

 : visited set

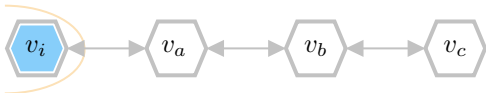
 : robot state

*Preach*

.995

.970

.920



$\text{gain}(v)$

