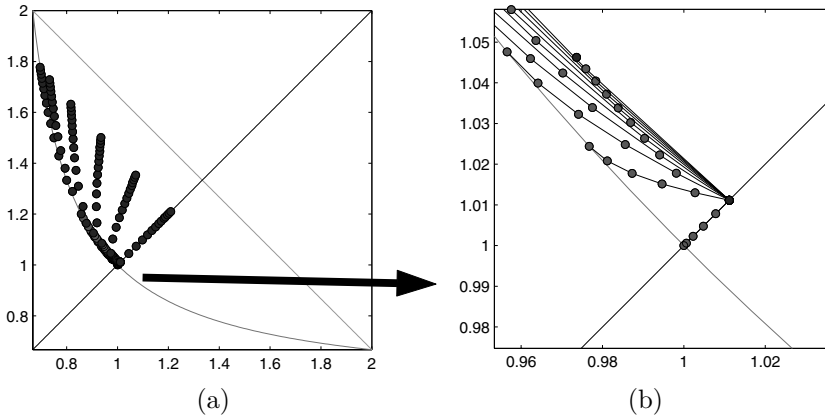
parameterizations of domains to attain points in A_1 and A_2 . This is solely for the convenience of the computations.

Attainability of the region A_1 . Let

$$U(s, t) = (1 - s)D(t) + sE(t), \quad 0 \leq s \leq 1, \quad 2 \leq t.$$

By this notation, we do not mean the convex combination of the two shapes. Notice for every t , that $D(t)$ and $E(t)$ are both star-shaped domains around the origin, i.e., there exist two functions $d_t \in C^1([0, 2\pi])$ and $e_t \in C^\infty([0, 2\pi])$ such that $\partial D(t) = \{(\varphi, d_t(\varphi)), \varphi \in [0, 2\pi]\}$ and $\partial E(t) = \{(\varphi, e_t(\varphi)), \varphi \in [0, 2\pi]\}$. The precise definition of $U(s, t)$ for a given $s \in [0, 1]$ is the bounded domain limited by the C^1 curve $\partial U(s, t) = \{(\varphi, (1 - s)d_t(\varphi) + se_t(\varphi)), \varphi \in [0, 2\pi]\}$. Note that $|U(s, t)| = \frac{1}{2} \int_0^{2\pi} ((1 - s)d_t(\varphi) + se_t(\varphi))^2 d\varphi$ is not a priori equal to one. We therefore rescale the polarization tensor by a factor $1/|U(s, t)|$.

Our goal in this section is to show that the points inside A_1 are attained by the domain $U(s, t)$. Note that $U(1, t) = E(t)$ is an ellipse and $U(0, t) = D(t)$ is a cross. As t gets larger, the ellipse $U(1, t)$ becomes thinner and the cross $U(0, t)$ becomes thinner and longer. For a fixed t , $U(s, t)$ changes its shape from a cross to an ellipse as s varies from 0 to 1. The left-hand side of Figure 5 shows the variation of the domain $U(s, t)$. Numerical computations show that as $t \rightarrow \infty$, the eigenvalue pair of PT associated with $U(0, t)$ moves toward the point $(\lambda_1, \lambda_2) = ((k - 1)(k + 1)/(2k), (k - 1)(k + 1)/(2k))$ following the line $\lambda_1 = \lambda_2$ while that of $U(1, t)$ moves toward the point $((k - 1)/k, k - 1)$ following the hyperbola. Both of these facts will be rigorously established in § 5. For each fixed t , the eigenvalue pair for $U(s, t)$, $0 \leq s \leq 1$, makes a curve in the region A_1 , and these curves make foliation of the region A_1 as t varies. Figure 5 shows variations of $U(s, t)$ and the result of numerical computations.

FIGURE 6. The variations of $L(s, t)$ and the corresponding eigenvalue pairs of its PT.FIGURE 7. The left figure shows the eigenvalue pairs of the PTs associated with $U(s, t)$ and $L(s, t)$. The blue points are eigenvalue pairs corresponding to $U(s, t)$ and the red ones to $L(s, t)$. The right figure enlarges A_2 .

Attainability of the region A_2 . Let

$$L(s, t) := (1 - s)E(t) + sD(2), \quad 0 \leq s \leq 1 \text{ and } 1 \leq t < 2.$$

As above, this notation does not mean the convex combination of $E(t)$ and $D(2)$ but the bounded domain limited by the curve $\{(\varphi, (1 - s)e_t(\varphi) + sd_2(\varphi)), \varphi \in [0, 2\pi]\}$. Note that $D(2)$ is fixed. For each fixed t , $E(t)$ corresponds to a point on the lower hyperbola. So, $L(s, t)$ interpolates the point on the hyperbola and the fixed point on the line $\lambda_1 = \lambda_2$ corresponding to $D(2)$. Numerical computations give the evidence of the fact that the points in A_2 arise as the eigenvalue pairs of the PT corresponding to the domain $L(s, t)$. Figure 6 shows the variation of $L(s, t)$ and the corresponding eigenvalues of its PT.

Figure 7 shows attainability of both the regions A_1 and A_2 .

4 An approximate formula for the foliation

In the previous section, we parameterized domains to show that as the parameter s varies from 0 to 1 for a fixed t , the eigenvalue pairs make a curve. Then, by varying t these curves, a foliation of the region, say A_1 , can be obtained.

In this section, we derive an approximate formula for this foliation. Since the formula for the region A_2 can be obtained in almost the same way, we omit its derivation.

Choose finite sets of parameters, $S = \{s_0 = 0, s_1, \dots, s_m = 1\}$ and $T = \{t_0 = 2, t_1, \dots, t_n\}$. Then numbers m, n are at our disposal. We may take large ones if we need very accurate approximations. We then compute the eigenvalues $(\lambda_1(s_i, t_j), \lambda_2(s_i, t_j))$ of the PT associated with the domain $U(s_i, t_j)$ for $i = 0, \dots, m$ and $j = 0, \dots, n$. Our objective is to find a formula to relate $\lambda_1(s_i, t_j)$ with $\lambda_2(s_i, t_j)$.

Let us introduce a transformation which makes the computations easier. Let V be given by

$$V(x, y) := R_{\frac{\pi}{4}} \left(x - \frac{(k-1)(k+1)}{2k}, y - \frac{(k-1)(k+1)}{2k} \right),$$

where R_θ is the rotation by θ . Then define

$$(\rho_1(s, t), \rho_2(s, t)) := V(\lambda_1(s, t), \lambda_2(s, t)).$$

We seek to find a function $P(x, t)$ of the form

$$P(x, t) = \sum_{l=0}^m a_l(t) x^l,$$

such that

$$\rho_2(s_i, t_j) = P(\rho_1(s_i, t_j), t_j) = \sum_{l=0}^m a_l(t_j) \rho_1(s_i, t_j)^l.$$

We can obtain the desired formula by completing the following steps.

An approximate formula for the foliation

S1. For each $s_i \in S$ ($i \neq m$) and $l = 1, 2$, we look for a function P_i^l on $(1, 3/2]$ satisfying

$$P_i^l \left(\frac{1+t_j}{t_j} \right) = \rho_k(s_i, t_j), \quad t_j \in T,$$

or minimizing

$$\sum_{t_j \in T} \left| P_i^l \left(\frac{1+t_j}{t_j} \right) - \rho_k(s_i, t_j) \right|.$$

We obtain such a polynomial P_i^l using the least square curve fitting.

If $i = m$ or $s_i = 1$, then $U(s_m, t)$ is an ellipse, and the corresponding eigenvalues are given explicitly by (3.3.3). We use these explicit formulas for our P_m^l , $l = 1, 2$.

S2. We seek a function $P(x, t)$, which is the unique m -th degree polynomial in x satisfying

$$P(\rho_1(s_i, t_j), t_j) = \rho_2(s_i, t_j), \quad s_i \in S \text{ and } t_j \in T.$$

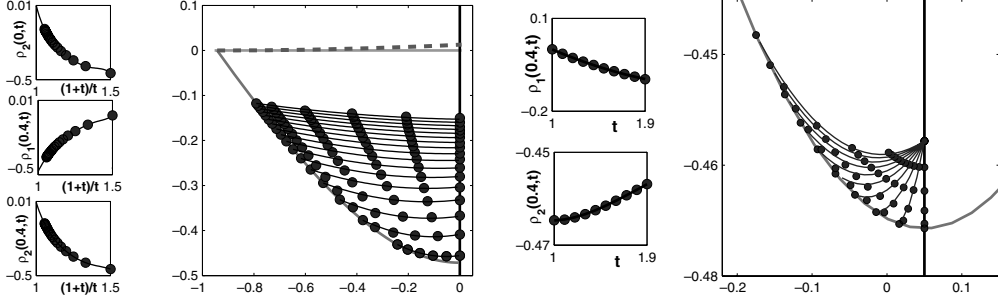


FIGURE 8. Numerical results for U and L . The dots are the computed eigenvalue pairs of the PT of the domains and solid curves are curves fitting dots.

Such a polynomial is given by

$$\begin{aligned}
 P(x, t) &= \sum_{i=0}^m a_i(t) x^i \\
 &= \sum_{i=0}^m \prod_{\substack{l=i \\ l=0, \dots, m}} \left(\rho_2(s_i, t) \frac{x - \rho_1(s_l, t)}{\rho_1(s_i, t) - \rho_1(s_l, t)} \right) \\
 &= \sum_{i=0}^m \prod_{\substack{l=i \\ l=0, \dots, m}} \left(P_i^2 \left(\frac{1+t}{t} \right) \frac{x - P_l^1 \left(\frac{1+t}{t} \right)}{P_i^1 \left(\frac{1+t}{t} \right) - P_l^1 \left(\frac{1+t}{t} \right)} \right),
 \end{aligned}$$

where $P_i^1, P_i^2, i = 0, \dots, m$, are the polynomials obtained in step S1.

Notice that for the sake of a simpler parameterization we have used two different ways of interpolation for the lower and upper parts.

Figure 8 shows results of numerical tests using Matlab program. For these computations we assume the conductivity $k = 3$. The boundary integral is discretized at 16,000 boundary points. This large number of points will be used throughout the paper. After doing experiments on the accuracy of the method, we have chosen this number to make the numerical computations precise, since as the cross gets thinner, the domain variations affect very little the PT. The dots in the left figure of Figure 8 are the computed eigenvalue pairs of the PT associated with $U(s, t)$ for $s = 0, 0.2, \dots, 1$ and $t = 2, 3, \dots, 18$. The solid-curves are graphs of $P(x, t)$ fitting dots, which are computed following the procedure described in steps S1 and S2. We use $S := \{0, 0.4, 1\}$ and $T := \{2, 3, \dots, 18\}$ for the computation of $P(x, t)$. The right hand side figure is for $L(s, t)$, $s = 1, 1.1, \dots, 1.9$, $t = 2, 3, \dots, 18$. Numerical values for the eigenvalues are recorded in Tables 1 and 2. Figure 9 shows whole foliation by $P(x, t)$ of the HS bounds.

5 Asymptotics of PT for thin crosses, and analytic accuracy of the foliation

On Figure 5 we see that the upper trace bound is reached by the PT corresponding to $E(t)$ as t tends to infinity. It also seems that as the cross becomes thinner and longer, the corresponding PT approaches the upper trace bound.

Table 1. The eigenvalue pairs $(\lambda_1^U(s, t), \lambda_2^U(s, t))$ associated with $U(s, t)$

$t \backslash s$	0	0.2	0.4	0.8	1
2	(1.0111,1.0111)	(0.9736,1.0463)	(0.9376,1.0847)	(0.8778,1.1640)	(0.8571,1.2000)
3	(1.0443,1.0443)	(0.9812,1.1021)	(0.9194,1.1656)	(0.8227,1.2886)	(0.8000,1.3333)
4	(1.0737,1.0737)	(0.9945,1.1480)	(0.9160,1.2292)	(0.7938,1.3803)	(0.7692,1.4286)
5	(1.0981,1.0981)	(1.0074,1.1852)	(0.9171,1.2798)	(0.7767,1.4498)	(0.7500,1.5000)
6	(1.1182,1.1182)	(1.0187,1.2158)	(0.9195,1.3208)	(0.7656,1.5042)	(0.7368,1.5556)
7	(1.1351,1.1351)	(1.0285,1.2413)	(0.9220,1.3548)	(0.7578,1.5482)	(0.7273,1.6000)
8	(1.1491,1.1491)	(1.0366,1.2627)	(0.9243,1.3833)	(0.7520,1.5844)	(0.7200,1.6364)
9	(1.1622,1.1622)	(1.0443,1.2815)	(0.9268,1.4078)	(0.7475,1.6147)	(0.7143,1.6667)
10	(1.1717,1.1717)	(1.0497,1.2970)	(0.9282,1.4286)	(0.7438,1.6407)	(0.7097,1.6923)
11	(1.1811,1.1811)	(1.0552,1.3111)	(0.9299,1.4470)	(0.7410,1.6629)	(0.7059,1.7143)
12	(1.1881,1.1881)	(1.0591,1.3229)	(0.9308,1.4629)	(0.7382,1.6824)	(0.7027,1.7333)
13	(1.1964,1.1964)	(1.0640,1.3344)	(0.9325,1.4773)	(0.7361,1.6995)	(0.7000,1.7500)
14	(1.2025,1.2025)	(1.0675,1.3441)	(0.9335,1.4901)	(0.7342,1.7147)	(0.6977,1.7647)
15	(1.2077,1.2077)	(1.0703,1.3527)	(0.9341,1.5013)	(0.7325,1.7281)	(0.6957,1.7778)
16	(1.2134,1.2134)	(1.0736,1.3609)	(0.9351,1.5117)	(0.7309,1.7403)	(0.6939,1.7895)
17	(1.2205,1.2205)	(1.0779,1.3690)	(0.9368,1.5213)	(0.7299,1.7511)	(0.6923,1.8000)
18	(1.2272,1.2272)	(1.0819,1.3764)	(0.9384,1.5301)	(0.7282,1.7613)	(0.6909,1.8095)

Table 2. The eigenvalue pairs $(\lambda_1^L(s, t), \lambda_2^L(s, t))$ associated with $L(s, t)$

$t \backslash s$	0	0.2	0.4	0.8	1
1	(1.0111,1.0111)	(1.0078,1.0078)	(1.0048,1.0048)	(1.0006,1.0006)	(1.0000,1.0000)
1.1	(1.0111,1.0111)	(1.0027,1.0130)	(0.9946,1.0152)	(0.9812,1.0208)	(0.9767,1.0244)
1.2	(1.0111,1.0111)	(0.9981,1.0178)	(0.9856,1.0248)	(0.9642,1.0399)	(0.9565,1.0476)
1.3	(1.0111,1.0111)	(0.9940,1.0222)	(0.9775,1.0339)	(0.9491,1.0581)	(0.9388,1.0698)
1.4	(1.0111,1.0111)	(0.9903,1.0264)	(0.9702,1.0424)	(0.9357,1.0753)	(0.9231,1.0909)
1.5	(1.0111,1.0111)	(0.9869,1.0302)	(0.9636,1.0504)	(0.9237,1.0917)	(0.9091,1.1111)
1.6	(1.0111,1.0111)	(0.9838,1.0338)	(0.9575,1.0580)	(0.9128,1.1074)	(0.8966,1.1304)
1.7	(1.0111,1.0111)	(0.9810,1.0372)	(0.9520,1.0652)	(0.9029,1.1224)	(0.8852,1.1489)
1.8	(1.0111,1.0111)	(0.9783,1.0404)	(0.9468,1.0720)	(0.8938,1.1368)	(0.8750,1.1667)
1.9	(1.0111,1.0111)	(0.9759,1.0434)	(0.9421,1.0785)	(0.8855,1.1506)	(0.8657,1.1837)

The first result of this section show that this is indeed what is predicted by the asymptotics.

Theorem 5.1 The PT $M_{D(t)}$ associated to $D(t)$ satisfies

$$\lim_{t \rightarrow \infty} M_{D(t)} = \frac{(k-1)(k+1)}{2k} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}. \quad (5.5.1)$$

On Figure 9, it seems that as the “thinness” parameter t becomes large, the curve described by $(\lambda_1^U(s, t), \lambda_2^U(s, t))$ as s varies between 0 and 1 appears to be a straight line. This can be measured on table 1 as well. The cross-shape was designed to be “simple”

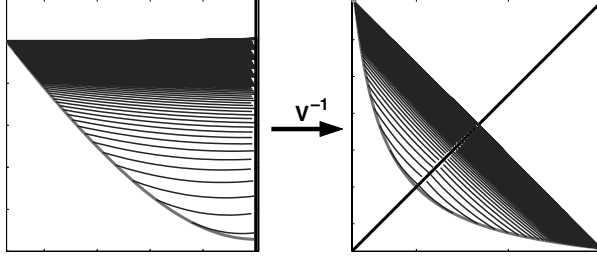


FIGURE 9. The numerical results for the foliation.

from a computational point of view. The drawback is that obtaining precise analytical results for this shape is unreasonably technical. We shall show that the affine nature of the curve $(\lambda_1^U(s, t), \lambda_2^U(s, t))$ is asymptotically correct for a similar (but different) cross for which analytical computations are simpler.

The alternate cross we consider is given as follows. Let F_t and S_t be a “flat” elliptic beam and a “standing” elliptic beam given by

$$F_t : \frac{x^2}{b^2} + \frac{y^2}{a^2} = 1, \quad S_t : \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, \quad a = \frac{1}{\sqrt{2\pi t}}, \quad b = ta.$$

Define $X_t := F_t \cup S_t$, and following the approach introduced in section 3, define for all $s \in [0, 1]$ and $t \in [1, \infty)$,

$$U(s, t) = sE(t) + (1 - s)X(t),$$

the domain of unit area obtained by radial interpolation between $X(t)$ and $E(t)$. The second result of this section shows that as s varies between 0 and 1, the curve described by $(\lambda_1^U(s, t), \lambda_2^U(s, t))$ is asymptotically a line.

Theorem 5.2 *The PT $M_{U(s,t)}$ associated to $U(s, t)$ satisfies*

$$M_{U(s,t)} = \frac{(\sqrt{2}s + 1 - s)^2}{(\sqrt{2}s + 1 - s)^2 + (1 - s)^2} M_{U(1,t)} + \frac{(1 - s)^2}{(\sqrt{2}s + 1 - s)^2 + (1 - s)^2} M_{U(0,t)} + \epsilon(t),$$

where $\epsilon(t)$ tends to zero as t tends to infinity.

We shall start by proving Theorem 5.1.

Note that $D(t)$ can be approximated by $\tilde{D}_t = H_t \cup V_t$, where

$$H_t = \left[-\sqrt{\frac{t}{8}}, \sqrt{\frac{t}{8}} \right] \times \left[-\frac{1}{\sqrt{8t}}, \frac{1}{\sqrt{8t}} \right] \quad \text{and} \quad V_t = \left[-\frac{1}{\sqrt{8t}}, \frac{1}{\sqrt{8t}} \right] \times \left[-\sqrt{\frac{t}{8}}, \sqrt{\frac{t}{8}} \right].$$

The difference between the two domains are the smooth corners of $D(t)$, and the surface of $H_t \cup V_t$ which is not exactly one. It is easy to see that, for every $t > 0$ there exists t_1 and t_2 and λ such that

$$|t_1 - t_2| + |\lambda - 1| \leq \frac{C}{t},$$

where C is a constant independent of t , and $\tilde{D}_{t_1} \subset D(t) \subset \lambda \tilde{D}_{t_2}$. Since the polarization tensors are monotonous with respect to inclusion, we deduce that

$$M_{D(t)} = M_{\tilde{D}(t)} + O\left(\frac{1}{t}\right).$$

In the sequel, we will identify D and $\tilde{D}(t)$. The asymptotic limit of the polarization tensor of a single thin beam is known [7]. We have

$$\lim_{t \rightarrow \infty} M_{H(t)} = \frac{1}{2} \begin{pmatrix} k-1 & 0 \\ 0 & \frac{k-1}{k} \end{pmatrix}, \text{ and } \lim_{t \rightarrow \infty} M_{V(t)} = \frac{1}{2} \begin{pmatrix} \frac{k-1}{k} & 0 \\ 0 & k-1 \end{pmatrix}.$$

Given $\xi \in \mathbb{R}^2$, let $w_t^\xi \in W^{1,2}$ be the solution to

$$\Delta w_t = (1-k)\nabla \cdot (\chi(D(t))(\nabla w_t + \xi)),$$

and let h_t^ξ , and v_t^ξ be the solutions to the same equations with $D(t)$ replaced with H_t and V_t , respectively. The following lemmas hold.

Lemma 5.3 *For any unit vector $\xi = (\xi_1, \xi_2)$, the functions h_t^ξ and v_t^ξ satisfy*

$$\left\| \nabla h_t^\xi + \chi(H_t) \frac{1-k}{k} \xi_2 e_2 \right\|_{L^2(\mathbb{R}^2)} = \epsilon(t), \text{ and } \left\| \nabla v_t^\xi + \chi(V_t) \frac{1-k}{k} \xi_1 e_1 \right\|_{L^2(\mathbb{R}^2)} = \epsilon(t), \quad (5.5.2)$$

where $\lim_{t \rightarrow \infty} \epsilon(t) = 0$.

Proof Write $M(H_t) = (M_t^{ij})_{i,j=1,2}$. Since

$$M_t^{1,1} = \frac{k-1}{2} + \epsilon(t) \quad \text{as } t \rightarrow \infty,$$

it follows from (2.2.3) and (2.2.4) that

$$\int_{\mathbb{R}^2} \gamma_{H_t} |\nabla h_t^{e_1}|^2 = \epsilon(t).$$

On the other hand, since $M_t^{2,2} = (k-1)/2k + \epsilon(t)$ as $t \rightarrow \infty$, we get from (2.2.3) that

$$\int_{\mathbb{R}^2} \gamma_{H_t} \left| \nabla h_t^{e_2} + \frac{k-1}{k} \chi(H_t) e_2 \right|^2 = \epsilon(t).$$

Since $h_t^\xi = \xi_1 h_t^{e_1} + \xi_2 h_t^{e_2}$, we obtain the first limit in (5.5.2). The second estimate can be proved in a similar fashion. $\square$

Lemma 5.4 *For each unit vector ξ , we have*

$$\left\| \nabla w_t^\xi - \left(\nabla h_t^\xi + \nabla v_t^\xi \right) \right\|_{L^2(\mathbb{R}^2)} = \epsilon(t), \quad (5.5.3)$$

where $\lim_{t \rightarrow \infty} \epsilon(t) = 0$.

Proof Let us, for simplicity, drop superscripts ξ . Since

$$\|\nabla h_t\|_{L^2(H_t \cap V_t)} \leq \left\| \nabla h_t + \chi(H_t) \frac{1-k}{k} \xi_2 e_2 \right\|_{L^2(H_t \cap V_t)} + \xi_2 |H_t \cap V_t| = \epsilon(t),$$

it follows from (5.5.2) that

$$\|\nabla h_t\|_{L^2(V_t)} = \epsilon(t). \quad (5.5.4)$$

Likewise we get

$$\|\nabla v_t\|_{L^2(H_t)} = \epsilon(t). \quad (5.5.5)$$

By simple algebra, we obtain

$$\begin{aligned} & \nabla \cdot \gamma_{D(t)} \nabla (w_t - h_t - v_t) \\ &= (k-1) \nabla \cdot (\chi(V_t) \nabla h_t + \chi(H_t) \nabla v_t) - (k-1) \nabla \cdot (\chi(H_t \cap V_t) (\nabla h_t + \nabla v_t + \xi)). \end{aligned}$$

If we multiply the above equation by a test function ϕ and integrate by parts, we get

$$\int_{\mathbb{R}^2} \gamma_{X_t} \nabla (w_t - h_t - v_t) \cdot \nabla \phi = (k-1) (A + B + C)$$

with

$$\begin{aligned} |A| &= \left| \int_{H_t \cap V_t} (\nabla h_t + \nabla v_t + \xi) \cdot \nabla \phi \right| \leq \|\nabla h_t + \nabla v_t + \xi\|_{L^2(H_t \cap V_t)} \|\nabla \phi\|_{L^2(\mathbb{R}^2)}, \\ |B| &= \left| \int_{V_t} \nabla h_t \cdot \nabla \phi \right| \leq \|\nabla h_t\|_{L^2(V_t)} \|\nabla \phi\|_{L^2(\mathbb{R}^2)}, \\ |C| &= \left| \int_{H_t} \nabla v_t \cdot \nabla \phi \right| \leq \|\nabla v_t\|_{L^2(H_t)} \|\nabla \phi\|_{L^2(\mathbb{R}^2)}. \end{aligned}$$

Thanks to (5.5.4) and (5.5.5), we obtain

$$\left| \int_{\mathbb{R}^2} \gamma_{D(t)} \nabla (w_t - h_t - v_t) \cdot \nabla \phi \right| \leq \|\nabla \phi\|_{L^2(\mathbb{R}^2)} \epsilon(t),$$

for any test function ϕ , and hence (5.5.3) follows. $\square$

We are now ready to prove Theorem 5.1.

Proof of Theorem 5.1 By (2.2.1) we have

$$M_{D(t)} \xi \cdot \xi = (k-1) \left[1 + (k-1) \int_{D(t)} \xi \cdot \nabla w_t^\xi dx \right],$$

for any $\xi \in \mathbb{R}^2$. It then follows from (5.5.3) that

$$M_{D(t)} \xi \cdot \xi = (k-1) \left[1 + (k-1) \int_{D(t)} \xi \cdot (\nabla h_a^\xi + \nabla v_d^\xi) dx \right] + \epsilon(t). \quad (5.5.6)$$

From (5.5.2) we obtain that

$$\begin{aligned} \int_{D(t)} \xi \cdot (\nabla h_t^\xi + \nabla v_t^\xi) dx &= \int_{H_t} \xi \cdot \nabla h_t^\xi + \int_{V_t} \xi \cdot \nabla v_t^\xi + \int_{D(t) \setminus H_t} \xi \cdot \nabla h_t^\xi + \int_{D(t) \setminus V_t} \xi \cdot \nabla v_t^\xi \\ &= \int_{H_t} \xi \cdot \nabla h_t^\xi + \int_{V_t} \xi \cdot \nabla v_t^\xi + \epsilon(t). \end{aligned}$$

Therefore, (5.5.6) yields

$$M_{D(t)} \xi \cdot \xi = M_{V(t)} \xi \cdot \xi + M_{H(t)} \xi \cdot \xi + \epsilon(t).$$

Now, (5.5.1) immediately follows from (5). □

Proof of Theorem 5.2 We have introduced

$$U(s, t) = sE(t) + (1 - s)X(t),$$

that is, a domain with vertical and horizontal symmetries defined in the first quadrant as the domain inside the curve given, in polar coordinates, by

$$\begin{aligned} \text{for } 0 \leq \varphi \leq \frac{\pi}{4}, \quad \rho_U(\varphi) &= \sqrt{\frac{t}{2\pi}} \left(\frac{\sqrt{2}s}{\sqrt{t^2 \cos^2(\varphi) + \sin^2(\varphi)}} + \frac{1-s}{\sqrt{t^2 \sin^2(\varphi) + \cos^2(\varphi)}} \right) \\ \text{for } \frac{\pi}{4} \leq \varphi \leq \frac{\pi}{2}, \quad \rho_U(\varphi) &= \sqrt{\frac{t}{2\pi}} \frac{\sqrt{2}s + 1 - s}{\sqrt{t^2 \cos^2(\varphi) + \sin^2(\varphi)}}. \end{aligned}$$

With this definition, we can compute

$$|U(s, t)| = \int_0^{\frac{\pi}{4}} \frac{1}{2} \rho_U^2(\varphi) d\varphi + \int_{\frac{\pi}{4}}^{\frac{\pi}{2}} \frac{1}{2} \rho_U^2(\varphi) d\varphi = \frac{(1-s)^2}{2} + \frac{(\sqrt{2}s + 1 - s)^2}{2} + \epsilon(t).$$

Furthermore, we see that, up to a small volume, $U(s, t) = \tilde{F}_{st} \cup \tilde{S}_{st} + \epsilon(t)$, where

$$\tilde{F}_{st} : \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1, \quad \tilde{S}_{st} : \frac{x^2}{c^2} + \frac{y^2}{d^2} = 1, \quad a = \frac{\sqrt{2}s + 1 - s}{\sqrt{2\pi t}}, \quad b = ta$$

and

$$c = td, \quad d = \frac{(1-s)}{\sqrt{2\pi t}}.$$

Arguing as before, we see that the PT corresponding to $U(s, t)$ is equal to the PT corresponding to $\tilde{F}_{st} \cup \tilde{S}_{st}$, up to an error $\epsilon(t)$ which tends to zero as t tends to infinity. The polarization tensors of $\tilde{F}_{st}$ and $\tilde{S}_{st}$ are known [8] and given by (3.3.3). Thus we have

$$\lim_{t \rightarrow \infty} M_{F_{st}} = \|F_{st}\| \begin{pmatrix} k-1 & 0 \\ 0 & \frac{k-1}{k} \end{pmatrix}, \quad \text{and} \quad \lim_{t \rightarrow \infty} M_{S(t)} = \|S_{st}\| \begin{pmatrix} \frac{k-1}{k} & 0 \\ 0 & k-1 \end{pmatrix}.$$

Using the same arguments that in the proof of Theorem 5.1, with $D(t)$, $H(t)$ and $V(t)$

replaced by $U(s, t)$, $\tilde{F}_{st}$ and $\tilde{S}_{st}$ respectively, formula (5) becomes

$$\|U(s, t)\| M_{U(s, t)} \xi \cdot \xi = M_{F_{st}} \xi \cdot \xi + M_{S_{st}} \xi \cdot \xi + \epsilon(t),$$

which, together with (5), concludes the proof of Theorem 5.2. $\square$

In concluding this section, we would like to refer to the recent paper by Capdeboscq and Kang [9] where it is shown that if the domain contains certain set of volume and is not thin than its PT stays away from the upper HS-bound.

It is also worth noticing that the asymptotic result in this section holds in the three-dimensional case as well. Indeed, taking combinations of ellipsoids, we can show by exactly the same arguments as those presented above the optimality of the upper bounds (1.1.1) and (1.1.2).

6 Identification of domains

In this section, given a pair (λ_1, λ_2) inside the HS bounds, we present a method to find the parameters s and t , such that this pair arises as the eigenvalue pair of the PT associated with $U(s, t)$ or $L(s, t)$.

Our procedure is described in the following.

Identification algorithm

S'1. Given $(\lambda_1, \lambda_2) \in A_1$, transform it into

$$(\rho_1, \rho_2) := V(\lambda_1, \lambda_2).$$

S'2. Find the zero $t^* \geq 2$ satisfying

$$P(\rho_1, t^*) = \rho_2.$$

Here $P(x, t)$ is the polynomial computed in the previous section.

S'3. Compute $(\rho_1(s_i, t^*), \rho_2(s_i, t^*))$ for $s_i \in S$. From these data, we derive the relation between s and $\rho_1(s, t^*)$ as follows:

$$x_1(s) = \sum_{i=0}^m \prod_{l \neq i} \left(\rho_1(s_i, t^*) \frac{s - s_l}{s_i - s_l} \right), \quad 0 \leq s \leq 1.$$

S'4. Find s^* so that

$$x_1(s^*) = \rho_1.$$

We can check the validity of the above algorithm by computing the relative error. If (s^*, t^*) is the computed pair of parameters, then we calculate the eigenvalues $\lambda_1(s^*, t^*)$ and

Table 3. *The numerical results for the identification algorithm. For a given eigenvalue pair (λ_1, λ_2) , we compute the parameters t^*, s^* of the domain and find the eigenvalues $(\lambda_1(s^*, t^*), \lambda_2(s^*, t^*))$. The last column is the relative error*

(λ_1, λ_2)	t^*	s^*	$(\lambda_1(s^*, t^*), \lambda_2(s^*, t^*))$	$\frac{ (\lambda_1, \lambda_2) - (\lambda_1(s^*, t^*), \lambda_2(s^*, t^*)) }{ (\lambda_1, \lambda_2) }$
(1.0470, 1.2893)	9.5607	0.1992	(1.0480, 1.2902)	8.0838E-4
(0.8277, 1.4614)	6.8182	0.6081	(0.8248, 1.4586)	2.3709E-3
(1.2060, 1.2060)	14.4493	4.7730E-15	(1.2062, 1.2062)	2.1222E-4
(0.9387, 1.5378)	19.0739	0.4008	(0.9403, 1.5394)	1.2567E-3
(0.7274, 1.7702)	18.4077	0.8089	(0.7253, 1.7681)	1.5114E-3
(1.1015, 1.4132)	26.7781	0.1981	(1.1065, 1.4182)	3.9419E-3

$\lambda_2(s^*, t^*)$ of its associated PT. We can see the order of the relative error by computing

$$\frac{|(\lambda_1, \lambda_2) - (\lambda_1(s^*, t^*), \lambda_2(s^*, t^*))|}{|(\lambda_1, \lambda_2)|}.$$

As shown in Table 3, the above algorithm identifies the parameterized domain pretty well.

7 Conclusion

In this paper we proved that the PT associated with crosses approaches to the upper bound as cross gets thinner and longer. We then show, by numerical computations based on a boundary integral method, that every point inside the Hashin-Shtrikman bounds for polarization tensors can be attained by a simply connected domain which is given explicitly in terms of two parameters. We also present a method to find the parameters corresponding to a given pair of eigenvalues inside the Hashin-Shtrikman bounds.

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