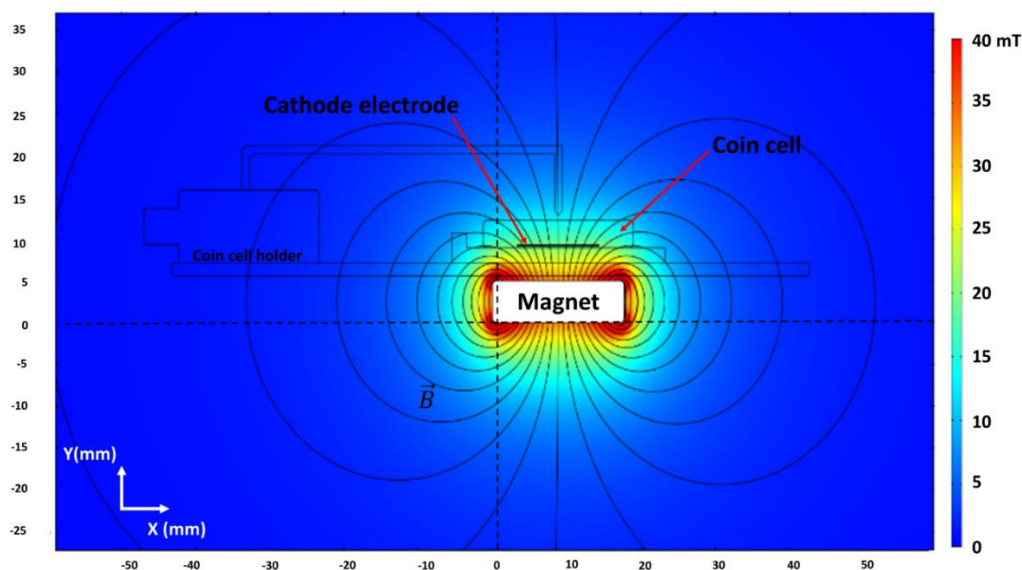
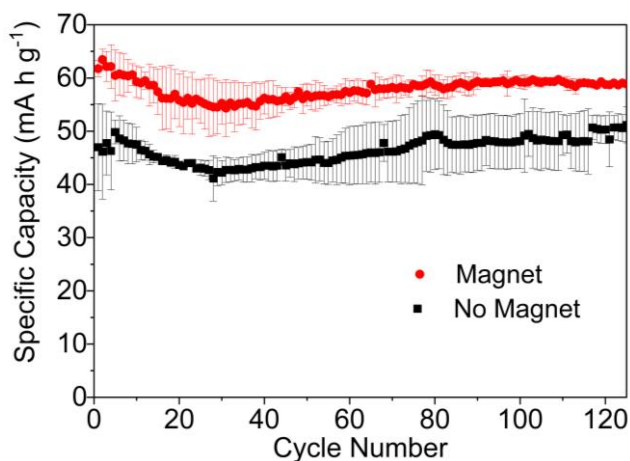


**ESI 1:** COMSOL simulation of the lines of magnetic field generated by the magnet.

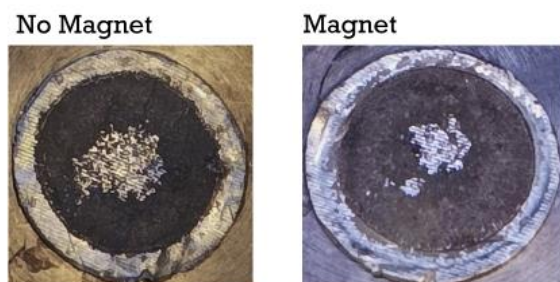


**ESI 2:** Effect of the magnetic field on the cathode and anode.



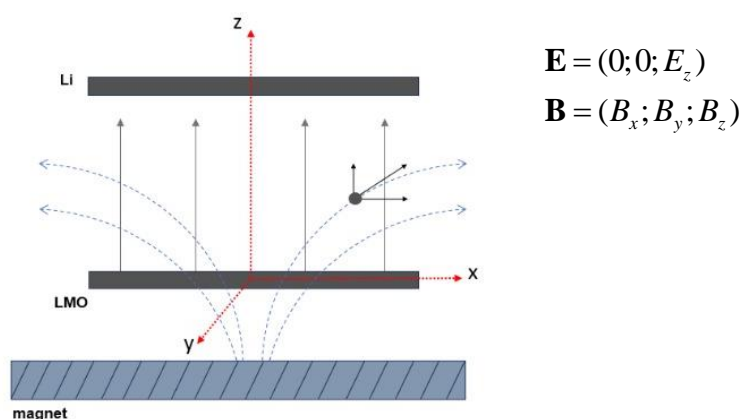
**Figure 1 ESI2:** Point-to-point standard deviation of the capacity of P,Fe-LMO cells cycled at 2C with and without magnetic field (33 mT).

### 500 cycles



**Figure 2 ESI2:** Photography of metallic Li electrodes after 500 cycles with and without the influence of a magnetic field of 33 mT (330 Oe).

**ESI 3: Magnetic and hydrodynamic features.**



**Figure 1 ESI3:** geometry for the simulation

**Table 1 ESI3:** Magnetic susceptibility of the materials used for the simulation at room temperature.

Material	Magnetic Susceptibility at Room Temperature (emu mol <sup>-1</sup> Oe <sup>-1</sup> )	Reference
P-LMO	0.0116	<a href="https://doi.org/10.1016/j.jallcom.2023.172837">https://doi.org/10.1016/j.jallcom.2023.172837</a>
P,Fe-LMO	1.3688	
LiNi <sub>0.5</sub> Mn <sub>0.3</sub> Co <sub>0.2</sub> O <sub>2</sub> (NMC 532)	0.0082	Estimated from its theoretical composition and charge of the transition metals

Figure 1 ESI3, shows the geometry used for the simulation. The magnetic susceptibilities of the different materials used for the simulations can be found in **Table 1 ESI3**. Other parameters used for the simulation are exhibited in **Table 2 ESI3**.

**Table 2 ESI3:** Parameters used for the COMSOL simulations.

Parameters used	Values
Lithium concentration (C <sub>Li+</sub> )	1 mol/L
Ionic Conductivity (σ)	0.957 S/m
Volumetric density of charge (ρ)	9.632 x 10 <sup>7</sup> C/m <sup>3</sup>
Electrode radii (L)	5.5 mm
Current at 2C	1.63 mA
Electrode voltage where the simulation was performed	3.8 V
Anode-Cathode distance	25 μm

From the expression of the magneto-hydrodynamic effect, the current density vector  $\mathbf{J}$  can be obtained as a function of the components of the electric and magnetic fields.

$$\vec{\mathbf{J}} = \sigma \vec{\mathbf{E}} + \frac{\sigma^2}{C_{Li}F} \vec{\mathbf{E}} \times \vec{\mathbf{B}} \quad (1)$$

$$\vec{\mathbf{E}} \times \vec{\mathbf{B}} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & E_z \\ B_x & B_y & B_z \end{vmatrix} = \hat{i}(-E_z B_y) - \hat{j}(-E_z B_x)$$

$$\vec{\mathbf{J}} = \hat{i} \left( -\frac{\sigma^2}{C_{Li}F} E_z B_y \right) + \hat{j} \left( \frac{\sigma^2}{C_{Li}F} E_z B_x \right) + \hat{k}(\sigma E_z) \quad (2)$$

The electric field was considered to be perpendicular to the surface. Its module was calculated at a voltage 3.8 V from the expression ( $E=V/d$ ), where  $d$  is the distance between the anode and the cathode (25  $\mu\text{m}$ ). The current density vector can also be expressed as a function of the speed of the charge carriers according to the classical Drude-Lorentz conduction model:

$$\vec{\mathbf{J}} = \rho \vec{\mathbf{v}} = \rho \left( \frac{dx}{dt}; \frac{dy}{dt}; \frac{dz}{dt} \right)$$

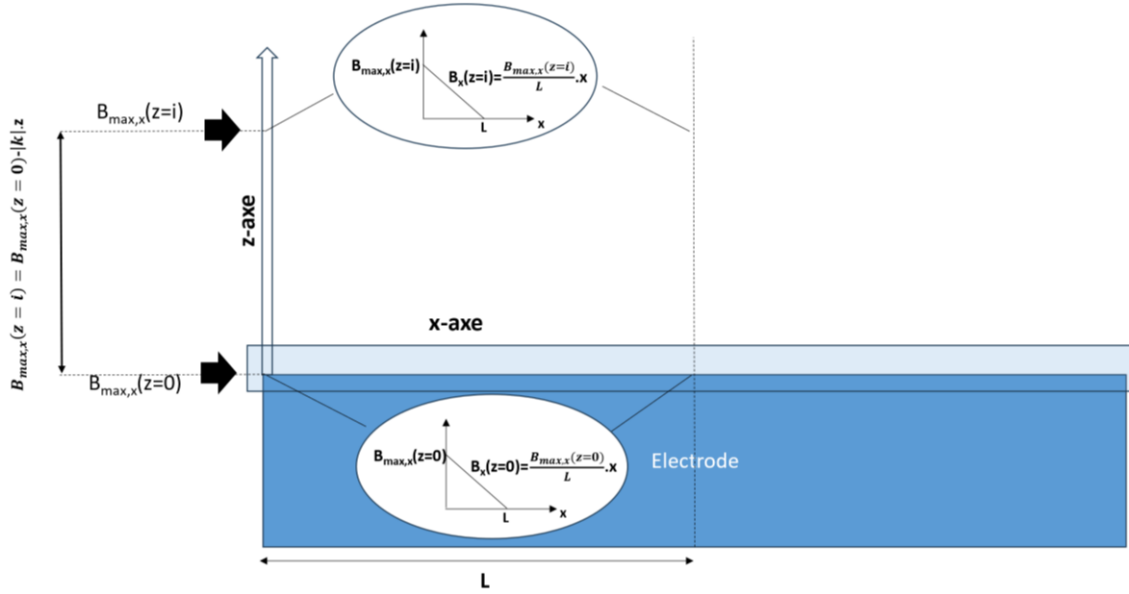
Where  $\rho$  is the volumetric charge density and  $\mathbf{v}$  is the speed of the charge carriers. Transforming to the cylindrical coordinates and taking  $\theta = \omega t$ , we obtain that:

$$\vec{\mathbf{J}} = \hat{i}(-\rho \omega r \sin(\omega t)) + \hat{j}(\rho \omega r \cos(\omega t)) + \hat{k}(\rho z/t) \quad (3)$$

Comparing equations (2) y (3):

$$\begin{aligned} -\frac{\sigma^2}{C_{Li}F} E_z B_y &= -\rho \omega r \sin(\omega t) = -\rho \omega y \\ \frac{\sigma^2}{C_{Li}F} E_z B_x &= \rho \omega r \cos(\omega t) = \rho \omega x \\ \sigma E_z &= \rho z/t \end{aligned} \quad (4)$$

From the results of the simulations in Figure 7 of the manuscript, a linear dependence of the X and Y components of the magnetic field on the distance to the centre of the electrode is assumed, see scheme of **Figure 2 ESI3**.

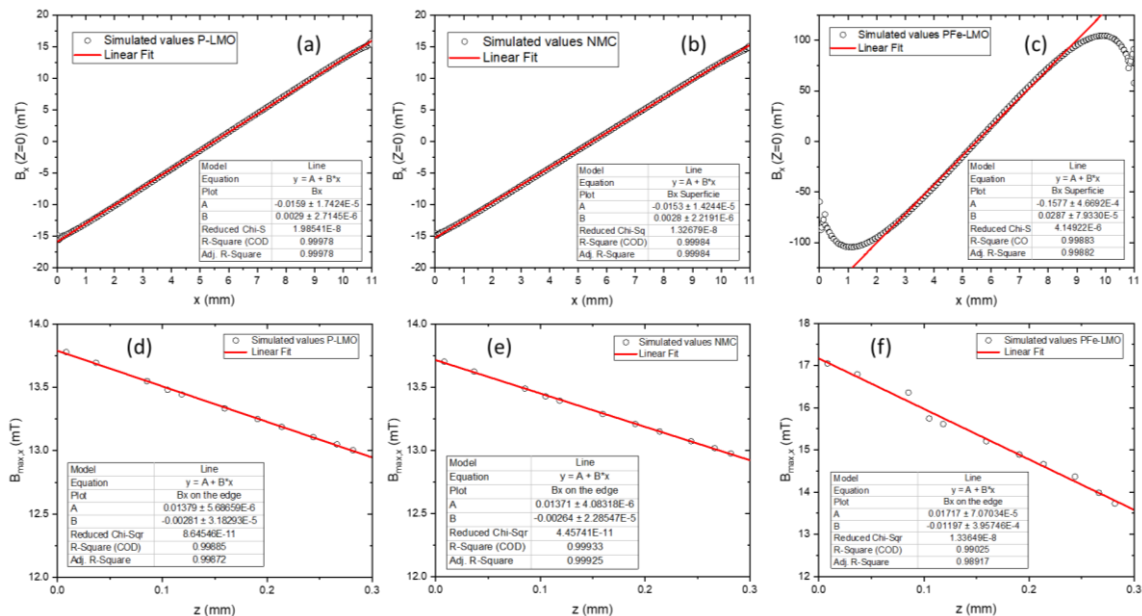


**Figure 2 ES13:** Schematic representation of the assumed mathematical dependencies of the  $B_x$  component of the magnetic field along  $x$  for different heights ( $z$ -axis) above the electrode surface. In the scheme, only  $B_x$  is represented given that because of the symmetry of the system around the  $z$ -axis, the modules of  $B_x$  and  $B_y$  are equals.

$$B_x = \frac{B_{\max,x}(z=i)}{L} x = \frac{B_{\max,x}(z=i)}{L} r \cos(\omega t)$$

$$B_y = \frac{B_{\max,x}(z=i)}{L} y = \frac{B_{\max,x}(z=i)}{L} r \sin(\omega t)$$
(5)

$B_{\max,x}(z=i)$ ,  $B_{\max,y}(z=i)$  are the maximum values of  $B_x$  and  $B_y$  for a given  $z$ -coordinate, respectively.  $L$  is the radius of the electrode. An example of the suitability of this linear fitting of the  $X$  and  $Y$  components of the magnetic field is provided in **Figure 3 a,b and c ES13** for electrodes made of P-LMO, NMC 532 and P,Fe-LMO materials. The graphics were created using  $B_{x,y}$  components along  $x$  (or  $y$ ) for  $z = 0$  (surface of the electrode).



**Figure 3 ES13:** (a, b, c)  $B_x$  along the  $x$  direction at  $z = 0$  mm; (d, e, f)  $B_{\max,x}$  along the  $z$  direction.

Because,  $B_{\max,x}(z=i)$  and  $B_{\max,y}(z=i)$  also change between  $z=0$  and  $z=i$ , a linear dependency is also assumed for  $B_{\max,x}(z=i)$ ,  $B_{\max,y}(z=i)$  along the  $z$ -axe, equations 6. This allows us to finally parametrize the dependency of  $B_x$  and  $B_y$  above the electrode surface for any desired  $z$  vale.

$$B_{\max,x}(z=i) = B_{\max,x}(z=0) - k \cdot z \quad (6)$$

$$B_{\max,y}(z=i) = B_{\max,y}(z=0) - k \cdot z$$

where  $B_{\max,x}(z=0)$  and  $B_{\max,x}(z=i)$  are the maximum value of  $B_x$  on the electrode surface and a  $z=i$  distance from the surface, respectively.  $k$  is the rate of change of  $B_{\max}$  from the button up to a high  $z=i$ .

The fitting of  $B_{\max,x}(z=i)$  for the LMO, NMC 532, and P,Fe-LMO electrodes can be seen in Figure 3d, e, f ESI3.

By substituting (5) and (6) in (4) and clearing the Cartesian coordinates, the parametric equation of the cathode-anode trajectory of a  $\text{Li}^+$  ion starting at a distance  $r$  from the centre of the electrode is obtained. The form of the equation shows a trajectory in the form of a conical helix, where  $t$  (associated with the time) is the independent parameter.

$$\begin{cases} x = (A + B \cdot t)r \cos(wt) \\ y = (A + B \cdot t)r \sin(wt) \\ z = C \cdot t \end{cases} \quad (7)$$

$$\text{where } A = \frac{\sigma^2 E_z B_{0,\max}}{\rho w C_{\text{Li}} FL}, \quad B = \frac{\sigma^2 E_z k}{\rho w C_{\text{Li}} FL} \text{ and } C = \frac{\sigma E_z}{\rho}$$

The parameter  $w$  (associated with the angular velocity) can be easily determined from the current imposed during cycling by the expression:

$$w = \frac{I}{\pi L^2 \rho r} \quad (8)$$