

The Making of Continuous Colormaps

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Abstract—Continuous colormaps are integral parts of many visualization techniques, such as heat-maps, surface plots, and flow visualization. Despite that the critiques of rainbow colormaps have been around and well-acknowledged for three decades, rainbow colormaps are still widely used today. One reason behind the resilience of rainbow colormaps is the lack of tools for users to create a continuous colormap that encodes semantics specific to the application concerned. In this paper, we present a web-based software system, CCC-Tool (short for *Charting Continuous Colormaps*) under the URL <https://ccctool.com>, for creating, editing, and analyzing such application-specific colormaps. We introduce the notion of “colormap specification (CMS)” that maintains the essential semantics required for defining a color mapping scheme. We provide users with a set of advanced utilities for constructing CMS’s with various levels of complexity, examining their quality attributes using different plots, and exporting them to external application software. We present two case studies, demonstrating that the CCC-Tool can help domain scientists as well as visualization experts in designing semantically-rich colormaps.

Index Terms—CCC-Tool, charting continuous colormaps, colormap specification, perceptual uniformity, colormap analysis.

1 INTRODUCTION

DESIGNING colormaps is one of the most abiding and prevailing topics in the field of visualization. The critiques of rainbow colormaps by Rogowitz and Treinish [1], Borland and Taylor II [2], and many others have been discussed in almost every course on data visualization, and in the tutorial on color theory by Rhyne [3] that has been a fixture in IEEE VIS for many years. Online software systems for recommending colormaps, such as *ColorBrewer* [4], have been popular among visualization researchers and practitioners. Many practitioners of different application domains prefer discrete colormaps for mapping continuous data by filled contours (e.g., [5]). However, in recent years, there was a noticeable amount of research effort on categorical colormaps (e.g., [6], [7], [8], [9]) as well as a refreshed interest in continuous colormaps (e.g., [10], [11], [12]). As part of this continuing collective effort by the visualization community, this work focuses on the specification of continuous colormaps.

While the critiques of rainbow colormaps are widely acknowledged, they are still widely used. Many domain scientists are aware of more effective choices (e.g., [5]). However, there are many possible reasons why rainbow colormaps are still often employed. Some visualization tools use rainbow as a default colormap. Further explanations are, e.g., the use of legacy code, the need for compatibility to existing visualizations, the effort needed to customize

colormaps, or lacking guidance on effective alternatives. Commonly used visualization software contain as many as one hundred predefined colormaps. These colormaps, however, do not encode domain-specific semantics (e.g., points of freezing, melting, boiling, etc.), various categorizations (e.g., periods, phases, wavelengths, quality levels, etc.), and various critical values (e.g., between safe and unsafe, normal and abnormal, and profit and loss, etc.). To account for the actual data visualized, predefined colormaps may need to be modified and adapted to domain specific semantics. While there are colormap creation tools available, the above characteristics are difficult to attain [11], [13], [14]. Thus users often default to the traditional rainbow, cool warm and viridis colormaps, in which they are accustomed to the association between colors and domain-specific semantics. Other existing software systems (e.g., [11]) use interactive exploration techniques for the creation of colormaps. While this is beneficial for single cases, the resulting colormaps might not be optimal for different datasets captured with similar mechanisms, for automated generation of visualizations in routine activities.

Without a protocol and an easy-to-use tool for specifying and analyzing colormaps, many application users could not propose and deliberate any new standard colormap without writing programs for generating and analyzing new colormaps. In the field of visualization, there is a consensus that a continuous colormap should provide perceptually-uniform mapping from values to colors [10], [12], [15]. However, perceptually-uniform mapping comes with a trade-off with resolving power. The value of the resolution versus the equality can have a very significant impact on the information revealed, and this is a decision for the scientist. Limited software for the creation of perceptually-uniform colormaps or the analysis of colormaps to perceptual-uniformity hinders the creation of such colormaps. Furthermore, implementing this wisdom is curtailed by current limitations in color science and technology. All relatively sophisticated color difference metrics are only considered to be correct

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Manuscript received Month Day, 2018; revised Month Day, 2018.

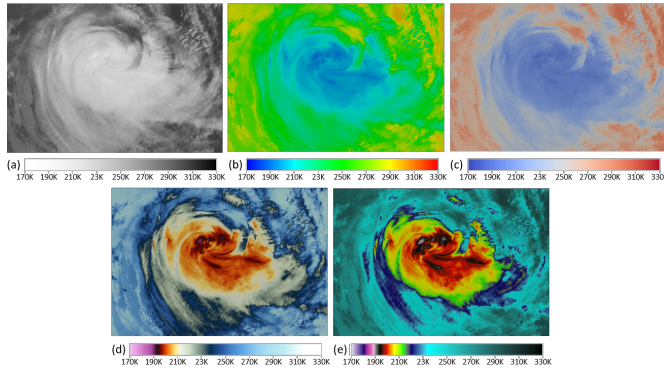


Fig. 1: Given a scalar field, e.g., a temperature field of a hurricane in (a), we all agree a rainbow colormap is not the best solution (b). We can also observe the commonly-used blue-white-red map (c) is unsuitable as the semantics of using white to represent 250 Kelvin can cause confusion. Using more color bands with brightness variation helps (d). As shown in (e), Scientists introduced some semantics into the colormap, such as discontinuous transitions at 192K and 189K as well as a very wide color band between 225-330.

in the precisely-controlled laboratory testing environments.

In this paper, we propose to separate the specification from the realization of a colormap. The latter is traditionally given in the form of an array of gradually-changing colors or a hard-coded color-mapping function. We propose that the specification should focus primarily on encoding domain-specific semantics, and on enabling application users to address the aforementioned obstacles. We have developed a web-based software tool, called **CCC-Tool** (*Charting Continuous Colormaps*), based on the idea of a general tool for the creation and export of colormaps with the effort to minimize the needed interaction components. This foundation of the tool is extended by a collection of recommended colormaps, which can be adapted to encode the users own domain-specific semantics, and the facilities for analyzing colormaps. CCC-Tool supports a number of commonly-used color spaces and color difference metrics, currently including RGB, HSV, CIELAB, CIELCH, CIE94, CIEDE2000, and DIN99.

CCC-Tool complements the existing web sites (e.g., [16], [17], [18]) and software systems (e.g., [11], [19]) that recommend continuous colormaps by enabling users to adapt the recommended design ideas more easily. CCC-Tool also complements the existing color-based data exploration tools, such as ColorMoves [11]. On the one hand, tools such as ColorMoves allow users to explore various colormaps that can depict interesting patterns. On the other hand, CCC-Tool allows users to specify a standard or de facto standard based on a collection of default colormaps resulting from exploring specific datasets. Here it is helpful to point out that a standard or de facto standard map is designed to enable the visualization of all possible datasets that may be captured with similar mechanisms. So a standard map is not necessarily optimized for a known dataset, but should be optimized in general for all possible datasets in relation to various visualization tasks that may be performed using the colormap.

2 RELATED WORK

Colormapping. A popular method for visualizing a scalar field is *colormapping* [12], [20], [21]. A colormap defines a path through a colorspace [10]. A narrow interpretation of “continuous colormap” implies the continuity of the colormap, while a broad interpretation implies the continuity of the scalar field, while the path can be comprised of one or more path-segments. In this work, we adopt the broad interpretation.

Color Spaces. The space of all colors is in principal infinite dimensional, but since the human eye has only three receptors for color, the space of distinguishable colors is only three-dimensional [22], [23]. Depending on the choice of the three basis dimensions, many different colorspace were developed. The XYZ space by the Commission Internationale de L’Eclairage (CIE) is considered as the basis of all modern color spaces [24], [25]. It embeds all visible colors unambiguously into one space of three imaginary primaries [26], [27]. A number of spaces, e.g., CIELAB, CIELCH, CIELUV, DIN99, and CIECAM [25], [28], [29] were defined as transformations of XYZ in order to derive an ideal color space [30], where the Euclidean distance is proportional to the perceived color difference. The state of the art in color science indicates that such an ideal color space is yet to come because of the complexity of human vision [31], [32], [33]. Some color standards, e.g., CIELAB with ΔE_{1994} and ΔE_{2000} , address this problem by introducing a non-Euclidean metric on top of a color space [34], [35], [36]. It is widely advocated to use a perceptually *near-uniform* color space for the design, assessment, and improvement of colormaps [37], [38], [39], [40], [41], [42].

Design Guidelines. Many guidelines for colormap design have been proposed. Some have been applied intuitively for centuries [43]. The most popular ones include discriminative power, uniformity, order, smoothness, and monotonicity [10].

Discriminative power [37], [39], [44], [45], [46], [47], [48] refers to the length of a colormap’s path through a color space. It may be measured by the just-noticeable-differences along the path, or coarsely the number of distinguishable colors. The bigger the discriminative power, the higher contrast among pixels with different data values and the more details of the data can be observed. This guideline is sometimes in conflict with other needs such as color symbolism, *order*, and *monotonicity*.

Uniformity [1], [2], [40], [41], [49], [50], [51], [52] describes how well perceived color differences resemble differences in the data values. A perceptually near-uniform colormap represents the underlying patterns of the data more truthfully. This guideline is not always followed due to the difficulties mentioned in Section 1 and the early part of this section.

Order [15], [44], [50], [53], [54], [55] commonly refers to the easiness for observers to determine the order of different colors preattentively or based on learning [10]. It can be measured through experiments where observers are presented a subset of colors from a colormap and given the task to sort them in order. A colormap is considered to be more ordered if more observers could sort the colors in the same order as defined in the colormap. This guideline

is usually followed within each individual color band in a colormap, but not always applied to the colors across different bands.

Smoothness [37], [47], [48], [50] refers to a colormap without discrete bands or sudden color changes. It prevents the misinterpretation of discontinuity when the underlying data is continuous. This guideline is sometimes intentionally violated in order to observe the nominal categorization of continuous data or critical values in the data.

Monotonicity assures the changes of colors within a band depend on only one color attribute. Many advocate monotonicity in luminance [1], [2], [38], [51], [54], [56], [57], [58], [59], [60], [61], but some also suggest monotonicity in hue, saturation, or simple paths in the RGB space [39], [46], [62]. The guideline relates to the guideline of order, but is in conflict with *discriminative power*.

A good summary of design guidelines is given by Rheingans et al. [59] and a taxonomy that differentiates the contexts in which these guidelines have been used is discussed by Bujack et al. [10]. As discussed above these design guidelines are not absolute laws. Some of them are competing and a trade-off needs to be found. In some applications, one or more guidelines have to be violated in order to meet domain-specific needs [63], [64].

Rainbow. The rainbow colormap remains to be one of the most used colormaps even though many visualization researchers have described its potential shortcomings for decades [1], [2], [37], [48], [54]. It transverses the color spectrum in the order of wavelength [2], [45], [65]. One problem is that this order is not universally perceived [45], [46], [59], [62], [65]. If presented with just a few of its colors arbitrarily chosen, observers tend to sort them very differently, e.g., by luminance or alphabetically [2], [15]. Another problem is its lack in perceptual uniformity. In some bands (especially around green), colors are transversed much slower than others, hiding features in the data. The inconsistent variation of luminance causes inconsistent banding that distorts the perception of data changes [1], [2], [54].

Tools. Most popular visualization tools like **ParaView** [66] and **VisIt** [67] have a basic integrated colormap editor. But except for having defaults, they do not provide any guidance for the user. The visualization community provides tools for the guided selection of colormaps. Pioneering work in this realm has been done in PRAVDA Color [57]. Here, colormaps are suggested based on the visualization task, data types, and spatial frequency. Also **ColorBrewer** [13] provides carefully designed discrete color palettes and recommendations. **I want Hue** uses custom restriction of hue, chroma, and luminance to calculate discrete color palettes based on the CIE Lab colorspace. A different approach is followed by the tools **Color Hex**, **Adobe Color CC**, or **COLRD**. They provide mechanisms so users can generate, share, rate and/or comment palettes. **ColorCAT** [14] extends PRAVDA Color and also encompasses for combinations of visualization tasks. There is an extension to matplotlib [68] called **VisCM**. Based on CIECAM, the user can create near-uniform colormaps that increase linearly in luminance, like the new matplotlib default **Viridis**. However, the emphasis on monotony in luminance restricts the users from meeting other requirements in their applications. **ColorMoves** [11]

enables scientists to build colormaps visually customized to align with their data facilitating feature identification and exploration as well as colormaps specifically designed for communication purposes. The custom colormaps are built by assigning pre-designed colormaps to specific regions within the data and seeing the results in real-time on one's data. While this enables the construction of colormaps tuned to a specific data set, it is not designed to produce colormaps for general use. Being a customizing color construction tool it does not contain a means for evaluating the colormaps for widely applicable usage. **ColorMeasures** [10] analyzes the performance of a colormap based on popular design rules evaluated in different color spaces. While this informs the user on characteristics such as discriminatory power, uniformity and the other criteria in Section 2.3, it does not include the ability to create colormaps.

In this paper, we present our web-based colormap tool, by which we can reach a cross-platform ability that only requires an installed browser. This not only improves the accessibility towards tools like Paraview, VisIt, ColorCAT or VisCM but also enables a possible future publication functionality (sharing, rating, commenting) like it is done with discrete color palettes at tools like ColorHex, Adobe Color CC or COLRD. CCC-Tool complements the webtool ColorMoves, which allows to create colormaps exploratively per dataset, with the opportunity to build standardized colormaps for consistent visualizations. In contrast, the CCC-Tool is designed for consistent standard colormaps in application domains, intended for long-term use for many datasets and likely by many users. Therefore, it is helpful for the users to conduct some analysis about the quality of the proposed designs, even if color science may be considered as "often imprecise and idiosyncratic". This is the motivation of integrating the results by Bujack et al. [10] into CCC-Tool. There are some strengths of the current version of the CCC-Tool in comparison with other tools. The tool offers a platform independent web based availability and allows the use of perceptually uniform color spaces. With a separate selection of an interpolation method, it is also possible to create colormaps with the notation of commonly used colorspace (e.g., RGB), that also include the benefits of perceptually uniform colorspace. For experts, the tool has a range of color and metric settings. Additionally, this is the first tool, to the best of our knowledge, that combines the capability of generating, analyzing, and editing colormaps. This combination empowers the user to make informed decisions about where to closely follow the design rules and where to break them for the benefit of application specific conventions, tasks, audiences, or visualization goals.

3 REQUIREMENTS ANALYSIS AND SYSTEM OVERVIEW

The obstacles discussed in Section 1 provide the motivation for designing and developing a software tool that can enable easy creation of continuous colormaps for different visualization applications. Our requirement analysis, which was partly based on established expertise in colormaps within the team [6], [10], [11], [52], [64], [69], [70], [71], [72] and partly based on the feedbacks from domain scientists (in-

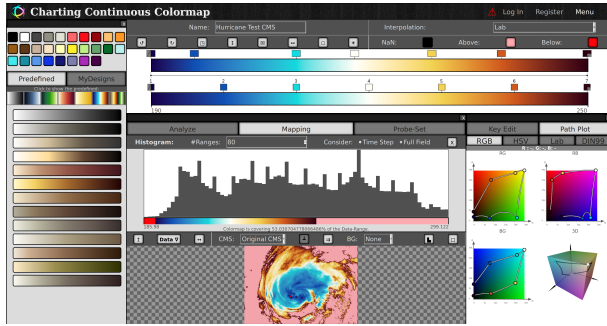


Fig. 2: The screenshot shows a version of Edit-Section of the CCC-Tool. On the left side, the Structure-Window offers constant bands at the top and below a set of predefined CMS or CMS from the MyDesigns list. The CMS-Window at the top right side shows the linear- and below the Band Sketch-visualization of the CMS. At the bottom are the Analysis-Window (left) and Edit-Window (Right), which shows a collection of utilities for Analysis, Color-Mapping, Probe-Sets, Key-Edit and Path-Plot-Edit. Most of these utilities will be detailed in sections 5 and 6.

cluding one co-author) in different applications, identified the following requirements:

- R1. A colormap can consist of multiple bands to meet the semantic needs of many applications as well as to capitalize confirmed cognitive advantages [56], [69].
- R2. A colormap can feature major transition points that represent important semantic values specific to an application.
- R3. A colormap can have a continuous color transition between two bands in order to facilitate depiction of the gradient of color transformation.
- R4. A colormap can have a discrete color transition between two bands in order to facilitate depiction of contour lines without additional algorithms.
- R5. A colormap can map a value range to a constant color (e.g., for depicting erroneous values).
- R6. Key elements of the colormap have freely selectable successive reference values.
- R7. A colormap can be edited without the need for modifying a large number of interval colors or writing a program to do so.
- R8. Users can browse a library of recommended colormaps, adopt or adapt them for their own applications, and use them as components for designing more complex colormaps.
- R9. Users can choose a color space (from some commonly-used color spaces and some perceptually-uniform color spaces) to interpolate colors across a color band.
- R10. Utilities are provided for users to measure and evaluate attributes of a colormap and visualize these attributes.
- R11. Users can export a conventional colormap (i.e., in an array of value-color intervals) to be used in applications where linear interpolation can

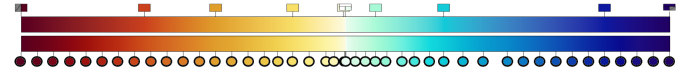


Fig. 3: This figure shows an example of a common colormap (bottom) with a high number of interval colors in comparison to a reproduction (top) according to the CMS idea of less key colors, for creation and editing, and an automatic calculation of many interval colors during the export. (Source: Paraview; Warm to Cool Extended)

be used to interpolate between intervals without the need for complex algorithms associated with some color spaces.

- R12. Ideally the system is available on the web to reach a large number of users around the world.
- R13. The system will be supported by online tutorials on using the system as well as guidance on designing colormaps.

Our web-based system was developed according to the above requirements. Fig. 2 shows a screenshot of the Edit-Section section of the CCC-Tool. We will describe the functions of the CCC-Tool in detail in Sections 4–6. The windows at the screenshot and the other sections of the tool address different requirements, such as: Edit-Window and Structure-Window for R1-R9 and Analysis-Window for R10, Gallery-Section for R8, Export-Section for R11 and Tutorial-Section for R13. The section MyDesigns stores up to ten user created colormaps and allows to manage them. In relation to the obstacles mentioned in the introduction, requirement R8 allows selecting a predefined colormap with specific semantics. R1, R2 and R7 facilitate the creation of new colormaps with semantic correlations or the modification of existing ones. Critical values can be highlighted with R2 or R4. With R6 we ensure the build of standardized colormaps for consistent visualization. The support of perceptually-uniform color spaces allows with R9 and R10 a perceptually-uniform mapping. Furthermore, the idea of the colormap specification allows creating new colormaps, which have the same basic structure and involve the latest future perceptually-uniform color spaces or metrics. CCC-Tool was developed in HTML, CSS and Javascript. It has been tested on the desktop browsers Firefox Version 59.0.1 and Google Chrome Version 64.0.3282.186.

4 COLORMAP SPECIFICATION

Continuous colormaps are traditionally stored and edited as arrays of interval colors (e.g., [19]). Often those colormaps can have a high number of intervals to reach perceptual uniformity, which is very important for software that is not able to interpolate in perceptually uniform colorspace (see example at Fig. 3). Another reason to use many interval colors are applications, that use the colormap as a discrete lookup table without linear interpolation. Hence, manually creating and editing such a colormap becomes a time-consuming and tedious task. In most applications where continuous colormaps are deployed, the users are typically interested in controlling the number of color bands, the overall color and their symbolism in each band, the mapping between bands and data ranges, and the transition points (in terms of their colors and data values) between consecutive bands.

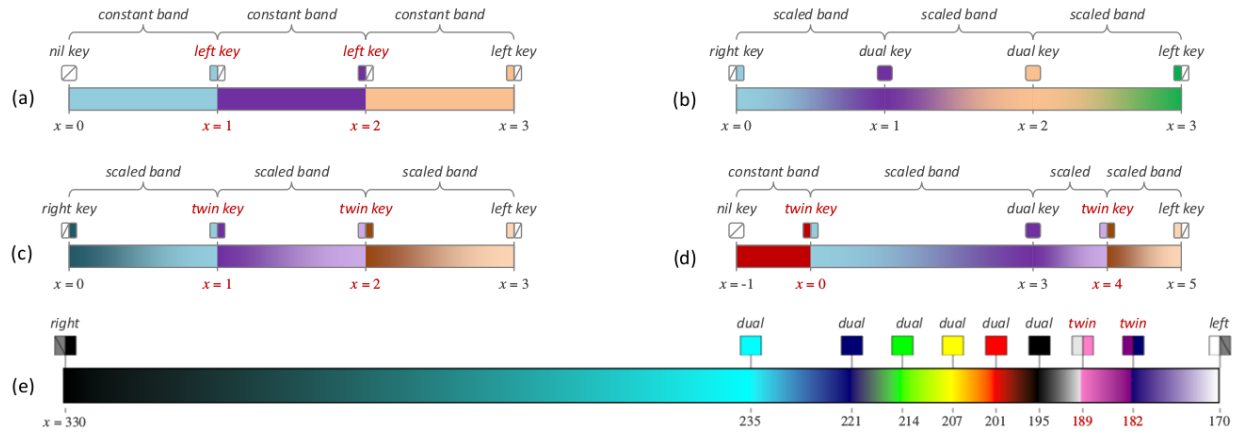


Fig. 4: Examples of creating colormap specifications using different keys. (a) A discrete colormap with 3 discrete colors for 3 data ranges. (b) A continuous colormap with 3 scaled color bands for 3 data ranges. (c) A continuous colormap with two discontinuous transition points (labeled with red texts). (d) A composite colormap features constant as well as scaled color bands and continuous as well as discontinuous transitions. The color bands also have different widths. (e) A CMS that recreates a NASA colormap used for visualizing Hurricane Irma data (7 September 2017).

In almost all situations, users typically wish to observe the gradient of the changes of data values, hence smooth transitions are desirable as shown in Fig. 1(a-d). In many situations, users may wish to be able to relate a pixel color with a particular data range at a glance, hence multiple color bands are desirable as in Fig. 1(b-d). Often one aspect of data semantics (e.g., danger) overwrites the other (e.g., color) as in Fig. 1(d,e). In some situations, users may wish to be able to identify an important data value easily in the visualization, hence a discrete transition between two color bands is useful as in Fig. 1(e). Occasionally, users may wish to map a particular data range (i.e., erroneous data values) to a single color.

All these suggest the necessity for a colormap specification that focuses on bands and major transition points rather than hundreds of interval colors. Users should be able to incorporate application-specific semantics into the color specification (e.g., the greenish band shows the value range related to a phenomenon X) rather than trying to make some vague associations (e.g., the colors from some shade of light blue to some shade of medium red are related to the phenomenon X).

Hence, in this section, we first consider the novel concept of the *Colormap Specification* (CMS), and then detail its conversion to the traditional interval-based colormap with discussions on color spaces and discrete transitions.

4.1 High-level and Flexible Specification

A colormap specification (CMS) consists of one or more *color bands* B_1, B_2, \dots, B_n ($n \geq 1$). Each band B_i is defined by two transition points, k_{i-1} and k_i , which are referred to as *keys*. Any two consecutive bands, B_i and B_{i+1} , share a common key k_i . Therefore, a CMS is stored as a sequence of keys, $k_0, k_1, k_2, \dots, k_n$.

Each key is a data tuple, $k := (\text{type}, x, c_L, c_M, c_R)$, where x is the corresponding data value in the overall data range to be encoded using colors. Let the overall data range be $[x_{\min}, x_{\max}]$ where $x_{\min}, x_{\max} \in \mathbb{R}$ and $x_{\min} \leq x_{\max}$. The x values in all the keys, $k_0, k_1, k_2, \dots, k_n$ in the CMS must

satisfy the conditions $x_0 = x_{\min} < x_1 < x_2 < \dots < x_n = x_{\max}$.

There are five types of keys, each of which is associated with different requirements for the three color specifications, c_L, c_M, c_R , referred to as left, middle, and right colors respectively. For a key, k_i , its left color (c_L) is used to interpret the colors in the color band on the left (B_i), and its right color (c_R) is for the color band on the right (B_{i+1}). We will discuss the middle color (c_M) in Section 4.4. Together with the illustration in Fig. 4, the five types are defined as follows.

- **nil key:** $c_L = c_M = c_R = \text{nil}$. This key (k_i) implies that the color at the corresponding transition point x_i is undefined. It relies on the specification of either k_{i-1} or k_{i+1} . This type of key is only allowed to be defined at $x_0 = x_{\min}$.
- **right key:** $c_L = \text{nil}$ is undefined while $c_R = c_M$ is defined. This key is also only allowed at $x_0 = x_{\min}$.
- **left key:** c_L is defined but $c_R = \text{nil}$ is undefined. c_M must be assigned to c_L or the nil state of c_R . This key cannot be used at $x_0 = x_{\min}$, but can be used for any other key $k_i, i = 1, 2, \dots, n$.
- **dual key:** $c_L = c_M = c_R$ are defined as the same color. This key cannot be used at $x_0 = x_{\min}$ or $x_n = x_{\max}$.
- **twin key:** c_L and c_R are defined separately, and have to be different colors ($c_R \neq c_L$). c_M must be assigned to one of the two colors, i.e., either $c_M = c_L$ or $c_M = c_R$. This key cannot be used at $x_0 = x_{\min}$ or $x_n = x_{\max}$.

The asymmetry of the left and right keys is because of the need to avoid the situation where a color band is defined by two nil colors, i.e., when a nil color of a left key k_i is followed by that of a right key k_{i+1} . Using a combination of these five types of keys, we can define a CMS with the following types of color bands and transition points:

- **Constant Band:** All colors within a band are of the same color. Given a band B_i with two keys k_{i-1} and k_i , the band (B_i) is a constant band if (i) $c_{R,i-1} = c_{L,i}$; or (ii) $c_{R,i-1} = \text{nil}, c_{L,i} \neq \text{nil}$.

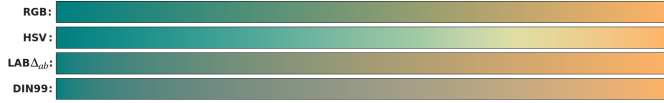


Fig. 5: The image shows the interpolation between two colors in different color spaces. We can observe their visual differences.

- **Scaled Band:** The colors within the band are interpolated between two different colors $c_{R,i-1}$ and $c_{L,i}$. A band (B_i) is a scaled band if and only if $c_{R,i-1} \neq \text{nil}$, $c_{L,i} \neq \text{nil}$, and $c_{R,i-1} \neq c_{L,i}$.
- **Continuous Transition:** The color at an intermediate key ($k_i, i \neq 0, i \neq n$) is smoothly interpolated in both left and right directions. A key (k_i) is a continuous transition point if k_i is a dual key.
- **Discontinuous Transition:** The color at an intermediate key ($k_i, i \neq 0, i \neq n$) is discontinuous in either left or right direction. A key (k_i) is a discontinuous transition point if (i) k_i is a twin key, or (ii) k_i is a left key and $c_{L,i+1} \neq c_{L,i}$.

It is necessary to note that the widths of color bands do not need to be the same. They can be stretched by setting the values of x_i at a non-uniform pace. As shown in Fig. 4, the flexibility of this scheme allows users to define a CMS composed of different types of color bands and different transitions. Before 2017, NASA used a multi-band colormap with continuous transitions for showing temperatures of hurricanes. When Hurricane Irma struck Caribbean islands, NASA introduced two new color bands with discrete transition points for the range [170-189] Kelvin (Fig. 4(e)). Our scheme can easily address such needs.

4.2 Color Spaces

For any CMS with scaled color bands, the corresponding colormap may appear differently depending on the color space used for interpolation. Fig. 5 shows four different interpolations between a cyan color ($\text{RGB}_{[0,1]} : 0, .5, .5$) and an orange color ($\text{RGB}_{[0,1]} : 1, .7, .4$) using the RGB space, HSV space, CIELAB with CIEDE2000, and DIN99.

The CCC-Tool allows to define each color using one of the four spaces, namely RGB, HSV, CIELAB, and DIN99. Given two colors in RGB space (or HSV), the CCC-Tool uses linear interpolation to define the color transformation within the color band. For the CIELAB space, there are several ways to measure the color difference between two colors, including Euclidean distance (ΔE_{ab}), CIE94 (ΔE_{94}), and CIEDE2000 (ΔE_{00}), representing the progressive improvement of the perceptual uniformity of the difference metrics. The CCC-Tool supports all three metrics.

DIN99 relates closely to CIELAB and it provides a transformation from (L, a, b) to (L_{99}, a_{99}, b_{99}) so that the color differences can be computed in a Euclidean distance metric. The difference measures using DIN99 are perceptually more uniform than those using CIE94 and are comparable to those using CIEDE2000 [73], [74]. Because of the transformation, given two colors in the DIN99 space, the CCC-Tool also uses linear interpolation. In this work, we leave the decision about the color space to users, while we provide users with utilities to analyze and compare CMS using different color spaces.

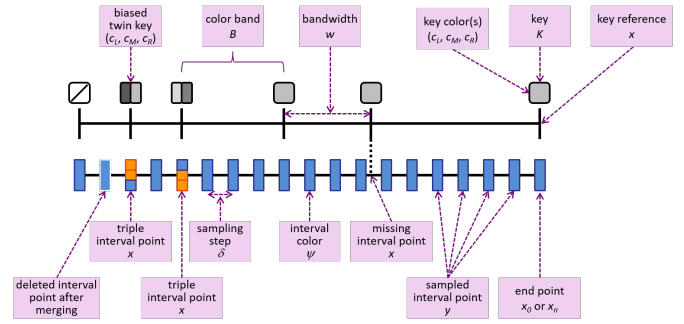


Fig. 6: The merge of the reference points in a CMS and a set of regularly sampled intervals to create a final set of intervals for a colormap.

4.3 CMS to Colormap Conversion

As we mentioned before, a colormap is traditionally stored as an array of interval points, $[z_\tau, c_\tau]$, $\tau = 0, 1, \dots, \eta$, where z_τ is a reference value in the data range, c_τ is a color, and η is the number of intervals. In general, most application software uses such a colormap as a look-up table. Given a value v in the data, the software first searches for two consecutive cells in the array such that $z_\tau \leq v \leq z_{\tau+1}$. The software may determine the color of v by selecting the nearest cell, in other words, c_τ if $|z_\tau - v| \leq |v - z_{\tau+1}|$, and $c_{\tau+1}$ otherwise. Alternatively, the software may interpolate the color linearly between the two cells based on $z_\tau, v, z_{\tau+1}$.

Most applications do not directly support less common color spaces such as CIELAB or DIN99, or non-Euclidean difference metrics. In order to support such applications, CCC-Tool allows exporting a CMS to a conventional colormap in the form of an array of sampled colors. The CCC-Tool export function allows the user to choose a color space (RGB, HSV, CIELAB, or DIN99) for the interpolation and a possibly deviating color space for the “color-annotation” within the generated file. Colormaps can be exported as XML, JASON, or CSV.

One may uniformly sample the data range $[x_{min}, x_{max}]$ to determine the reference values z_τ in each cell of the colormap. For example, one may start with $y_0 = x_{min}$, and add more interval points with a uniform step δ as $y_{j+1} = y_j + \delta$, until reaching y_m such that $y_m + \delta > x_{max}$. However, this is not adequate enough. As illustrated in Fig. 6, some reference values of the keys in the CMS, $x_i, i = 0, 1, 2, \dots, x_n$ may not coincide with the sample points. In order to prevent a possible loss of key information, we thus need to merge the two sets of reference values $\{x_0, x_1, \dots, x_n\}$ and $\{y_0, y_1, \dots, y_m\}$ into the z_0, z_1, \dots, z_η . The merge also ensures that $z_\eta = x_{max}$. During the merging, we search for interval points within of constant bands. Such interval points can be rejected, because the joined key information is sufficient to describe constant bands. Additional interval points at the positions of discontinuous transition points have to be complemented by the triple color information of twin and left keys. In contrast to data related sampling (e.g., histogram-based sampling), the use of uniform sampling is rather suitable for colormaps designed as a standard mapping function required for routine observations, comparison between datasets, and many data sharing, collaborative, and disseminative activities.

4.4 The Function of Middle Color c_M in Keys

Whenever applying a colormap with discontinuous transitions to a continuous data range, there is a common issue of consistency. As each discontinuous transition point x is associated with two different colors, their interpolation is inevitably ambiguous. In traditional colormaps, this issue is usually addressed by having two overlapping sample colors. For example, consider the following four color cells, A , B_L , B_R , and C , in a colormap: $\dots, A : [z_{j-1}, c_{j-1}]$, $B_L : [z_j, c_j]$, $B_R : [z_{j+1}, c_{j+1}]$, $C : [z_{j+2}, c_{j+2}]$, \dots , where B_L and B_R are at the transition point x such that $z_j = z_{j+1} = x$ and $c_j \neq c_{j+1}$ at the transition point.

This approach makes the ambiguity largely unnoticeable. In most application software, mapping the value x involves a search for two interval colors. If the software searches from $j = 0$, it will reach the transition point from the left by finding A and B_L . So the color for x will be c_j . If a user unknowingly interprets c_{j+1} in B_R as x exactly, what is depicted by c_{j+1} is actually associated with $x + \epsilon$ where $\epsilon > 0$ is a small number. Occasionally, especially with a discrete colormap, the problem can be serious as illustrated in Fig. 7.

Fig. 7 shows a simple colormap corresponding to three discrete bands. The colormap is represented by six interval points, A, B_L, B_R, C_L, C_R, D , where B_L and B_R are with the transition point at $x = 2$, and C_L and C_R are with $x = 4$. Given the example dataset, if we search the colormap from the left, we get a cyan-white visualization, and if we search from the right, we get a white-orange visualization. The user may want the first transition point to be cyan and the second to be orange in order to have a cyan-white-orange visualization.

Although this problem is inherently that of conventional colormaps, we have devised a solution to the problem through our CMS scheme. We introduce the middle color c_M in twin keys and left keys. This field can be used to specify the exact color of the transition point. c_M is not really a new color, but a toggle between c_L or c_R . Therefore, the middle of triple information can be easily stored as a boolean attribute without causing trouble at external tools, which can not handle this information.

4.5 Probes

When a small sub-range of the global data range needs to be inspected or highlighted in more detail, *probes* can be defined within the tool and combined with any CMS. In our context, a probe is a sub-range within a continuous colormap that is replaced by or blended with either a uniform color (Constant-Probe), a color gradient (One-Sided-Probe), or a color/transparency gradient (One-Sided-Transparent-Probe). In resulting visualizations, probes (or sets of probes) have the appearance of isoline-like structures of variable width. The width visualizes the spatial data gradient - the larger the width, the smaller the gradient is. Using a gradient shading for probes simplifies the depiction of the local gradient within the global data range.

Within CCC-Tool, a probe is defined in addition to the normal colormap part of the CMS. This allows displaying the data with the “normal” CMS and to overlay the probe

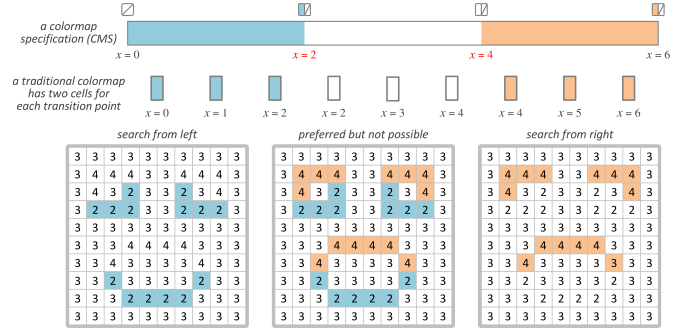


Fig. 7: Illustration of the consistency problem in colormap-mapping. Given a traditional colormap with two discontinuous transition points at $x = 2, 4$. When a conventional colormapming algorithm searches the color table from left, it generates the image on the left. When it searches from right, it generates the image on the right. It would not be possible to generate the middle image. The middle color c_M in our CMS addresses this issue.

on request. However, since the colormap definitions of visualization systems so far don't support directly using a CMS that include separate probe definitions, two colormaps need to be exported, the original CMS and the original CMS combined with the probe(s). Both can then be imported and used within visualization tools such as ParaView. For interactive probing, the probe feature and means to change the probe settings interactively would have to be implemented directly in the visualization systems used. Since the computation of isolines in addition to colormapming increases the computational costs, the use of probes via colormapming could be advantageous especially for interactive inspection of very large data sets.

All probes are defined by a starting value S , an ending value E and a probe-type. For the probe-types One-Sided and One-Sided-Transparent, the definition also includes the function $f_p(x, c)$ where x is a data value within the probe. The function defines a process (0 to 100 or 100 to 0) of saturation or lightness by linear interpolation between S and E . Furthermore the probe definition of Constant- and One-Sided-Probes includes a color C_p . Adding a Constant-Probe to a CMS requires the update of keys or an extension of new ones to get a left-key at S and twin-key with $c_L = C_p$ at E . The creation of a One-Sided-Probe needs a twin-key with $c_R = f_p(S, C_p)$ at S and a twin-key with $c_L = f_p(S, C_E)$ at E . One-Sided-Transparent-Probes are determined according to the same method of the One-Sided-Probe, except that the algorithm uses the CMS-colors C_S at S and C_E at E instead of C_p . The colors of CMS-keys, located between S and E , have to be updated with $f_p(x, c)$. With the monotone decreasing or increasing of lightness or saturation, the two One-Sided probe types form an ideal basis to inspect the range of the probe. It is easy to include such probes through the twin key of the CMS with a hard discontinuous transition of lightness to create the impression of an isoline-like-structure (see Fig. 8).

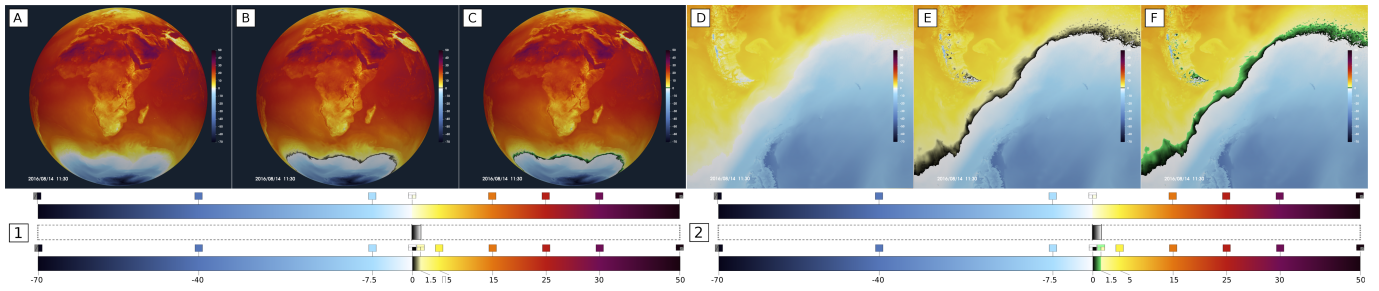


Fig. 8: At the example of the 2m-temperature of a high resolution simulation with the global atmosphere model ICON, the figure illustrates the use of probes to inspect small sub-ranges of the global data range. The rendering on the left (A) shows the the global temperature distribution with color-mapping using a CMS (inset 1, top) that was designed to resolve the data range from -70 to 50°C. However, within small sub-regions, as shown in a close-up (D), only a small section of the CMS is used and local structures are hardly visible. In order to probe the temperature range 0 - 1.5°C in more detail, we added single probe at 0°C to compose a CMS (1, bottom) that creates an isoline-like-structure to highlight the freezing point and the data range above. The images (B) and (E) show the result for a One-Sided-Transparent-Probe. The according colormap composition is shown in inset (1). Similarly, (C) and (F) show the according renderings for One-Sided-Probe according to the definition shown in inset (2, middle). (1: Top: Divergent CMS for the 2m-temperature. Middle: one sided transparent probe for the range 0 - 1.5°C. Bottom: resulting colormap. 2: One sided probe without transparency.)

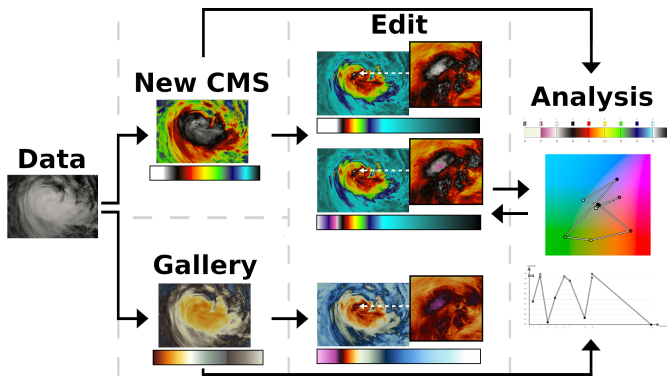


Fig. 9: A typical workflow for creating a colormap specification (CMS) using the CCC-Tool. The example dataset illustrates steps that may be used to recreate the colormap used by NASA to visualize hurricane data (courtesy of William Straka III). A user may use the Gallery to choose from a built-in colormap, or the New to create more complex or application-specific CMS.

5 CMS CONSTRUCTION

The introduction of a colormap specification (CMS) allows users to create and edit colormaps, and do retrospective amendments with a minimum number of key colors. The following paragraphs explain the methods for creation and editing of CMS used by CCC-Tool.

5.1 Creating and Editing a CMS

Fig. 9 shows the typical workflow of using the CCC-Tool. We offer a collection of CMS and a user can use them as initial CMS or directly for the export. Most of these were imported from ColorMoves [11], which were designed to provide discriminatory power within specific hue ranges and hue combinations. Alternatively, a user can start with an empty CMS. The following create/edit methods are independent, whichever way of beginning the user chooses.

Many users will likely use the CCC-Tool to create a CMS in order to meet the requirements of specific applications.

Here we use the colormap created by NASA for displaying hurricane datasets as an example. For a fast and easy compilation of a CMS, we implement sets of predefined CMS for the main edit/creation mechanism of our tool (see Fig. 2). The elements of these sets are drag-able and can be dropped between the key defined bands of the user's CMS. To ensure the condition of a good overview over the whole CMS during the creation/edit process, we decided to display the CMS on one hand as a corresponding linear plot and on the other hand as Band Sketch, where all bands have equal lengths. In many cases, the user may wish to introduce new bands or remove existing bands. Like at our example, the hurricane Irma (August/September 2017) exhibited unexpected strength. The very low temperature area of the data cannot be observed easily. As reported in the news at that time, scientists combined two new bands together with two discontinuous transition points as shown in the second CMS of the Edit-column (Fig. 9). Although the data used here is not that of Irma, we can still see the pink patch with temperature below 189 Kelvin, which is more difficult to see this using the CMS at the top. The discontinuous transition point between white and pink ensures that any data values just below 189 Kelvin will “pop out”, rather than smoothly changing from white to pink. With the drag and drop method of predefined CMS from the Structure-Window we created a process, where the user can easily handle such a situation.

Next to this technique, we also implement Key Edit and Path Plot offered at the Edit-Window, where the user can modify each key, including all its attributes, i.e., $k := (type, x, c_L, c_M, c_R)$. While the first method is a perfect beginning to create a new CMS, modification of keys is only practicable for a non-empty CMS.

Modifying the *type* of a key allows the user to change the continuity of the corresponding transition point and the appearance of the two neighboring color bands. Modifying the reference value x allows the user to change the width of the neighboring bands. Modifying the colors c_L, c_M, c_R allows the user to refine detailed color specification to encode application-specific semantics such as color symbolism. In

Fig. 9, the top two CMS in the `Edit`-column show more hurricane-related semantics by modified reference points and key colors. As the lower temperature values typically correspond to stronger part of the hurricane, narrower and more-attentive colors were used at the low-temperature side of the CMS.

Back to the hurricane example, we created an alternative CMS using the `Gallery`-starting-point as shown at the bottom of Fig. 9. In general, the CMS captures most features of the NASA colormap, but the missing of discontinuous transitions makes the observation of critical values hard. With the drag and drop technique, the solution to this problem would be a replacement of the band with a new one. The `Key Edit` offers the more intuitive solution of adding a discontinuous transition point by changing the key type.

In addition, to edit the CMS, we implement an interactive variant of the path plot (see Section 6.2), we called `Path Plot`, to modify the colors of the keys. Such a plot allows the user to manipulate the CMS with respect to a chosen color space. For example, a user may start with a plot in the HSV space as it aligns well with humans' intuitive descriptions about colors. A CMS is shown as a path in HSV and the user can adjust a node on the path by moving it to a location of the desired hue, saturation, and value. Once the user has determined the nodes (i.e., keys) on the path, the user can use the CIELAB space to create a perceptually more uniform CMS.

5.2 General Methodology for Constructing a CMS

Constructing a CMS requires the user to make a series of decisions: (a) how many color bands are needed within the CMS? (b) Are any bands or transition points of specific importance? (c) Does a domain-specific convention, such as color symbolism, exist? Some colormaps are created to assist in solving a specific problem in a specific dataset while others are steps towards a widely used CMS. Below we outline some general guidelines for using the CCC-Tool.

Key and Band Colors. Hue selection can be used to direct attention, define high-level categories of data values, and assign domain-specific semantics (e.g., red for risk) [15], [75]. In order to accomplish this, it is important to budget saturated hues and types of contrast. Allocating saturated and de-saturated hues as well as types of contrast enables the creation of organized visual hierarchy while minimizing distracting contrast [76]. Think of hues as having auditory volume. Fully saturated red is very loud, burnt orange is a mid-volume and tan is low volume. Assign the loudest colors to the most important data range and the quietest to ranges important only for context. If the data values are of equal importance, use hues of equal volume. In Fig. 9, the `Gallery` example places all of the saturation in the area of the hurricane. The "Create New" example renders the hurricane in grays and areas outside the hurricane in saturated lime green thus misdirecting attention. At the color wheel, angle is associated with hue, which means that small angle differences correspond to similar colors and colors on the other side with 180° difference correspond to complementary hue (see Fig.14). Related data ranges assigned colors close on the color wheel, such as blue, green,

and yellow, will be intuitively associated. Unrelated ranges rendered complimentary colors such as red and green signal multiple categories [15].

Number, Type, and Widths of Bands. The number of bands typically depends on the domain-specific semantics associated with the data (e.g., the number of categories). When such semantics are not available, more bands correspond to an increase in discriminatory power. However, too many bands can cause the visualization to become confusing. Constant bands are typically used for easy and quick identification of specific values within the data, while scaled bands enable the observation of more detailed patterns of variations in the data. The multiple bands with consistent widths and monotonic change of brightness within each band allow for more accurate observation of the gradient of the changes in the data. Varying widths allow users to observe important range of the data with more narrow bands, while "spending" less colors on less important data ranges.

Domain Convention. Encoding domain-specific semantics enables easy understanding and remembering of a colormap, and facilitates rapid observation and effective communication. Color symbolism is a powerful mechanism (e.g., red for hot or risk). The uses of discontinuous transitions need to be carefully managed. Colormap legends are essential for minimizing misinterpretation.

6 VISUAL ANALYSIS OF CMSs

The current version of the CCC-Tool offers six different visualization methods to analyze a colormap. These analysis plots provide information about interpolation, conditions between color spaces, uniformity, and order. Except for the key speed plot, all analysis plots use information of the interval colors. Fig. 11 shows an example using the speed (6.3) and the order (6.4) to improve a colormap.

6.1 Interpolation Space

For any CMS with scaled color bands, the corresponding colormap may appear differently depending on the color space used for interpolation. The `Interpolation Space` plot informs the user about possible visual differences. The example of Fig. 5 displays four interpolations between a cyan color and an orange color using uniform interpolation in the colorspace RGB, HSV, CIELAB, and DIN99.

6.2 Charting the Path of a Colormap

The `Path Plot` contains information about the key color positions and interval color positions. Likewise, the colormap path in one color space is indicated by an interpolation in another color space. The plot uses combinations of 2D and 3D visualizations. For the HSV-, LAB- and DIN99-path-plots variant, we implemented a plot showing the top view of the colormap path and the colorspace. Furthermore, we produced three plots: one for each component of a color. Their main task is to visualize the path of the colors for each of the components separately. In the case of the RGB path plot, all color components include hue and saturation. Therefore, we use a combination of three 2D plots projected

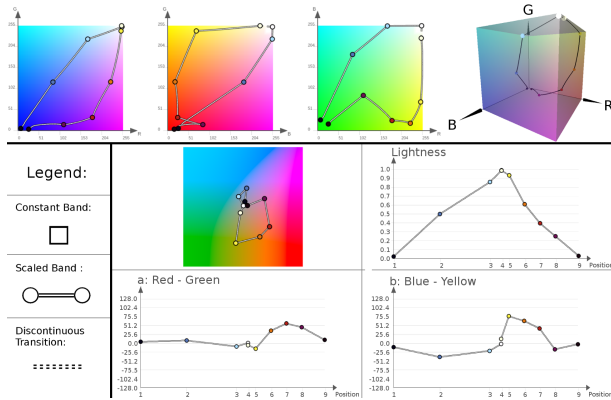


Fig. 10: This image shows two out of four variants of the colormap path plot. The upper one shows the RGB path plot and the bottom example the Lab path plot. Both plots show the CMS from Fig. 8 using the Lab Colorspace for interpolation.

along the axes, and a 3D rendering of colormap path and the space. Fig. 10 shows an example for a colormap path interpolated and visualized in RGB and a second example interpolated in LAB space and visualized in the HSV space. Every scaled band of a CMS is represented in the colormap path by a solid curve and one circle at each line end. The positions and the coloring of the circles are defined by the key colors which delineate the band. The solid lines are constructed with straight lines connecting each color position with the next one including the interval colors which are located between the two key colors. These solid lines form a straight line, if the interpolation space and the analyzed space are the same. If this is not the case, the solid lines result in a curve. Constant bands are illustrated as a single colored rectangle in the top view and RGB plots, and with two rectangles connected with a horizontal solid line in the line plots. Discontinuous transition points are indicated by dashed lines. For the identification of discontinuous transition points, the algorithm has to find twin-keys or left keys with $x_i \neq x_{max}$.

With the path plot, users can envision how the colormap passes through a color space and can identify critical parts like closely located colormap segments or intersections. The management of color components is also helpful for the evaluation like lightness, saturation and hue. The second example of Fig. 10 shows, how we used the plot to create a divergent CMS with a nearly monotonous increase of the lightness till the key at reference value 0°C and a following decrease of the lightness.

6.3 Speed Plots

For the analysis of perceptual uniformity, we implement the global and local speed plots according to Bujack et al. [10]. For colormaps with discontinuous points, we use the color of the maximum value for the global speed plot and omit to draw a bar at the local speed plot. Massive speed difference within the colormap leads to indistinguishable coloring of the remaining value ranges. For a better visualization in such cases, we implement a logarithmic mapping next to the linear color mapping. Alternatively, it is possible to focus these plots on a user specified key range. We use alternating

dark and light squares for the background to prevent any region to fade into a single background color. It can be difficult to visually analyze the speed between keys in the global plot. Therefore we also offer additional key speed plots. These figures show a stacked bar graph for the speed from one key to the next one.

6.4 Visualizing the Order of Colors

To analyze the order of colors, we build on the work of Bujack et al. [10], [77]. They evaluate intrinsic order depending on the mutual perceived distances between the colors. We merge the two matrix plots that they use into one newly designed plot (Fig. 11). We draw the negative local order values, which violate order, in red and the positive ones, which follow order, in blue local order values above the colormap. The visualization of the global order shows only the interesting negative values. For each interval of colors c_i and c_j , we calculate the minimal order value of the colors c_k with $i < k < j$. In case of a negative value, we draw an arc from the position of c_i to c_j colored in c_k . The maximal distance from the arc to the colormap shows how severely the intrinsic order is violated.

7 APPLICATION CASES OF CCC-TOOL

The two application case studies presented here illustrate the practical use of CCC-Tool for application specific colormap design and analysis.

7.1 Color Mapping of 3D Ocean Temperature Data

In climate sciences, 3d data representing the Earth system's compartments such as the atmosphere or the ocean are regularly analyzed. Due to different climatic conditions in different geographic regions, the data can, depending on the quantity chosen, span a wide range of values. As an example we use, as shown in Fig. 12, temperature data of a regional ocean model simulation covering the South Atlantic west of Africa as described in [78]. The Benguela Upwelling System, one of the major coastal upwelling systems [79], [80], [81], transports cold (and nutrient rich) water from greater depths to the surface near the coast of Namibia. Due to their importance to marine life and fishery, gaining a better understanding of upwelling systems is a very active research field. The water temperature patterns at the sea surface reflect an important part of the dynamic 3d flow of the upwelling system, and, more specifically, mixing processes of water masses of different origins. Since the sea surface temperature can also be observed from satellites, it is furthermore well suited for comparisons between simulations and ground truth.

Our goal here is to design a color palette and a mapping between color and temperature that efficiently emphasizes the relevant structures in the sea surface temperature (SST), but that, at the same time, reasonably resolves the temperature variations found at greater depths. For appropriate visualization of these features with a combination of vertical and horizontal slices (2D) using one joint colormap, we define the following requirements:

- 1) Global data range to be represented: $(0-30^\circ\text{C})$

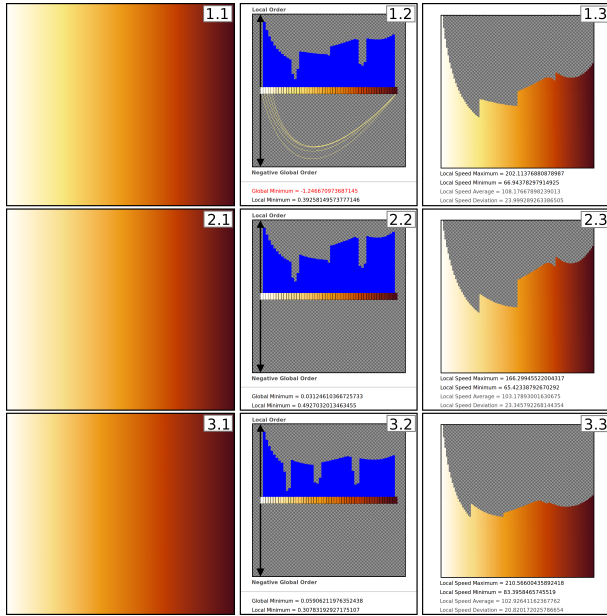


Fig. 11: Illustration of the process of improving an existing colormap. As an example, we chose a variation of the heated body colormap. It is the third from the top in the category “Yellow Orange” in the Gallery of the CCC. The improved colormap suffices intrinsic order w.r.t. ΔE_{2000} , it has a higher minimal discriminative power, and appears smoother. (1.1 Original colormap; 1.2 Order plot of original colormap shows that the CIELAB ΔE_{2000} observer would not be able to order yellow correctly between the bright part and the brown; 1.3 Speed plot of original colormap shows a drop in speed around yellow down to 67; 2.1 Colormap changed to make the yellow less brilliant; 2.2 Order plot shows that the changed colormap suffices global order everywhere; 2.3 Speed plot of changed colormap still shows a drop in speed around yellow down to 65; 3.1 Colormap changed to increase minimal speed; 3.2 Order is not affected by rearranging the locations of the keys; 3.3 Speed plot shows that the minimal speed was raised to 84, which increases uniformity.)

- 2) The sector of the color map representing the sea surface temperature ($13-30^{\circ}\text{C}$) requires as many discriminable colors as possible to visualize the complex horizontal flow patterns also represented by SST variations.
- 3) Slight temperature variations in the Benguela Upwelling System (the dark green area east of Namibia shown in Fig. 12A, cf. [78]) need to be resolved in particular.
- 4) The remaining sector of the color map ($0-13^{\circ}\text{C}$) mainly represents the range of temperatures found at greater depths.
- 5) The colors used in the color map should be linearly ordered and follow best practices used by domain scientists for representing temperature by color, i.e. warm=red, cold=blue.

To get an overview on the data first, we combine several color mapped slices through the 3D model domain using different standard colormaps (Fig. 12 B,C,D) and analyze the features that we observe. First, we look at the horizontal

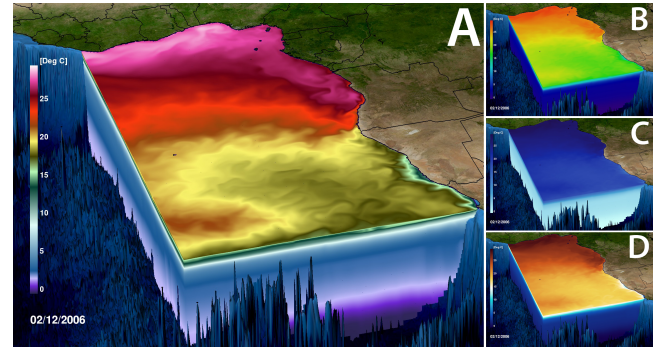


Fig. 12: The visualization of the temperature field of vertical and horizontal slices of a 3d regional ocean model is a good example of the use of multiple color/brightness bands with strong local color and luminance gradients. Note the exaggeration in the vertical scaling to show details in the vertical cross section (A). Compare the complex application colormap with common colormaps: rainbow (B), lightblue to darkblue (C) and blue-white-red (D).

SST patterns at a given point in time.

Within the domain, we find a strong northward increase from about 13°C in the South-East to 29°C in the North, overlaid by some local variations caused by ocean eddies and currents. Looking at the vertical East-West-section in the foreground, we find horizontal banding in the temperature with a very strong temperature gradient towards the sea surface. The temperature ranges from little above 0°C in the deep ocean to about 17°C at the surface.

With respect to the design of a new colormap optimized for the actual application case, we first visually evaluate the performance of the three standard colormaps used on the right side of Fig. 12 (B,C,D) and, accordingly, the close-ups B,C,D shown in Fig. 13:

B The rainbow colormap resolves many of the SST patterns described above, but the vertical sections show only few variations except for the strong gradient near the surface. The shades of blue representing low temperatures are hardly distinguishable from the blue color used for rendering the bathymetry. Also, some of the SST structures are not sufficiently represented by color gradients due to lacking variations in luminance. The upwelling zone west of Namibia is hard to depict.

C The strong vertical temperature gradient near the surface is the dominant information in the visualization using the simple scaled band colormap (light blue to dark blue). However, it does not resolve any details in the SST; particularly the cold upwelling zone west of Namibia is not visible.

D The symmetric blue-white-red-colormap shows only little of the temperature variations at the sea surface. Also, only little detail is visible at greater depths. The bright center part of the colormap, which is “loud” due to its high luminance contrast, is only visible on the vertical slices denoting the high vertical temperature gradient.

A For the application case we decided to design a colormap using almost the complete possible hue range combined with luminance modulations. The resulting visualization shown in Fig. 12A illustrates the concept: the luminance

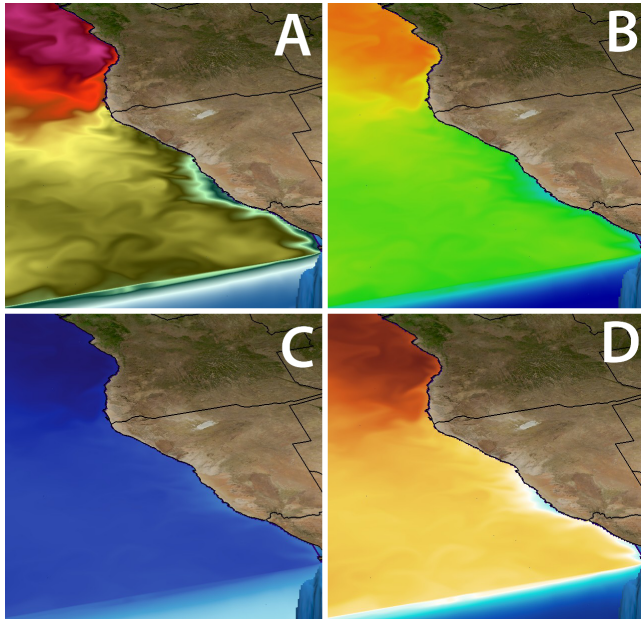


Fig. 13: This image shows close-ups of the visualizations shown in Fig. 12. The enhanced local contrast of the colormap created with CCC-Tool (A) enables the depiction of ocean eddies and filaments, i.e. important representations of the dynamic flow field, while the standard colormaps used for B, C, and D don't resolve these features.

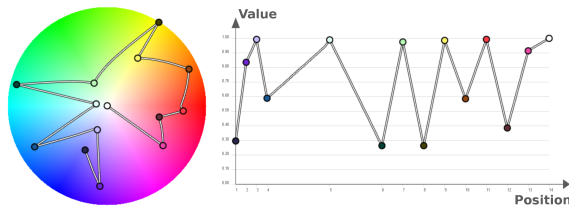


Fig. 14: The HSV-Path Plot analysis (6.2) of the CCC-Tool applied to the ocean temperature color map visualizes the color and luminance variations used in Fig. 12A.

waves (Fig. 14) enhance the local contrast between adjacent temperature subranges. This allows for a detailed visualization of the small scale variations that are related to features in the flow field, and, at the same time, to adequately resolve the full temperature range found in the data. Ranges with strong gradients in the data are represented by quicker changes in the color. The temperature range between 4 and 14°C is coarser resolved because of the strong temperature gradient found vertically.

As a result, the visualization in Figs. 12A/13A allows depicting all relevant details found in the data, specifically the upwelling of cold water off the coast of Namibia (lower right corner) and its further transport and mixing with warmer water masses. The enhanced local contrast of the application-specific colormap created with CCC-Tool enables the depiction of ocean eddies and filaments, i.e. important representations of the dynamic flow field, while the visualizations with the standard colormaps (B,C,D) mostly don't allow to depict these structures.

7.2 Ancient Water Formation

Half of all of the water in the universe predates the sun. Scientists Joseph Smidt, LANL, and Brandon Wiggins, SUU, set out to understand how, where, when and with what frequency this ancient water appears in the early universe. They combined expertise in theoretical astrophysics, molecular chemistry, and high performance computing. Identifying the locations and prevalence of the complex interactions between multiple variables that enable the formation of water is essential as well as closely examining how those variable interact [82]. The team combined a high resolution hydrodynamics simulation of the early universe closely coupled with this hydroxyl and water-producing chemistry model to simulate how water molecules were created and distributed in space and time in the early universe [82].

Answering the scientific questions required tracking, over time, the conditions that give rise to water - dense gas, warm gas temperatures, as well as the presence of oxygen and heavy metals. By examining the densities and distributions of these materials in supernovae explosions, comparative visualization enabled the identification of regions in the ancient universe where water likely formed.

For the simulation, three codes were combined, Enzo, Grackle, and WaterNet, and the results visualized in Paraview. While previous colormaps did little to facilitate the ability to see the relationships between key variables, the CCC-Tool isolated the data ranges within each variable conducive to water formation. Thus the scientists were able to more easily compare multiple variables over time and identify where gas density, temperature, oxygen and heavy metals were co-located within the ranges in which water formation occurs. Specifically, CCC-Tool's ability to apply specific color bands to narrow data ranges within each variable enabled scientists to examine the ensemble visualizations and identifying the locations where multiple variables over time across multiple 2D plots align for potential water formation.

Figure 16 illustrates the clarity provided by highlighting the specific temperature, the "sweet spot" for water formation. While the viridis colormap, left, provides an overview of the temperature distribution, the CCC-Tool colormap, right, clearly identifies the regions scientists need to identify in order to answer their scientific question. Specifically, water most likely forms between 300 - 900 K, (A to B), [82], rendered in a red to yellow color scale. Being such a narrow section of the full data range, 0 to 9800K, applying the CCC created colormap enables quick identification of the "sweet spot" region. Data from 0 to 300K, being cooler is rendered in blue. Above 900K is rendered in a neutral light green, another cool hue, which contrasts with the region of primary importance rendered in the red to yellow warm hues, but is not a focal point due to the low saturation value. The multiple types of contrast applied direct and focus attention to the most important region [83]. The resolution in both examples has been increased by deleting data above 7800 K (C), shown in gray, as it is not a range visible here.

As Figure 15 demonstrates, we used the CCC-Tool to assign a different color palette to each variable, enabling us to focus on different regions of interest. We were able to quickly compare visually the qualities of each variable when

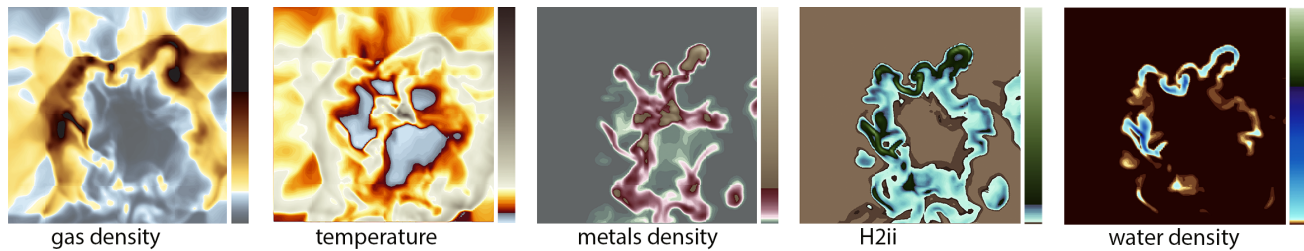


Fig. 15: Scientists examine multiple variables in order to gain an understanding into the locations and quantities where ancient water was likely to have formed. CCC-Tool color bar locations are crafted to highlight the data ranges for each variable that is conducive to water formation, enabling scientists to easily recognize and compare the locations over multiple variables and time steps.

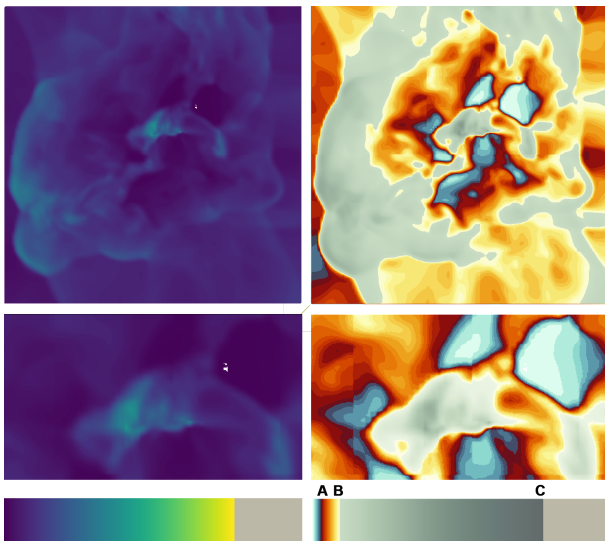


Fig. 16: Water is most likely to form between 300 - 900K [82]. On the left, temperatures between 0 - 7800K are rendered in viridis. On the right, the CCC created colormap renders the range: too cool for water formation, 0 - 300K in blue; the temperature range most likely to form water (A to B) in a red to yellow; the muted green color scale (B to C) recedes in comparison to the saturated warm hues of the sweet spot. The solid gray, 7800 to 9800K contains no perceptable data.

conditions aligned to form water.

Focused visualizations proved to be critical here because they not only illuminated critical co-located conditions, but also enable crucial verification and validation throughout the lengthy and complicated coding process. Specifically, the visualizations provided the means for the results to be verified throughout the process of writing and testing code. In adding the molecular chemistry to Enzo, it is essential to ensure that the chemistry is integrating properly into the code. By comparing visualizations with and without the molecular chemistry, scientists could observe how the chemistry was affecting the behavior of the code. CCC-Tool enabled scientists to compare simulations at an increased level of detail within the regions of importance enabling checks that the chemistry is integrating properly with the code and that each aligns with theoretical understanding.

8 DISCUSSIONS

From various examples mentioned in the previous sections, such as the NASA colormap used for visualizing Hurricane

Irma data (Figs. 1, 4, and 9), visualization of the atmospheric simulation results of ICON (Fig. 8), and the case studies in Section 7 (Figs. 12, 15, and 16), one can observe the usefulness of the CCC-Tool and its complex, user-defined CMS. These CMS suggest the need for further theoretical and empirical researches in order to understand how they perform on different visualization tasks.

On the one hand, such user-defined CMS typically feature positive criteria supported by existing empirical studies in the literature. For example, (a) the benefit of using multiple hue-based bands was confirmed by several studies [11], [56], [69], [84]. (b) Allowing users to define the ordering of colors and bands that is semantically meaningful to application adheres the design guideline suggested by many [15], [50], [71], [85], [86], [87].

On the other hand, allowing users to create their CMS may lead to violations of such design guidelines discussed in Section 2. For example, (c) it is very difficult for a multi-band CMS to maintain the overall uniformity across different bands when mapping data values to color values. (d) It is also common for users to intentionally or unintentionally design a CMS, in which different bands have different discriminative power across different bands. (e) Perhaps one may have a serious concern about the introduction of discontinuous transition points, spoiling the smoothness property of a continuous colormap.

It is common for a discourse on designing colormaps to assume a scenario where a user performs a visualization task without much a priori knowledge about the data being depicted or the semantics of the colormap being used. In such a scenario, when a user sees a similar level of difference in different parts of a colormap (e.g., in the blue and yellow bands), the user would perceive that the underlying data has a similar level of difference in values. Hence non-uniformity or different discriminative power in different parts would cause perceptual errors. However, in many practical scenarios, the users do have a priori knowledge about the data and colormap. It would be unwise to presume that the NASA meteorologists would have made a mistake to have a much wider cyan band between 225-330K (Fig. 1).

Similarly, if users are aware of discontinuous transition points in a colormap, it would be unwise to presume that the users would still interpret a corresponding discrete visual pattern in the visualization as a discontinuous phenomenon in the depicted data. If such a presumption were generally correct, one had to presume that the users would interpret

the data depicted by a black-white contour plot as discontinuous.

Chen and Golan proposed an information-theoretic metric for measuring the cost-benefit of visualization processes [88]. This metric can be used to explain the visualization process involving the users' *a priori* knowledge. Let F_C be a process of colormapping with a continuous colormap C , and F_P be a cognitive process for perceiving a color in a visualization. Viewing a data value $v_{x,y}$ at position (x, y) through a colormapped pixel $c_{x,y}$ is thus a composite process $F_P(c_{x,y}) = F_P(F_C(v_{x,y}))$. Because of the limited bandwidth in colormapping and color perception, there is a huge amount of information loss. In [88], Chen and Golan theorized that such information loss brings about some positive benefit, such as reducing the cost for viewing the data and for succeeding processes, e.g., detecting critical changes or unusual patterns. Meanwhile the positive benefit is to be subtracted by the potential distortion in the reversing process for transforming the perceived color to the data value $v_{x,y}$. The more knowledge the user has about the dataset and about the colormap C , the less potential distortion will be in the reversing process, hence the more the overall benefit.

Recently, Schloss et al. reported an empirical study for comparing sequential colormaps where the color ordering was consistent or inconsistent with some common-sense knowledge [89]. They showed that participants could perform visualization tasks faster using consistently ordered colormaps. In the context of colormapping, this is the first study that evidenced Chen and Golan's theory. Combining these two pieces of work, one may naturally develop a further hypothesis that users' knowledge about the data and the colormap in a visualization can alleviate the disadvantages that might be caused by a colormap that is not so uniformly designed, has less discriminative power in some bands, or feature discontinuous transitions between some bands.

In 2019 when this work was under review, Quinan et al. reported an empirical study for measuring how participants perceived in different continuous colormaps [90]. Their results showed that the perception of implicit discretization (e.g., the separation between yellow and green) varied noticeably among participants. They concluded that "we currently have an insufficient understanding of the mechanisms that drive this phenomenon and no method for modeling or predicting the banding." This study naturally leads to a hypothesis that if a colormap features explicitly-defined discontinuous transition points between different bands, users should be able to perceive the "discretization" consistently. Meanwhile, they should still be able to interpret the discrete patterns caused by discontinuous transition between two consecutive color bands as continuous patterns if they know that the data being visualized are of a continuous nature and there is a very low probability for unexpected discretization to occur along discontinuous transition points.

Of course, these hypotheses will need to be tested in purposely designed empirical studies in the future.

9 CONCLUSION

The new web-based CCC-Tool supports users in creating continuous colormaps by introducing a new colormap specification model, the CMS (4). Here, key colors and reference points can be specifically optimized with respect to semantic and/or physical characteristics of a target application in order to enable identification, highlighting, and isolation of specific focal areas in the data. By reducing the number of color keys to a minimum and automatic interpolation between colors, which is possible for different color spaces, complex colormap structures can be defined without having to manage the large number of color keys that would usually be required for conventional colormaps. With this new CMS, the CCC-Tool allows users quickly to create, edit, import, and export complex colormaps. The introduction of a middle color for discontinuous key types in the CMS allows set color keys at the according physical values for discontinuous transitions within continuous colormaps and hence provides a solution to a long-standing consistency problem in colormapping (4.4). Additional evaluation methods (6.1-6.4) in multiple colorspace allow to test the perceptual uniformity and order of colormaps as well as intuitive fine tuning of the contrast levels. The ability to interactively manipulate and evaluate in the process of colormap construction is a capability not found in other colormap construction tools. The implementation supporting multiple colorspace in combination with the interval colors (4.3) enables the user to import, manipulate and export colormaps in either RGB or HSV color space as well as to use also the interpolation information of perceptually uniform colorspace.

The design decisions were influenced by collaborations with domain scientists doing application oriented case studies. Inexperienced users were faced with the problem to find favourable colors in the commonly used procedure of placing colors in a colormap. Therefore, we decided to implement a drag and drop method for predefined maps composed by experts. One desired feature was highlighting specific ranges, extrema, or outliers with selected colors. This is implemented via the constant bands in the CMS. The modification of a colormap via the Path Plot is advantageous to exploit the characteristics of the different color spaces as a whole. We extended the plots with line plots of the individual components (e.g. saturation and hue for HSV) for a straightforward manipulation. As the functionality of our tool continues to grow, the number of opportunities overstrained non-expert users. We counteract this problem with a new design of the Edit-Section, where less often needed functionality can be hidden (Fig. 2). Overall the scientists confirmed the impact and relevance of the opportunity to create application specified colormaps.

9.1 Future Work

The CCC-Tool is still under development, and as such, will require further additions and improvements. To support an application-oriented colormap design process, the tool includes the capability to provide a color mapped visualization of vtk data (ASCII; Structured or Rectilinear) as preview. This feature is an early version and has to be fully

developed and be stocked with built-in datasets and test-functions. For the import of externally produced colormaps with potentially hundreds of color keys (that presumably resulted from linear color interpolation), it would be advantageous if the tool could detect the original keys used for the creation of the external colormaps and store only these in the CMS, since colormaps with large number of keys can hardly be edited in a meaningful way. Moreover, we want to add an interpolation algorithm to our tool that will use the metric information of CIEDE94 or CIEDE2000 to enhance the colormap design process for perceptually uniform colormaps [91]. For novice users, we are working on a built-in-guideline for the creation of sequential-, divergent-, and multiband-colormaps based on specific tasks. Another possible extension to support the creation process would be a colormap database including semantic information. With regard to the analysis of colormaps, we would like to support colormap design with respect to color-blindness by introducing CMS renderings with trichromacy, dichromatic, and monochromatic views. Furthermore, we plan to include support for transfer functions. With the additional opacity channel, the development of perceptually uniform colormaps is faced with new challenges and requires further work.

ACKNOWLEDGMENTS

We would like to thank: William Straka III, University of Wisconsin - Madison, Space Science and Engineering Center (SSEC), Cooperative Institute for Meteorological Satellite Studies (CIMSS) for his visualizations and data of hurricane.

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