

# **Pile groups under axial loading: an appraisal of simplified nonlinear prediction models**

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## **ABSTRACT**

The settlement behaviour of vertically-loaded pile groups has been the subject of an extensive body of research over the past two decades. In particular, this work has identified the over-conservatism associated with predictions of pile interaction derived from elastic theory and the corresponding amplification of group settlement relative to single pile values. Researchers have since redoubled efforts to refine settlement predictions for pile groups towards more economical design, largely through more rigorous treatment of soil stiffness nonlinearity. Although foundation design engineers are increasingly employing three-dimensional continuum analyses to quantify pile interaction on a site-specific basis, simplified design approaches remain an integral part of preliminary foundation design. The purpose of this paper is to undertake a critical examination of these methods with a view to increasing their potential for take-up by foundation engineering practitioners. A database of simplified models has been collated for the prediction of nonlinear pile interaction that exists within vertically-loaded pile groups. These models are categorised as either analytical or empirical. The development, limitations, and range of applicability of these models are explored in detail in the context of some published case histories.

## INTRODUCTION

Pile foundations have been used for centuries as a means of transmitting structural loads to competent strata at depth in the ground. Piles installed in groups have the potential to carry large loads and are often the only viable solution when structures to be supported are heavy, or when the ground conditions are challenging. Traditionally, the emphasis in pile design was on predicting ultimate pile capacity, with a large factor of safety ensuring that settlements were small, formal estimates of which could often be avoided. More recently, this focus has shifted towards more economical serviceability limit-state design thereby prompting considerable research effort to refine predictions of single pile and pile group settlement. In particular, this has necessitated more reliable modelling of the development of pile-soil interface resistance during loading as well as more realistic treatment of pile-to-pile interaction.

An important outcome of research into the settlement behaviour of pile groups under axial loads is that predictions based on elastic theory alone are excessively conservative. As a result, the application of nonlinear frameworks to pile groups has increased substantially over the last two decades. Within a nonlinear framework, pile settlement is no longer uncoupled from the ultimate capacity and therefore an accurate estimation of capacity is a prerequisite for a rigorous analysis of the serviceability limit state. While three-dimensional nonlinear continuum analyses are becoming more commonplace, simplified design approaches remain an integral part of preliminary foundation design. There is now a myriad of approaches in the literature for the prediction of nonlinear pile interaction. The purpose of this paper is to undertake a critical examination of a selection of these methods, in the context of selected case histories, with a view to increasing their potential for take-up by foundation engineering practitioners; the primary focus is on developments since the seminal review paper on pile groups by Poulos (2006).

The settlement behaviour of piled foundations subjected to vertical loads is potentially governed by both pile-to-pile interaction and pile-soil-raft interaction (Ghalesari et al. 2015). Pile interaction effects, in particular those that exist between pile shafts, necessitate rigorous treatment as settlements are amplified relative to single pile values. Interaction between pile shafts is therefore central to this review. The role of soil stiffness nonlinearity on pile interaction is first considered. A database of existing simplified nonlinear models is collated, and categorised as either empirical or analytical. The associated assumptions, limitations, and applicability of each model are also discussed. Clearly the accuracy of any predictive model is dependent on the appropriateness of the input parameters. In light of this, careful consideration

of the pile type, installation effects, and the corresponding soil responses (dilation, pore pressure generation and evolution of stresses for example) is paramount.

## BACKGROUND: PILE GROUP INTERACTIONS

### *Pile-soil-raft interaction*

According to Comodromos et al. (2016), the resistance of a piled raft can be partitioned into three stages depending on the group settlement normalized by the pile diameter,  $S_{ng}$ :

1.  $0\% < S_{ng} < 1.5\%$ : the resistance of both the piles and the raft are linear and the resistance contribution from the raft is insignificant and therefore commonly ignored (Mandolini and Viggiani 1997; Xu and Zhang 2007; Kumar et al. 2017);
2.  $1.5\% < S_{ng} < 4\%$ : the piles exhibit up to ~90% of their limit capacity;
3.  $S_{ng} > 4\%$ : additional resistance of the piled raft is essentially attributed to the raft.

Those authors reported that the maximum contribution from the raft (acting within the piled raft system) was considerably lower than the corresponding resistance of an isolated raft. It was also noted that the maximum resistance provided by the piles was essentially unaffected by the existence of the raft (Comodromos et al. 2009). In light of this, the spring elements replacing the soil resistance around the piles may be considered independent from those simulating the resistance under the raft.

### *Nonlinear two-pile interaction factors*

The interaction factor method (IFM) is the most common means of accounting for pile interaction in the design of pile groups. This process essentially applies an amplification factor to the settlement of a single pile with the same applied load at the pile head. Initially, the interaction between a pair of piles (i and j) is quantified as a ‘two-pile interaction factor’,  $\alpha$ :

$$\alpha = \frac{\text{Additional settlement of pile } j \text{ due to nearby loaded pile } i}{\text{Settlement of single pile under its own (equivalent) load}} \quad (1)$$

Values of  $\alpha$  may be computed for each pile spacing,  $s$ , occurring within the group. The principle of superposition is then applied to calculate the cumulative interaction occurring within the group. However, inconsistencies in how  $\alpha$  is calculated feature in the literature. The receiver pile may be load-free (henceforth referred to as ‘Approach I’; see Fig. 1(a)) or loaded (henceforth referred to as ‘Approach II’, see Fig. 1(b)). When used within a linear elastic (LE)

framework, both approaches yield the same result. For real soils, however, the increased level of shear strain in the vicinity of a loaded pile causes a corresponding reduction in the soil modulus. The consideration of soil nonlinearity therefore results in different values of  $\alpha$  depending on the applied load level and whether Approach I or Approach II is adopted (McCabe and Sheil 2015).

#### *Validity of superimposing nonlinear interaction factors – numerical investigations*

The principle of superposition is not valid in nonlinear engineering problems. Nevertheless, a number of studies have investigated the role of soil stiffness nonlinearity in pile interaction and pile group settlement. Caputo and Viggiani (1984) described a case history on the interaction between an identical pile pair. The pile load tests consisted of one loaded pile while the other nearby pile remained load-free (i.e. Approach I). These authors noted that while the response of the loaded pile was highly nonlinear, the settlement of the load-free pile increased linearly with increasing applied load on the loaded pile (see Fig. 2).

Using three-dimensional finite element analysis (FEA), Trochanis et al. (1991) noted that the axial response of a single pile is identical whether the soil is modeled as elastic or elastoplastic when slip is accommodated at the pile-soil interface as shown in Fig. 3 (see Fig. 1(a) for definitions of pile/soil parameters). These authors concluded that soil nonlinearity must therefore be concentrated at the pile-soil interface from which it was deduced that the soil remains in a linear elastic state outside of this narrow region.

Leung et al. (2010) investigated the role of linear elasticity in pile group analysis by appraising LE and nonlinear methods for the analysis of pile groups against hypothetical scenarios and published case histories. These authors observed that within a pile group the “*nonlinearity in individual pile behavior becomes overwhelmed by the interaction effects*” and therefore pile interaction is governed by elastic behaviour (see Fig. 4).

Ju (2015) explored the role of soil stiffness nonlinearity on pile interaction using three-dimensional FEA. Three types of analyses were carried out: (1) a LE analysis of the entire soil domain; (2) a composite LE-nonlinear analysis where the soil immediately surrounding the piles was considered nonlinear and the rest of the soil considered LE; (3) a nonlinear analysis of the entire soil domain. This author noted that the type-2 analysis provided significantly improved agreement to field measurements by comparison to the type-1, which would be expected. Surprisingly, the agreement between FEA predictions and the measured response

was poorer for the type-3 compared to the type-2 analysis. It should be noted, however, that this comparison is highly dependent on the equivalent elastic stiffness adopted in the type-2 analysis. Nevertheless, these comparisons revealed that soil stiffness nonlinearity is confined to a radial distance of one pile diameter from the pile surface, slightly greater than that implied by Caputo and Viggiani (1984).

McCabe and Sheil (2015) employed a constitutive model featuring a stress-dependent nonlinear stiffness to explore the appropriateness of nonlinear IFM for predicting pile group settlement. This was achieved through comparison of settlement predictions determined from (i) a full 3D analysis of the entire group and (ii) superposition of  $\alpha$  using both Approach I and Approach II IFM. For floating pile groups, good agreement was observed between the direct and Approach I IFM methods. Comparisons between the direct and Approach II IFM predictions were less satisfactory. An example comparison is provided in Fig. 5 for a rigidly-capped floating pile group with a pile spacing-to-diameter ( $s/D$ ) ratio of 3 and a load factor ( $LF$ ) of 0.4 on the capacity of a single pile. Locating a stiffer stratum at the base of the piles was also shown to reduce the accuracy of Approach I predictions, although with a bias on the conservative side.

Wang et al. (2016a) presented similar comparisons between IFM and direct FEA. The IFM predictions involved coupling analytical single pile settlement predictions with the elastic interaction factors reported in Poulos and Davis (1980). Predictions of the total interaction experienced by a centre group pile for groups sizes,  $N$ , of 9, 25, and 49 piles are shown in Fig. 6. These authors suggested that “group reinforcing effects” on the soil continuum have a non-negligible influence on the accuracy of IFM, when compared to FEA, and they proposed a ‘linear approximate method’ to account for group reinforcing effects that demonstrated improved agreement to the direct analyses. Wang et al. (2016b) presented additional numerical results in an effort to reconcile the differences between IFM and FEA. This process involved determining the value of  $\alpha$  between a loaded source pile and a non-loaded receiver pile (labelled piles  $a - d$ ) using Approach I within groups of increasing size (see Fig. 7). Figure 8 shows that the influence of group reinforcing effects (i.e. the presence of intervening non-loaded group piles) on  $\alpha$  appear to be minimal for the group sizes and soil parameters considered in this example.

## 144 **EMPIRICAL METHODS**

### 145 *Overview of existing methods*

146 Empirical approaches allow pile group settlement performance to be determined directly, but  
147 based on experience from field/laboratory tests or advanced numerical modelling rather than a  
148 theoretical basis. The pile group settlement ratio,  $R_s$ , is the most common means of quantifying  
149 the extent of pile interaction within a pile group. This factor can be considered as an  
150 amplification factor on the settlement of a single pile subjected to an equivalent pile head load:

$$R_s = \frac{w_{group}}{w_{single}} \quad (2)$$

151 where  $w_{group}$  and  $w_{single}$  are the settlements of a pile group and single pile with the same head  
152 load per pile, respectively.

153 Skempton (1953) developed what appears to be the earliest empirical expression for  $R_s$  based  
154 on field tests of driven pile groups in sand:

$$R_s = \left( \frac{4B' + 2.7}{B' + 3.6} \right)^2 \quad (3)$$

155 where  $B'$  is the width of the plan area of the pile group in metres.

156 Meyerhof (1959) included the influence of pile spacing and the number of piles for square pile  
157 groups located in sand based on theoretical observations:

$$R_s = \frac{s/D(5 - \frac{(s/D)}{3})}{\left(1 + \frac{1}{n_r}\right)^2} \quad (4)$$

158 where  $n_r$  is the number of rows of piles in a square pile group.

159 Vesic (1969) simply related  $R_s$  to the pile group width,  $B_g$ , normalised by the pile diameter:

$$R_s = \sqrt{\frac{B_g}{D}} \quad (5)$$

160 Kaniraj (1993) developed a semi-empirical equation for  $R_s$ . A new term was introduced by this  
161 author, termed the 'settlement ratio for equal stress',  $R'_s$ , and defined as the ratio of the  
162 settlement of a pile group to that of a single pile when the average stress on their respective  
163 load transmitting areas are equal:

$$R'_s = 1.128 \sqrt{\frac{(n_r - 1)(n_c - 1)(S/D)^2}{\left(1 + 2\frac{L}{D}\tan\theta\right)^2} + \frac{(n_r + n_c - 2)\left(\frac{S}{D}\right)}{1 + 2\frac{L}{D}\tan\theta} + 1} \quad (6)$$

164 where  $\theta$  is the load dispersion angle, taken as  $\sim 7^\circ$  according to (Berezantzev et al. 1961), and  
 165  $n_c$  is the number of columns of piles in the pile group. The value of  $R_s$  may then be determined  
 166 as follows:

$$R_s = 1 + 0.67 \left( \frac{N_p S_{sh}}{R'_s S'_{sh}} - 1 \right) \quad (7)$$

167 where  $S'_{sh}$  and  $S_{sh}$  are the secant slopes of the hypothetical single pile load–displacement curve  
 168 under loads of  $qA_g/N$  and  $qA_s$  respectively and  $q$  is the applied stress. The term  $S'_{sh}/S_{sh}$  is used  
 169 to account for soil nonlinearity.

170 Castelli and Maugeri (2002) developed an approach based on the equivalent pier method  
 171 combined with a hyperbolic load–transfer function to model nonlinear interaction with soil:

$$R_s = \left( \frac{D}{D_g} \right)^{-\varepsilon} \quad (8)$$

172 where  $D_g$  is the equivalent diameter of the plan area of the pile group, and an exponent of  $\varepsilon =$   
 173 0.15 was derived from a limited database of pile group case histories.

174 McCabe and Lehane (2006) recast the Castelli and Maugeri (2002) approach to provide  
 175 improved agreement to a database of nine published pile group case histories. However, these  
 176 authors considered the group stiffness efficiency,  $\eta_g$ , defined as the inverse of  $R_s$ :

$$\eta_g = R_s^{-1} = \frac{[D_g/D]^{0.66}}{N} \quad (9)$$

177 Comodromos (2004) developed an approach through curve–fitting to numerically–derived  
 178 values of  $R_s$ . Three–dimensional finite difference analyses using an elastic–plastic soil model  
 179 were adopted for this purpose. The group sizes considered in the parametric analyses ranged  
 180 from 4 piles to 25 piles while a spacing of three pile diameters was maintained. Comodromos  
 181 and Bareka (2009) presented additional numerical analyses to extend the applicability of their  
 182 earlier approach to pile spacings ranging between two and five pile diameters, a broader range  
 183 of clayey soils, and alternative group configurations. Their expression is given below:

$$R_s = 0.8[S_{ns}^{0.07}(1.23N_R)^{1.9} + S_{ns}^{-0.08}e^{0.54N_R}] \ln \left( 1.25 + \frac{5}{s/D} \right) \quad (10)$$



184 where  $S_{ns}$  is the settlement of a single pile, normalised by the pile diameter and  $N_R$  is defined  
 185 by Comodromos et al. (2016) for large group sizes:

$$N_R = \frac{(N + 5)^{0.85}}{n_r + n_c} \quad (11)$$

186 Sheil and McCabe (2014) developed closed-form equations by curve-fitting results obtained  
 187 from 3D FEA using a nonlinear soil model. The influence of pile spacing, length, group  
 188 geometry and size, as well as the depth and stiffness of an underlying bearing stratum were all  
 189 considered in the parametric analyses. Three sets of equations to predict  $\eta_g$  were developed for  
 190 (i) pile groups in infinitely deep soil mass ( $h/L \geq 3$ ), (ii) pile groups in a finite soil mass ( $1 <$   
 191  $h/L < 3$ ), and (iii) pile groups end-bearing on a stiff soil stratum ( $h/L = 1$ ), where  $h$  is the depth  
 192 below ground level to a stiff bearing stratum.

193 For case (i), the following equation was developed where  $\eta_f$  signifies  $\eta_g$  for a floating pile  
 194 group:

$$\eta_g = \eta_f = \frac{[D_g/D]^A}{N + 1} \quad (12)$$

195 where  $A = 0.83(L/D)^{-0.071}$ . To account for the presence of a stiff bearing stratum beneath the  
 196 base of the pile group (case (ii)), additional terms were added to equation (12):

$$\eta_g = \eta_f + B \left( \frac{1}{h/L} \right)^6 \quad (13)$$

197 where  $B = 0.147(L/D)^{-0.272} \ln N$ . Finally, the expression developed for case (iii) was defined as  
 198 follows:

$$\eta_g = \eta_f \times \left( \frac{E_2}{E_1} \right)^C \quad (14)$$

199 where  $E_2/E_1$  is the stiffness of the bearing stratum relative to the soil along the pile shaft, and  
 200  $C = 0.112 \ln N - 0.11$ .

201

## 202 *Comparison of empirical methods*

203 Predictions of  $R_s$  determined by these empirical approaches are compared in Fig. 9 for a  
 204 variation in the number of piles (Fig. 9(a)) and pile spacing-to-length ratio ( $s/L$ ; Fig. 9(b)). A  
 205 selection of comparable field data has also been superimposed on these figures; the relevant

particulars are provided in Table 1. From Fig. 9(a), it can be seen that the associated predictions span a relatively broad spectrum. This highlights the importance of the data used in the development, calibration, and validation of these models and the corresponding range of applicability (see Table 2). In particular, the approaches developed by Comodromos (2004) and Comodromos and Bareka (2009) predict a steep increase in  $R_s$  with an increase in pile numbers. Comodromos et al. (2016) noted, however, that this approach was developed for smaller pile groups ( $N \lesssim 25$ ) and is likely to over-predict  $R_s$  for large groups. It can also be seen that predictions determined using the Skempton (1953) and Vesic (1969) are overly conservative, particularly for smaller pile groups. In contrast, predictions determined using the Castelli and Maugeri (2002) approach plot notably lower. This is due to the large proportion of end-bearing pile groups in the database of case histories used for calibration.

Considering the influence of  $s/L$  in Fig. 9(b), the three oldest approaches in this comparison predict an increase in  $R_s$  with increasing  $s/L$  predictions (the Meyerhof (1959) predictions exhibit a turning point at  $s/L \approx 0.3$ ), which contradicts the more recent approaches as well as the field data. This is probably due to the limited data from which the latter methods were developed.

## ANALYTICAL METHODS

### *Overview of existing pile shaft interaction models*

The aforementioned research on nonlinear soil behaviour has formed a basis for the use of the principle of superposition in nonlinear simplified predictive methods. These approaches vary in the number of parameters required to calibrate soil nonlinearity, their treatment of the elastic interaction displacements and conditions at the pile–soil interface such as whether slip is allowed (see Table 2).

Caputo and Viggiani (1984) documented one of the earliest nonlinear pile interaction methods. These authors compiled all values of  $\alpha$  that exist with a group into a single interaction matrix. Off-diagonal entries,  $\alpha_{ij}$  ( $i \neq j$ ), were assumed constant (independent of load level), whereas  $\alpha_{ii}$  varied depending on the load level to account for soil nonlinearity:

$$\alpha_{ii} = \frac{1}{1 - \frac{Q_i}{Q_{i,lim}}} \quad (15)$$

234 where  $\alpha_{ii}$  is the interaction factor for pile  $i$  under its own load,  $Q_i$ , and the ultimate load is  $Q_{i,\text{lim}}$ ,  
 235 as defined in Chin (1970).

236 Lee (1993) documented a simplified hybrid layer approach for predicting pile interaction; a  
 237 hyperbolic relationship between mobilised shear stress and displacement at the pile–soil  
 238 interface was used to consider soil stiffness nonlinearity. This author modified the Randolph  
 239 and Wroth (1978) elastic model, introducing a new stress–dependent  $\beta$  term. The incremental  
 240 soil settlement  $\Delta w_s$  for a single pile is obtained as follows:

$$\Delta w_s = \frac{\Delta P_s}{2\pi G_t L} \left[ \ln \left( \frac{r_m - \beta}{r_0 - \beta} \right) + \frac{\beta(r_m - r_0)}{(r_m - \beta)(r_0 - \beta)} \right] \quad (16)$$

$$\beta = \tau_0 r_0 R_f / \tau_f, \quad (17)$$

241 where  $\Delta P_s$  is the incremental load at the shaft node,  $G_t$  is the initial tangent shear modulus at  
 242 the pile shaft,  $L$  is the pile length,  $r_0$  is the pile radius,  $r_m$  is the lateral distance from the pile  
 243 centre at which the shear stress is considered negligible (Randolph and Wroth 1978),  $R_f$  is a  
 244 hyperbolic parameter, and  $\tau_0$  and  $\tau_f$  are the current and limiting shear stress at the pile–soil  
 245 interface respectively. For the calculation of  $\alpha$ , this author adopted the elastic solutions  
 246 documented in Randolph and Wroth (1979):

$$\alpha_{ij} = \frac{\ln \left( \frac{r_m}{r_s} \right)}{\ln \left( \frac{r_m}{r_0} \right)} \quad (18)$$

247 It is important to note that these values of  $\alpha$  were applied to the elastic portion of the soil  
 248 displacements (which may be obtained by setting the parameter  $\beta$  to zero).

249 As part of the French national project FOREVER, Maleki and Frank (1994) documented the  
 250 development of the ‘GOUPEG’ program for the analysis of micropiles installed in groups. This  
 251 method was considered a hybrid approach. The analysis of a single pile was conducted using  
 252 the load transfer method. Mindlin’s elasticity solutions were used to automatically calculate  
 253 the ‘interactive’ displacements induced on adjacent piles. The displacement component of the  
 254 single pile t-z curves was then modified to account for these additional interactive  
 255 displacements.

256 Costanzo and Lancellotta (1998) developed an analytical solution for nonlinear values of  $\alpha$  for  
 257 floating rigid piles. These authors proposed a linear variation of shear modulus with radial  
 258 distance from the pile to simulate, in a simplified manner, the degradation of shear modulus  
 259 due to shear strain:

$$G(r) = G_{min} + \frac{G_{max} - G_{min}}{r_l - r_0}(r - r_0) \quad (19)$$

where  $G(r)$  is the current shear modulus at a radius  $r$  from the pile,  $G_{max}$  and  $G_{min}$  are the maximum and minimum shear moduli occurring at a very large distance from the pile axis ( $r_l$ , taken as  $8.0D$ ) and at the interface of the pile ( $r_0$ ), respectively. The load–transfer relationship was subsequently defined as:

$$w_s = \frac{r_0}{G_{min}} \ln\left(\frac{r_l}{r_0}\right) \tau_0 \quad (20)$$

The free–field displacement field around a loaded pile (Randolph and Wroth 1979) was used to superimpose the effects of adjacent piles in the group, again ignoring the receiver pile reinforcing effect. The interaction between piles may then be determined as follows:

$$\alpha = 1 - \frac{\ln\left(\frac{s}{r_0} \frac{G_{min}}{G(s)}\right)}{\ln\left(\frac{r_l}{r_0} \frac{G_{min}}{G_{max}}\right)} \quad (21)$$

The influence of a reduced near–pile modulus on  $\alpha$  using this approach is presented in Fig. 10. Lee and Xiao (2001) adopted a discontinuous displacement function in order to confine plastic soil behaviour to a thin annulus surrounding a loaded pile (see Fig. 11). Outside of this annulus, the soil was assumed elastic. The pile settlement may be obtained as follows:

$$w_s = \frac{r_0}{G_0} \ln\left(\frac{r_m}{r_0}\right) \tau_0 + \frac{a\tau_0}{1 - b\tau_0} \quad (22)$$

where  $G_0$  is the small–strain (initial) stiffness, and parameters  $a$  and  $b$  describe the nonlinearity of the load–transfer curve (see Fig. 12). The first part of this expression represents the elastic soil displacements and corresponds to the solutions of Randolph and Wroth (1979). The second part represents the nonlinear portion of the displacements, using a hyperbolic model similar to that proposed by Duncan and Chang (1970). Pile interaction is determined using the free–field (elastic) soil displacement according to Randolph and Wroth (1979) and these are applied to the elastic portion of the settlement in equation (22); predictions of the displacement field surrounding a loaded single pile are shown in Fig. 13. Pile interaction is calculated by including the axial rigidity of the receiver pile; the final shear stress mobilisation at the interface is dependent on the relative pile–soil displacement.

Zhang *et al.* (2010) adopted a hyperbolic load–transfer model for the pile shaft:

$$\tau_0 = \begin{cases} \frac{w_s}{c + dw_s}; & w_s \leq w_u \\ \tau_f; & w_s \geq w_u \end{cases} \quad (23)$$

where  $c$  and  $d$  are the hyperbolic model fitting parameters, and  $w_u$  is the displacement required to mobilise  $\tau_f$ . Although parameters  $c$  and  $d$  should ideally be calibrated against measured experimental or field data, they may also be estimated from the following expressions (Zhang et al. 2010):

$$c = \frac{r_0 \ln\left(\frac{r_m}{r_0}\right)}{G} \quad (24)$$

$$d = \frac{R_f}{\tau_f} \quad (25)$$

where  $G$  is the shear modulus of the soil around the pile shaft. By contrast, no such guidance is provided for  $w_u$  in the absence of measured field or laboratory data. Pile interactive displacements were obtained by superimposing elastic free-field soil displacements according to Randolph and Wroth (1979) as defined in equation (18).

Zhang and Zhang (2011) considered interaction between piles with dissimilar lengths. The elastic solutions of Randolph and Wroth (1979) were adopted to describe the load-transfer relationship; nonlinearity of the load-displacement behavior of a single pile was included by imposing a maximum shear stress at the pile-soil interface. Instead of using the free-field displacement for the determination of the response of the non-loaded receiver pile, these authors also included the effect of the axial rigidity of the pile:

$$E_p A_p \frac{d^2 w_j(z)}{dz^2} - k_z \Delta w_j = 0 \quad (26)$$

where  $z$  is the depth below ground level,  $w_j$  is the pile displacement at point  $j$ ,  $k_z$  is the soil Winkler spring stiffness,  $\Delta w_j$  is the relative displacement between pile and soil at interface  $j$  of the non-loaded receiver pile, and  $E_p$  and  $A_p$  are the Young's modulus and area of the pile respectively. Wong and Poulos (2005) adopted approximate relationships to transform interaction factors for piles with identical lengths to those with dissimilar lengths. Modified versions of these expressions were adopted by Zhang and Zhang (2011):

For  $L_i > L_j$ :

$$\alpha'_{ij} \approx \frac{(\alpha_{ii} + \alpha_{jj})}{f_{1s}} \frac{1}{R_{1s}^K \cdot R_{1s}^L} \quad (27)$$

303 For  $L_i < L_j$ :

$$\alpha'_{ij} \approx \frac{\alpha_{jj}}{f_{s1}} \frac{1}{R_{s1}^K \cdot R_{s1}^L} \quad (28)$$

304 where  $L_i$  and  $L_j$  are the lengths of piles  $i$  and  $j$  respectively,  $f_{1s}$  and  $f_{s1}$  are the correction factors  
 305 for  $s/D$ , pile length difference, and soil modulus distribution,  $R_{s1}^K$  and  $R_{1s}^K$  are the correction  
 306 factors for the relative stiffness between the pile and soil,  $R_{s1}^L$  and  $R_{1s}^L$  are the correction factors  
 307 for the pile slenderness ( $L/D$ ). Closed-form expressions for these correction factors are  
 308 provided in Zhang and Zhang (2011) and Wong and Poulos (2005).

309 Wang *et al.* (2012) used a ‘*BoxLucasI*’ function to represent both the relationship between the  
 310 shear stress and local nonlinear displacement at the pile–soil interface,  $\Delta S$ :

$$\tau_0 = \tau_f (1 - e^{-A\Delta S}) \quad (29)$$

311 where  $A$  is a model parameter defined as follows:

$$A = \frac{G_0}{r_0 \ln\left(\frac{r_m}{r_0}\right) \tau_f} \quad (30)$$

312 The product of  $A$  and  $\tau_f$  can be considered as the initial stiffness of the curve (see Fig. 14).

313 Based on the work of Lee and Xiao (2001), the total displacement at the pile–soil interface is  
 314 obtained by adding the nonlinear displacements described by equation (29) (confined to the  
 315 pile shaft) and elastic displacements determined using the Randolph and Wroth (1979)  
 316 equations. These authors proposed an iterative process to account for the degradation in  
 317 stiffness of a concrete pile under compressive loads using the well-documented nonlinear  
 318 Hognestad model (Hognestad 1951; Hognestad et al. 1955). The interaction between piles was  
 319 based on the free-field (elastic) soil displacements which were determined using Randolph and  
 320 Wroth (1979).

321 Zhang and Zhang (2012) also adopted the hyperbolic load–transfer model (see equation (23))  
 322 employed by Zhang *et al.* (2010). These authors introduced a ‘reduction coefficient’,  $\lambda$ , to  
 323 account for the reinforcing effect in a simplified manner:

$$\lambda = \frac{r_0}{s} \frac{\ln\left(\frac{r_m}{s}\right)}{\ln\left(\frac{r_m}{r_0}\right)} \quad (31)$$

324 The modified interaction factor was therefore defined as:

$$\alpha = \left( \frac{s}{r_0} - 1 \right) \lambda \quad (32)$$

The influence of the reinforcing effect according to this simplified approach is shown in Fig. 15 along with predictions determined using the Mylonakis and Gazetas (1998) approach. For close pile spacings ( $s/D < 2$ ) this model predicts an increase in  $\alpha$  when reinforcing effects are taken into account. The minimum value of  $s/D$  that should be adopted is therefore equal to 2. Curiously, the interaction factor defined by equation (32), which is elastic, is applied to the total displacements, i.e. no distinction is made between plastic and elastic displacements.

Jiu and Huang (2014) proposed a simplified approach to consider the nonlinear behaviour of axially-loaded pile groups installed in layered soils. The nonlinearity of soil stiffness was confined to a narrow zone surrounding the soil while the soil medium was considered to be in a linear elastic state based on the findings of Caputo and Viggiani (1984). The nonlinear load-displacement behaviour of a single pile was considered using the hyperbolic load-transfer model proposed by Kraft et al. (1981):

$$w_s = \frac{\tau_0 r_0}{G_0} \ln \left( \frac{r_m/r_0 - R_f \tau_0/\tau_f}{1 - R_f \tau_0/\tau_f} \right) \quad (33)$$

Solutions for stresses and displacements in a layered elastic half space developed by Ai et al. (2002) were adopted to calculate elastic two-pile interactive displacements, while also accounting for the reinforcing effects of the receiver pile on the soil continuum. The principle of superposition is adopted to extrapolate to group behaviour. It is also possible to simulate realistic flexibility by coupling this analytical approach with FEA, making use of Mindlin's solution for an elastic plate (Mindlin 1951).

Sheil and McCabe (2016a; 2016b; 2017) adopted a nonlinear model for the evolution of soil shear modulus with mean pressure and shear stress level for the development of nonlinear load-transfer curves previously documented by Lee and Salgado (1999):

$$G = G_0 \left( 1 - f \left( \frac{\tau}{\tau_f} \right)^g \right) \left( \frac{p'}{p'_0} \right)^n \quad (34)$$

where  $G$  is the current shear modulus,  $f$  and  $g$  are empirical curve fitting parameters,  $p'$  is the mean effective stress which has a far field value of  $p'_0$ ,  $n$  is a constant between 0.5 and 1 and controls the stress dependency of soil stiffness.

Zhang et al. (2016) also adopted the load-transfer approach proposed by Lee and Xiao (2001) where the total settlement at the pile shaft is decoupled into elastic and plastic displacements.

Receiver pile reinforcing effects were included by relating the shear stress mobilised on the non-loaded receiver pile to the relative displacement between (i) the displacement field induced by the nearby loaded source pile, and (ii) the displacement of the receiver pile.

#### *Pile base interaction model*

Although the focus of this paper is a review of pile shaft interaction models, a model for the load-displacement relationship at the pile base must be included to enable comparisons with pile groups subjected to compressive axial loads. To this end, the well-documented base model proposed by Chow (1986) has also been adopted here and coupled with the shaft models described above:

$$w_b = \frac{P_b(1 - \nu_s)}{2DG_b} \frac{1}{\left(1 - \frac{R_{fb}P_b}{P_{bu}}\right)^2} \quad (35)$$

where  $w_b$  is the pile base settlement;  $P_b$  is the pile base load;  $\nu_s$  is the Poisson's ratio of the soil;  $G_b$  is the shear modulus at the pile base;  $P_{bu}$  is the limiting base load; and  $R_{fb}$  is a parameter that determines the extent of soil nonlinearity. The interaction between pile bases ( $\alpha_b$ ) was considered using the Randolph and Wroth (1979) approach:

$$\alpha_b = \frac{2r_0}{\pi r} \quad (36)$$

## **COMPARISON OF ANALYTICAL MODELS AGAINST FIELD DATA**

### *Case I: Single pile and pile group load tests, Belfast, Northern Ireland*

A selection of the aforementioned analytical models have been used to predict the behaviour of a tension-loaded single pile and five-pile group case history at Belfast, Northern Ireland (McCabe 2002; McCabe and Lehane 2006). Precast square concrete piles with an equivalent diameter,  $D_{eq}$ , of 0.282 m were driven to a depth of 6 m in a soft lightly-overconsolidated estuarine silt deposit. The group piles were arranged in a square quincuncial formation at a spacing-to-diameter ( $s/D_{eq}$ ) ratio of 2.7. An initial elastic shear modulus,  $G_0$ , of 10 MPa was deduced from seismic cone tests which remained relatively constant over the depth of the piles (McCabe 2002). A value of 20 kPa was measured for the in-situ undrained shear strength,  $s_u$ , (incorporating Bjerrum's correction for plasticity index) using a field shear vane (McCabe and



Phillips 2008). An adhesion factor of 0.8 combined with a shaft capacity reduction factor,  $R_t$ , of 0.85 to account for ‘barrelling’ of the pile and a loss of effective stress due to tension loading (De Nicola and Randolph 1993) results in a value of  $\tau_f = 13.6$  kPa.

The parameter selection for each of the analytical approaches is as follows:

- i. For the Lee et al. (1993) predictions,  $G_0$  was adopted for  $G_t$  in equation (16) while the value of  $r_m$  was calculated as 11.25 m for undrained conditions (Poisson’s ratio,  $\nu = 0.5$ ) and a constant–stiffness profile. A value of 0.9 was assumed for  $R_f$  in all instances.
- ii. For the implementation of their methodology, Costanzo and Lancellotta (1998) adopted a shear strain level of the order of 0.27%; from measured stress–strain curves in triaxial compression (McCabe 2002), this corresponds to values of  $G_{\min}$  and  $G_{\max}$  of  $0.1G_0$  and  $G_0$  respectively for use in equations (21) and (22). The value of  $r_1$  was assumed as 8.0D (2.3 m).
- iii. For the Lee and Xiao (2001) approach, the parameters  $a$  and  $b$  (equation (22)) were determined as the inverse of the initial shear stiffness at the pile–soil interface (assumed to be equivalent to  $G_0$ ) and the inverse of  $\tau_f$  respectively.
- iv. A limiting shear displacement,  $w_u$ , of 5 mm was adopted in equation (23) for the Zhang et al. (2010) approach based on common values reported in the literature (Sheil and McCabe 2016a). Parameters  $c$  and  $d$  were determined using equations (24) and (25) respectively.
- v. In the Wang et al. (2012) method, parameter A was determined using equation (30).

The analytical predictions are compared to measurements of the single pile load–displacement response, interaction between the centre and corner group piles (for  $LF = 0.5$ ), and group load–displacement response in Figs 16(a) – 16(c) respectively.

#### *Case II: Ghent Silos, Belgium*

Goossens and Van Impe (1991) documented a case history of 40 cylindrical reinforced concrete silos founded on a 1.2 m thick piled raft. The foundation had a footprint of 34 m by 84 m and comprised 697 driven cast-in-situ reinforced concrete piles. The piles were 13.4 m in length (13 m embedded length), 0.52 m in diameter and had an enlarged 0.8 m diameter base. The piles were located in predominantly ‘loamy or clayey sand’. Goossens and Van Impe (1991) used cone penetration test data to deduce a maximum shaft resistance,  $\tau_{f\_of}$  of ~100 kPa and an ultimate base load,  $P_{bu}$ , of 2.77 MN. A small-strain shear modulus of 28.6 MPa recommended by Poulos (1993) was also selected here. A default value of 0.9 was adopted for  $R_{fb}$ . Two static

pile load tests that were conducted at the site were documented by those authors as well as thirteen years of settlement monitoring along the length of the silos. The fully loaded silos, which imposed a footprint pressure of  $\sim 300$  kPa, transferred a load of  $\sim 1.3$  MN to each pile. The normalised spacing between piles ( $s/D$ ) was calculated as  $\sim 3.9$ . Given the uniform nature of the loading and the thickness of the raft with respect to its footprint, flexible boundary conditions (i.e. equal pile head loads) were assumed at the pile heads within the foundation. The parameter selection followed the same procedure as the previous case study with the following exceptions:

- i. The value of  $r_m$  was calculated as 24.4 m ( $\nu = 0.25$ ).
- ii. In the absence of site-specific data, a default value of  $0.25G_0$  was adopted for the Costanzo and Lancellotta (1998) approach. Results using two different values for the parameter  $r_1$  are compared in Fig. 17(b):  $r_1 = 8.0D$  (recommended in Costanzo and Lancellotta 1998) and  $r_1 = r_m = 24.4$  m.

The analytical predictions are compared to measurements of the single pile tests and the ‘short-term’ settlement distribution of the silos (i.e. approximately two years after construction) in Figs 17(a) and 17(b) respectively.

### *Case III: Liquid ammonia storage tanks, Thessaloniki, Greece*

Badellas et al. (1988), Georgiadis et al. (1989) and Savvaidis (2003) reported a case history of settlement measurements of a 38 m diameter liquid storage tank founded on 112 bored piles, 1 m in diameter and 42 m long (40.7 m embedded depth). The concrete raft was 0.8 m thick. The soil profile comprised predominantly silty clay. Undrained shear strengths ranging from 36 kPa to 115 kPa were reported by Georgiadis et al. (1989) while the small strain shear moduli ranged between 33 MPa and 226 MPa. The average normalised spacing for the piles was  $\sim 3.6$ . Flexible boundary conditions were again assumed at the pile heads. Fourteen of the piles were monitored for settlement during a water load test in which the tank was filled with 160 MN of water ( $\sim 1.4$  MN per pile). The analytical predictions are compared to measurements of the settlement distribution across the diameter of the tanks in Fig. 18.

441 From Fig. 16(a), it can be seen that the models documented by Lee and Xiao (2001), Zhang et  
442 al. (2010), and to a lesser extent Zhang and Zhang (2012), all provide good predictions of the  
443 single pile load-displacement response at the Belfast site. While the Lee (1993) method  
444 provides a very good estimate of the initial stiffness, the nonlinearity is significantly under-  
445 predicted. The least satisfactory predictions are obtained using the Costanzo and Lancelotta  
446 (1998) approach; it should be noted, however, that significantly improved agreement could be  
447 obtained if  $G_{\min}$  in equations (19) and (20) was a function of strain or stress level (see equation  
448 (34) for example) rather than simply selecting a constant value. Surprisingly, none of the  
449 approaches provide an accurate prediction of the two-pile interaction factor,  $\alpha$ , in Fig. 16(c).  
450 From Fig. 16(b) the approach documented by Zhang et al. (2010) appears to provide the best  
451 agreement to the field data. This may, however, be somewhat fortuitous given that this method  
452 over-predicts  $\alpha$ .

453 For the Ghent silos case history, all methods appear to provide similar predictions of the load-  
454 displacement response for the two single pile load tests in Fig. 17(a). This is probably because  
455 these methods are dominated by the response of the enlarged pile base and the same base model  
456 has been adopted for each approach. It can be seen from Fig. 17(b) that all approaches capture  
457 the shape of the settlement distribution reasonably well thereby justifying the assumption of  
458 equal pile head loads. In this instance, the methods documented by Lee (1993), Zhang et al.  
459 (2010), and Zhang and Zhang (2012) provide the best agreement to the monitored settlements.  
460 Two different sets of parameters were used with the approach documented by Costanzo and  
461 Lancellotta (1998) i.e.  $r_1 = 8.0D$  and  $r_1 = r_m$ . The former set of parameters provides relatively  
462 poor predictions. However, improved agreement is obtained using the relationship  $r_1 = r_m$ .

463 For the Thessaloniki storage tanks case history, all approaches provide an excellent description  
464 of the shape of the settlement distribution again indicating flexible pile cap behaviour. The  
465 method by Zhang and Zhang (2012) provides a very good prediction of the settlement  
466 distribution followed by the methods of Lee (1993), Wang et al. (2012) and Zhang et al. (2012).  
467 It can also be seen that the method proposed by Costanzo and Lancellotta (1998) using  $r_1 = r_m$   
468 provides good agreement.

469 From an overview of the results presented in Figs 16 – 18, the following general observations  
470 can be made regarding each analytical method:

- Lee (1993): although this method appears to over-predict the stiffness of the load-displacement response for a single pile, this is likely to be attributable to the use of  $G_t = G_0$  in the present paper; the use of a more realistic tangent modulus will therefore provide improved agreement. For working loads where the level of nonlinearity is reduced, this method provides very good predictions of group response.
- Costanzo and Lacellotta (1998): this method provides poor predictions of single pile and pile group response if the relationships proposed in that study are adopted. In particular, one of the difficulties with this approach is the selection of the  $G_{\min}$  parameter. For the Ghent silos and Thessaloniki storage tanks case histories, an arbitrary relationship of  $G_{\min} = 0.25G_0$  was adopted given the lack of detailed site investigation. Refinement of this parameter as well as  $r_1$  would improve the predictions significantly.
- Lee and Xiao (2001): in general, this method provides a good description of the load-displacement response of both a single pile and pile group while the method of determining and applying the pile interactive displacements is rigorous.
- Zhang et al. (2010): while this approach provides a good description of the load-displacement response of a single pile, the process of applying elastic interaction factors to the total single pile displacements leads to over-predictions of the settlement of a pile group (albeit slight at working loads).
- Wang et al. (2012): this method captures the initial stiffness of the load-displacement response for a single pile but struggles to capture the highly nonlinear responses considered in the these case histories. Nevertheless, this method provides good predictions of group response due to a rigorous treatment of pile interaction (i.e. application of interaction factors to elastic components of single pile settlement).
- Zhang and Zhang (2012): although this approach exhibits an unusual distribution for the pile interaction factor as a function of pile spacing (see Fig. 16(b)), the application of the interaction factor to the elastic component of the single pile settlement is a more robust procedure compared to its predecessor (Zhang et al. 2010). In light of this, predictions using this method consistently showed good agreement to the measured data.

It should be noted that the predictions presented herein are heavily dependent on the selected input parameters. Insistence upon high quality input parameters that will capture the behaviour

of a single pile is a key step in capturing pile group response. These parameters should reflect the type of pile, pile installation effects and the soil behaviour.

## CONCLUSIONS

In this paper, a database of simplified models has been collated, for use by foundation specialists, enabling the prediction of the nonlinear pile interaction that occurs within vertically-loaded pile groups. These models were categorised as either empirical or analytical. Recent research on the role of soil stiffness nonlinearity in pile interaction has confirmed that the influence of soil plasticity is confined to a narrow zone of soil surrounding a loaded pile whereas pile interactive displacements remain essentially elastic. This has paved the way for the use of the principle of superposition (i.e. the interaction factor method) within a nonlinear analytical framework. The vast majority (if not all) of existing analytical approaches for predicting nonlinear pile group behaviour are therefore coupled with the interaction factor method.

Three published case histories, involving different pile types, group sizes (5, 112, and 697 piles) and ground conditions, were considered to appraise predictions determined from a selection of the analytical methods reviewed in the paper. This exercise revealed that non-linear soil behaviour is essential if the highly nonlinear load-displacement response of a small pile group is to be captured accurately. For larger pile groups, the response of the group is dominated by elastic interactions and the contribution of soil-nonlinearity is therefore limited. The merit of including non-linear interaction within a design approach therefore appears to be dependent on the group size under consideration. It is worth noting that when the pile shaft resistance is fully mobilised, the continuous form of the interaction factor methods become less reliable and the use of the above methods at the onset of pile-soil slippage is not recommended. Although the methods explored in this paper provide a more rigorous framework for the analysis of pile group response, accurate assessment of pile / soil input parameters remains one of the key challenges in foundation design.

In contrast to analytical approaches, the majority of empirical approaches are not formed from a theoretical basis. Instead, these methods are developed, calibrated, and validated against a selection of case histories or numerical results. These approaches therefore have an implicit range of applicability that is often over-looked. In particular, approaches developed from

534 analyses of smaller pile groups provide overly-conservative predictions of pile interaction for  
535 large pile groups.

536

537 NOTATION LIST

$\alpha$	Two-pile interaction factor
$\beta$	Stress-dependent term used in Lee (1993)
$\varepsilon$	Exponent used in Castelli and Maugeri (2002) method
$\eta_f$	Stiffness efficiency of a floating pile group
$\eta_g$	Stiffness efficiency of a pile group
$\theta$	Load dispersion angle
$\lambda$	Pile interaction reduction factor due to receiver pile reinforcing effects
$\tau_f$	Limiting shear stress at pile-soil interface
$\tau_0$	Shear stress at pile-soil interface
$A$	Nonlinear fitting parameters used in Wang et al. (2012) method
$A_p$	Area of the pile
$a, b$	Nonlinear fitting parameters used in Lee and Xiao (2001) method
$B'$	Pile group width used in Vesic (1969) approach
$B_g$	Width of the plan area of a pile group in metres used in Skempton (1953) approach
$c, d$	Nonlinear fitting parameters used in Zhang et al. (2010) method
$D$	Pile diameter (circular) or width (square)
$D_{eq}$	Equivalent diameter of a non-circular pile
$D_g$	Equivalent diameter of the plan area of a pile group
$E_p$	Young's modulus of the pile
$f, g$	Nonlinear fitting parameters for soil modulus degradation model (Lee and Salgado 1999)
$f_{1s}, f_{s1}$	Correction factors for pile spacing, pile length difference, and soil modulus distribution used in Zhang and Zhang (2011) method
$G_{max}$	Maximum (far-field) soil modulus at a distance $r_1$ from the pile centre
$G_{min}$	Minimum shear modulus at the pile-soil interface
$G(r)$	Shear modulus at a distance $r$ from the pile centre
$G_t$	Initial tangent shear modulus at the pile shaft
$G_0$	Initial small-strain shear modulus
$k_z$	Soil Winkler spring stiffness
$L$	Pile length
$LF$	Load factor (as a fraction of the capacity of a single pile)

$L_i, L_j$	Length of pile $i, j$
$N$	Pile group size
$n$	Constant controlling the stress-dependency of soil stiffness
$n_c$	Number of columns of piles in a pile group
$n_r$	Number of rows of piles in a pile group
$\Delta P_s$	Incremental shaft load
$p'$	Current mean effective stress of the soil
$p'_0$	Far-field (undisturbed) mean effective stress of the soil
$q$	Applied stress
$Q_i$	Load applied to pile $i$
$Q_{lim}$	Ultimate limit load as defined in Chin (1970)
$R_f$	Hyperbolic model fitting parameter
$R_{s1}^L, R_{1s}^L$	Correction factors for pile slenderness used in Zhang and Zhang (2011) method
$R_{s1}^K, R_{1s}^K$	Correction factors for the relative stiffness between the pile and soil used in Zhang and Zhang (2011) method
$r_m$	Lateral distance from the pile wall at which the shear stress is considered negligible
$R_s$	Pile group settlement ratio
$R'_s$	Pile group settlement ratio for equal stress
$R_t$	Shaft capacity reduction factor during tensile loading due to pile barrelling and loss of effective stress
$r_0$	Pile radius
$s$	Spacing between piles
$S_{ng}$	Displacement of a pile group normalised by the pile diameter
$S_{ns}$	Displacement of a single pile normalised by the pile diameter
$S'_{sh}, S_{sh}$	Secant slopes of a hypothetical single pile load–displacement curve used in Kaniraj (1993) method
$s_u$	Undrained shear strength of the soil
$s_{u0}$	Far-field (undisturbed) undrained shear strength of the soil
$\Delta S$	Local nonlinear displacement at pile shaft
$w_{group}$	Displacement of a pile group
$\Delta w_j$	Relative displacement between pile and soil at interface $j$ of the non–loaded receiver pile
$\Delta w_s$	Incremental soil settlement at pile–soil interface



$w_s$	Soil displacement at pile-soil interface
$w_{\text{single}}$	Displacement of a single pile
$w_u$	Displacement required to mobilise limiting shear stress
$z$	Depth below ground level

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**Table 1** Particulars of the field data presented in Fig. 9

Reference	Pile type	Soil conditions	N	L/D	s/D
Koizumi & Ito (1967)	Driven	Silty clay	9	18.5	3
					5
					4
Brand et al. (1972)	Driven	Soft sensitive marine clay	4	40	3
					2.5
					2
Trofimenkov (1977)	Driven	Stiff silty clay	9	30	3.4
Bartolomey et al. (1981)	Driven	Stiff clay	9	39	3
O'Neill et al. (1982)	Driven	Stiff clay	9	48.5	3
Rampello (1994)	Bored	Medium – stiff clays	74	47	3.1
Randolph & Clancy (1994)	Bored	Hard silty clay & dense sand	38	25	3.5

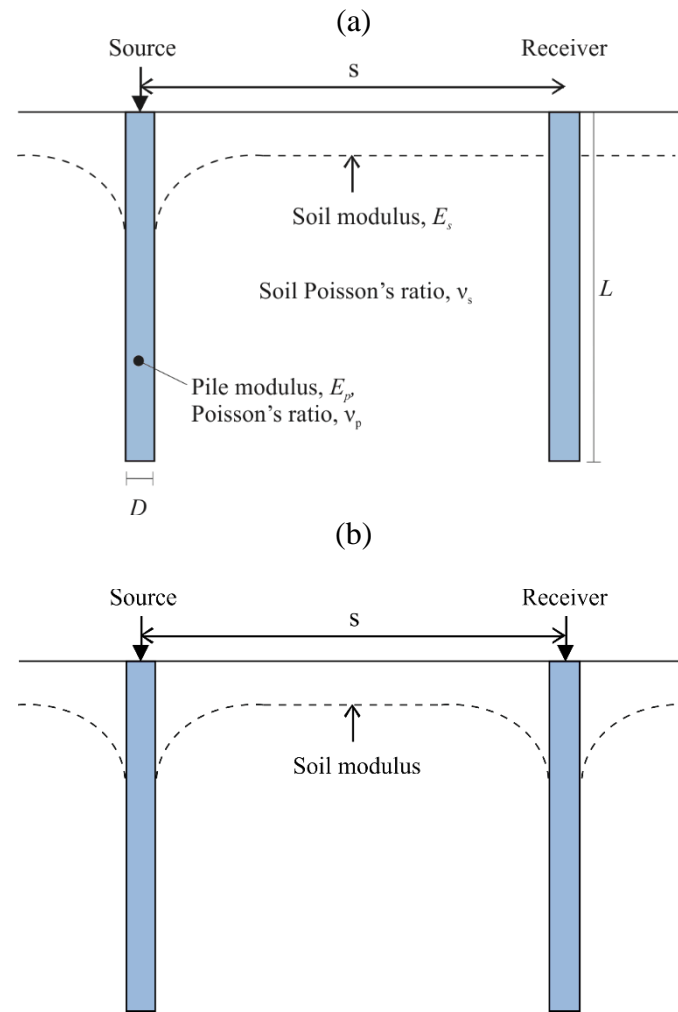
**Table 2** Database of empirical approaches and their range of applicability

Reference	Development	Validation data							
		Data	Soil conditions	Installation	Pile type	Load level	N range	s/D range	L/D range
						Single pile capacity			
Skempton (1953)	Field tests	Field tests	Sand	Driven	–	0 – 1 (can account for nonlinear behaviour)	–	–	–
Meyerhof (1959)	Theoretical observations	Field tests	–	–	–		–	–	–
Vesic (1969)	Field tests	Field tests	Medium sand	Jacked	Aluminium pipe		4 – 9	2 – 6	15
Kaniraj (1993)	Theoretical observations from Berezantzev et al. (1961) modified to fit a database of field tests	Field tests	Sand						
Castelli & Maugeri (2002)	Hyperbolic equivalent pier approach	Field tests	Clay, medium sand	Driven	Steel closed-ended pipe, concrete-filled steel pipe	–	4 – 140	3	33 – 44
Comodromos (2004)	3D elastic-plastic FEA	3D elastic-plastic FEA	Soft clay	Bored	Concrete	0 – 1	4 – 25	3	30
Comodromos & Bareka (2009)	3D elastic-plastic FEA	3D elastic-plastic FEA	Soft clay – stiff clay	Bored	Concrete	0 – 1	6 – 25	2 – 5	25 – 50
McCabe & Lehane (2006)	Modified Castelli & Maugeri (2002) hyperbolic approach	Field tests	Soft clay – medium sand	Driven	Concrete, steel pipe	0.4	4 – 97	2.5 – 7.1	18.5 – 26
Sheil & McCabe (2015)	3D nonlinear FEA	Field tests	Clays & sands	Driven, bored	Concrete, steel pipe, timber	0.4	4 – 697	1.8 – 7.1	14 – 107

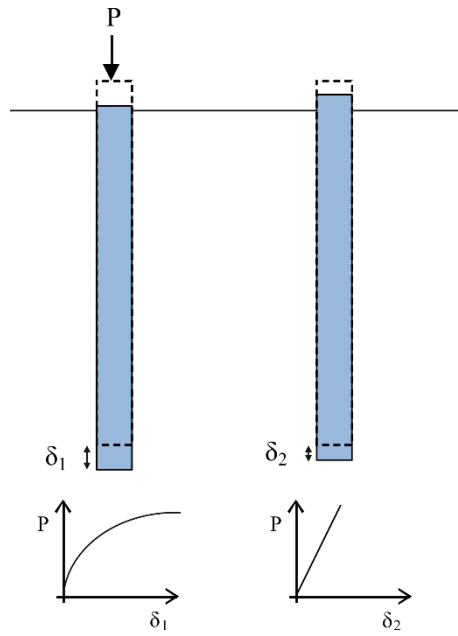
**Table 3** Database of closed-form analytical models for predicting pile interaction and their main features

Reference	Calibration of shaft load-transfer model parameters	Soil stiffness nonlinearity	Pile interaction	Pile-soil slip
Caputo & Viggiani (1984)	$Q_{lim}$ determined using Chin (1970) solutions	Nonlinear expression for $\alpha_{ii}$	Use of previously-documented elastic interaction factors.	Not included.
Lee (1993)	$R_f$ may be calibrated against measured load-transfer curves or assumed as 0.9; $r_m$ is determined using Randolph & Wroth (1979) expressions.	Hyperbolic load-transfer model.	$\alpha$ determined from elastic free-field soil displacements (Randolph & Wroth 1979) solutions, applied to the elastic component of the source pile displacements.	Redistribution of stresses once pile-soil limiting resistance is reached
Costanzo & Lancellotta (1998)	$G_{min}$ must be determined based on current shear stress level from measured stress-strain curves; $r_1$ may be determined from FEA or assumed as eight times the pile diameter.	Lateral variation in shear modulus.	$\alpha$ determined from elastic free-field soil displacements (Randolph & Wroth 1979) solutions, applied to total source pile displacements.	Not included.
Lee & Xiao (2001)	Parameters $a$ and $b$ are calibrated against elemental tests of the interface or measured load-transfer curves. Alternatively $a$ may be assumed as the reciprocal of the soil shear stiffness and $b$ the reciprocal of the limiting shear stress. Parameter $r_m$ determined using Randolph & Wroth (1979) expressions.	Hyperbolic model for the nonlinear portion of the load-transfer.	$\alpha$ determined from elastic free-field soil displacements (Randolph & Wroth 1979) solutions, applied to the elastic component of the source pile displacements. Influence of receiver pile rigidity considered by imposing negative skin friction on loaded pile.	Although pile and soil are considered ' <i>noncompatible</i> ', full pile-soil slip not possible due to the decoupling of elastic and plastic displacements.
Zhang et al. (2010)	Parameters $c$ , $d$ , $R_f$ and $w_0$ are determined experimentally or by back-analysis of field load tests results; a 'simple' analytical approach is also available for the estimation of parameters $c$ and $d$ .	Hyperbolic load-transfer model.	$\alpha$ determined from elastic free-field soil displacements (Randolph & Wroth 1979) solutions, applied to total source pile displacements.	Maximum shear stress enforced at interface introduces pile-soil slip implicitly.
Zhang & Zhang (2011)	Parameter $r_m$ determined using Randolph & Wroth (1979) expressions.	Maximum shear stress imposed at interface.	$\alpha$ determined from elastic free-field soil displacements (Randolph & Wroth 1979) solutions, applied to total source pile displacements. Influence of receiver pile rigidity considered by relating relative settlement to soil spring stiffness.	Maximum shear stress enforced at interface introduces pile-soil slip implicitly.
Wang et al. (2012)	Parameter $A$ is calibrated against elemental tests of the interface or measured load-transfer curves; $r_m$ determined using Randolph & Wroth (1979) expressions; $R_f$ may be calibrated against measured load-transfer curves or assumed as 0.9.	BoxLucas1 function used to define load-transfer curve.	$\alpha$ determined from elastic free-field soil displacements (Randolph & Wroth 1979) solutions, applied to the elastic component of the source pile displacements.	Full pile-soil slip not possible due to the decoupling of elastic and plastic displacements.
Zhang & Zhang (2012)	See calibration for Zhang et al. (2010).	Hyperbolic load-transfer model.	$\alpha$ determined from elastic free-field soil displacements (Randolph & Wroth 1979) solutions, applied to the total displacements of the source pile. Simplified model developed for including pile reinforcing effects.	Maximum shear stress enforced at interface introduces pile-soil slip implicitly.
Jiu & Huang (2014)	Parameter $r_m$ determined using Randolph & Wroth (1979) expressions; $R_f$ may be calibrated against measured load-transfer curves or assumed as 0.9.	Hyperbolic load-transfer model.	Interactive displacements determined using elastic solutions documented by Ai et al. (2002) which also consider receiver pile reinforcing effects.	Not included.
Zhang et al. (2016)	See calibration for Lee and Xiao (2001)	Hyperbolic model for the nonlinear portion of the load-transfer.	$\alpha$ determined from elastic free-field soil displacements (Randolph & Wroth 1979) solutions, applied to the elastic component of the source pile displacements. Influence of receiver pile rigidity considered by imposing negative skin friction on loaded pile.	Full pile-soil slip not possible due to the decoupling of elastic and plastic displacements.

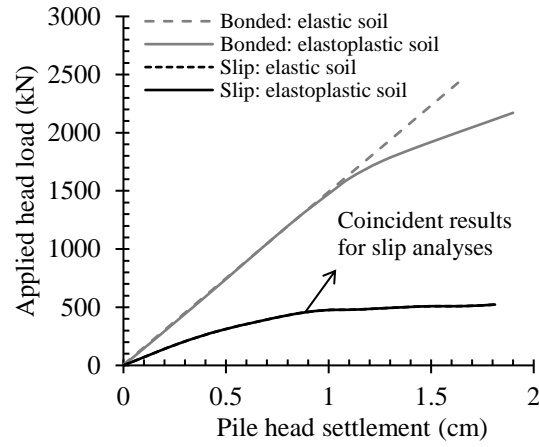




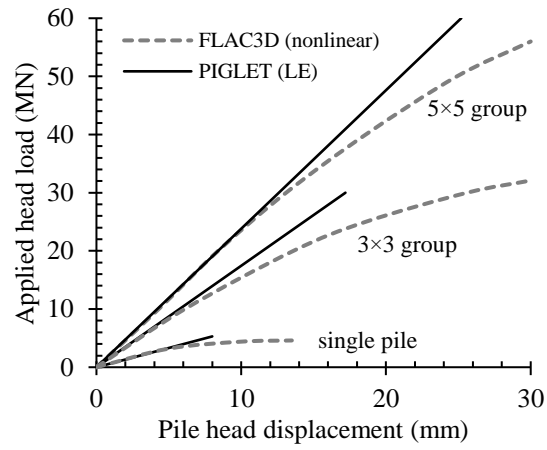
**Fig. 1** Illustration of (a) Approach I and (b) Approach II interaction factors



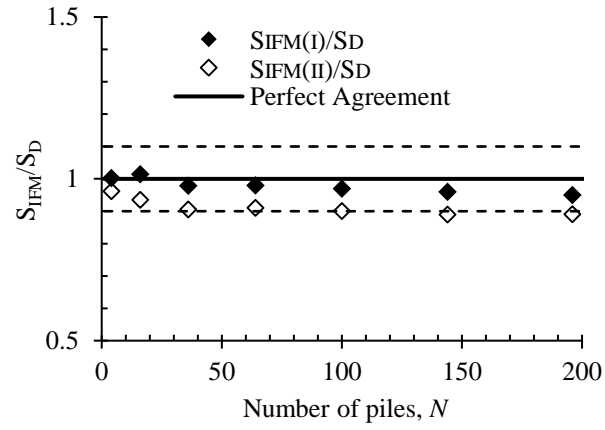
**Fig. 2** Illustration of case history and findings documented by Caputo and Viggiani (1984)



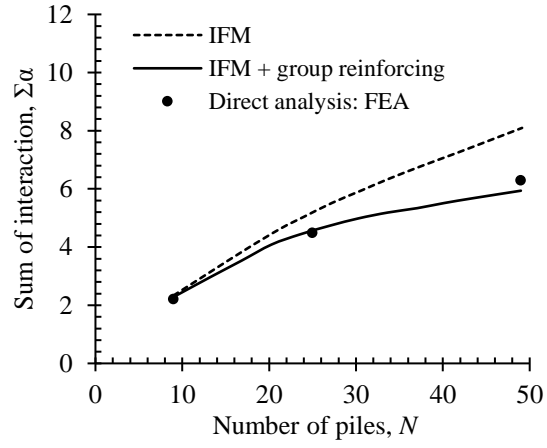
**Fig. 3** Influence of slip on the response of a single vertically loaded pile using FEA coupled with an elastic and elastoplastic (Drucker-Prager) model (after Trochanis et al. 1991);  $E_p = 20$  GPa,  $\nu_p = 0.3$ ,  $L = 10$  m,  $B = 0.5$  m,  $E_s = 20$  MPa,  $\nu_s = 0.45$ . Drucker-Prager parameters:  $\phi' = 16.7^\circ$ ,  $s_u = 34$  kPa.



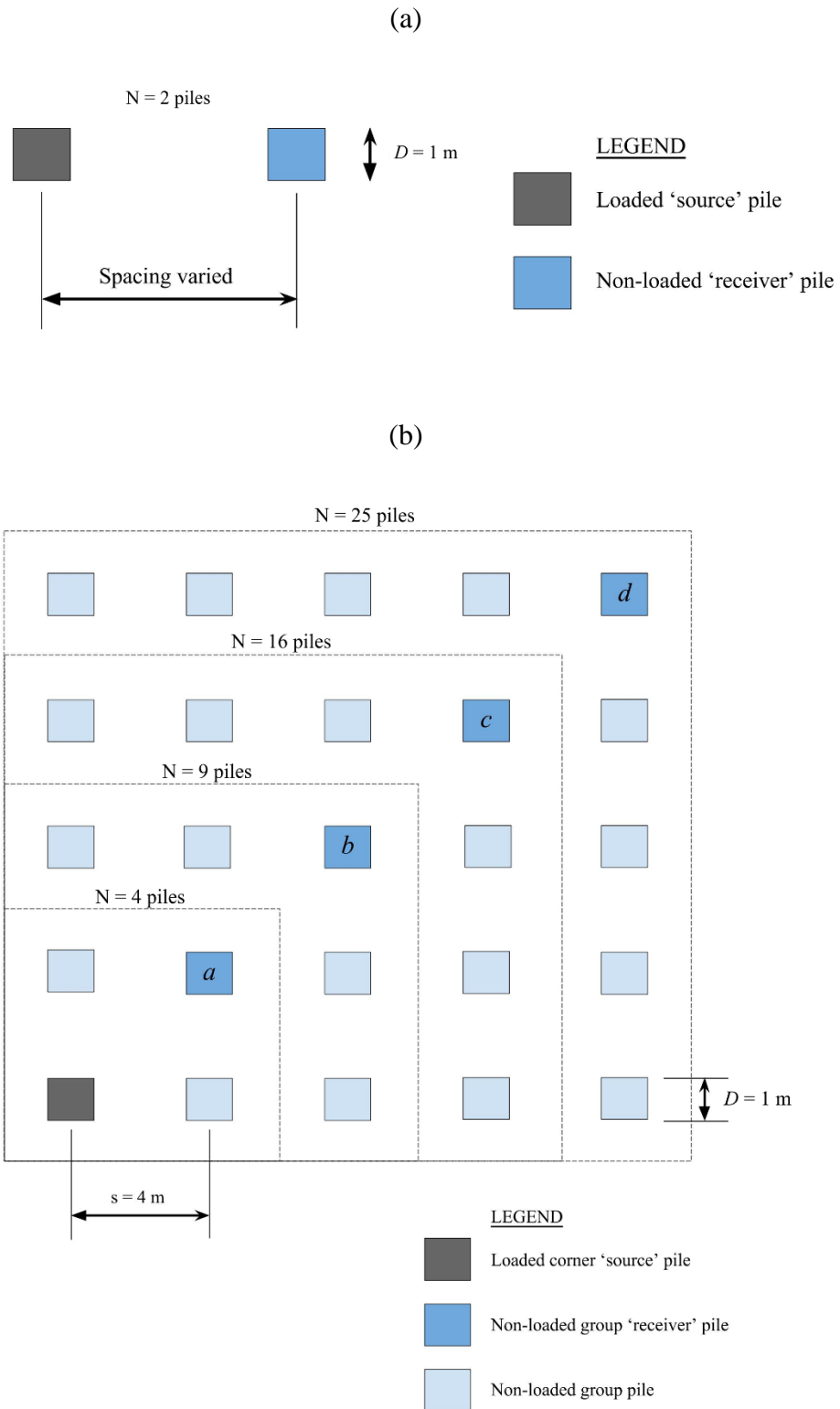
**Fig. 4** Comparison of nonlinear and LE numerical analyses (after Leung *et al.* 2010); no interface elements, pile groups connected to rigid cap,  $E_p = 30$  GPa,  $L = 20$  m,  $D = 1$  m,  $s = 3$  m,  $E_s = 30$  MPa,  $s_u = 60$  kPa,  $v_s = 0.3$



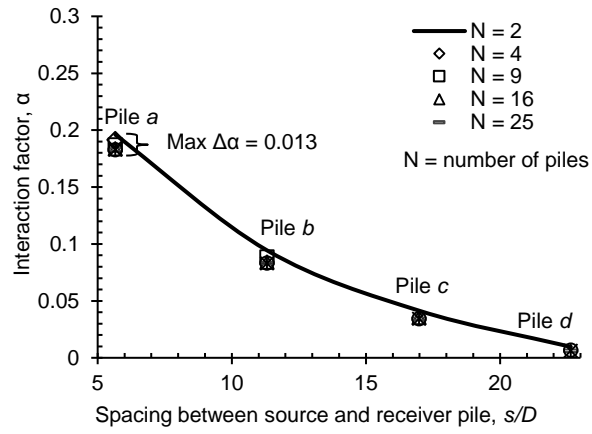
**Fig. 5** Comparison between Approach I IFM ( $S_{\text{IFM(I)}}$ ), Approach II IFM ( $S_{\text{IFM(II)}}$ ), and direct nonlinear ( $S_D$ ) predictions after McCabe and Sheil (2015); Nonlinear,  $L/D = 25$ ,  $s/D = 3$ , rigidly-capped floating pile group



**Fig. 6** Comparison of FEA and IFM predictions of the total interaction experienced by a centre group pile; LE,  $L = 40$  m,  $E_s = 24.5$  MPa,  $E_p = 19600$  MPa,  $s = 4$  m,  $D = 1$  m,  $v_p = 0.25$ ,  $v_s = 0.45$

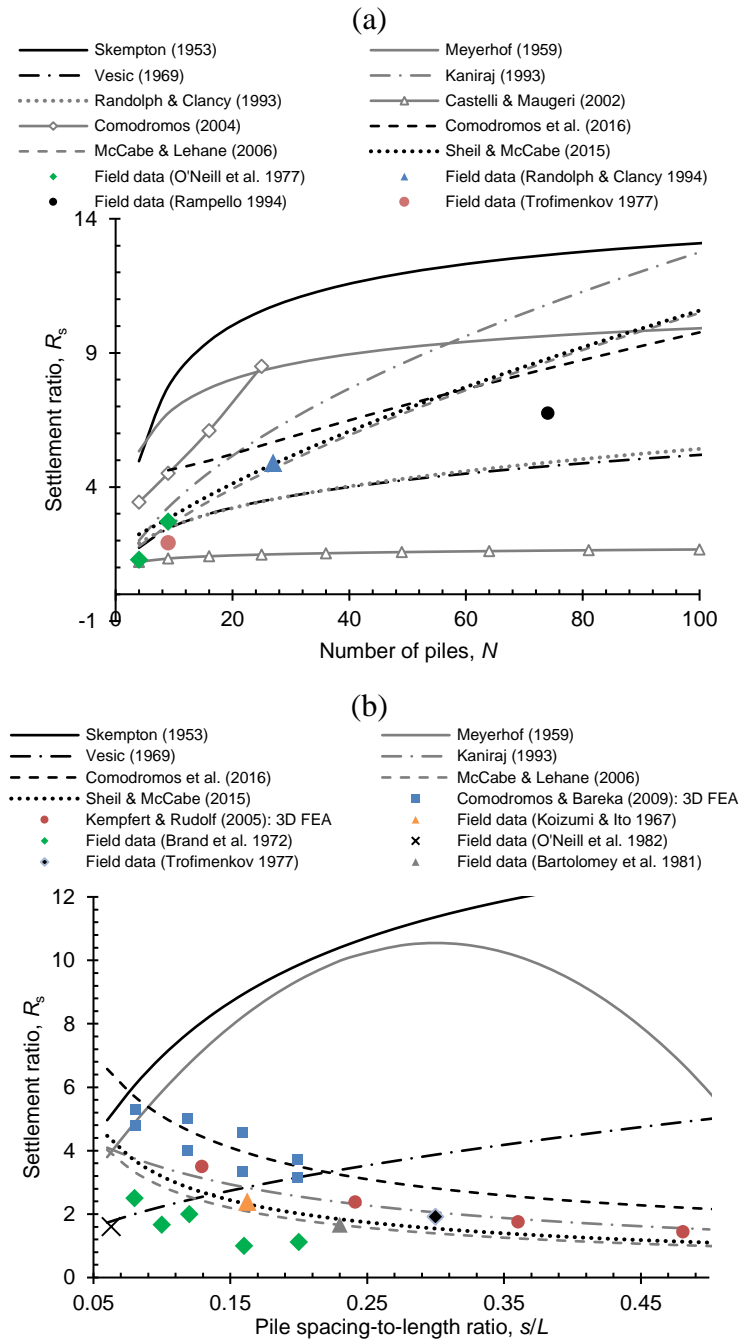


**Fig. 7** Illustration of (a) two-pile and (b) pile group geometry (only groups of up to  $N = 25$  piles shown for clarity)

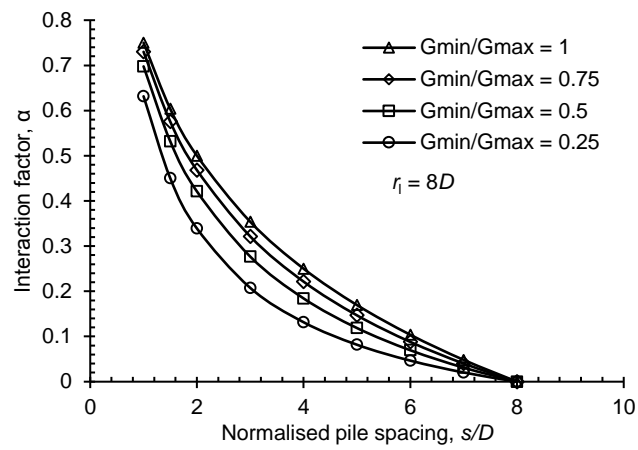


**Fig. 8** Influence of intervening free-headed (non-loaded) group piles on two-pile interaction factor using Approach I;  $L = 40$  m,  $E_s = 24.5$  MPa,  $E_p = 19600$  MPa,  $s = 4$  m,  $D = 1$  m,  $\nu_p = 0.25$ ,  $\nu_s = 0.45$

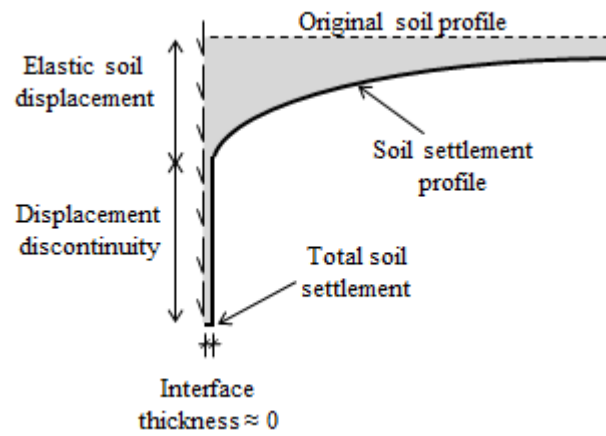




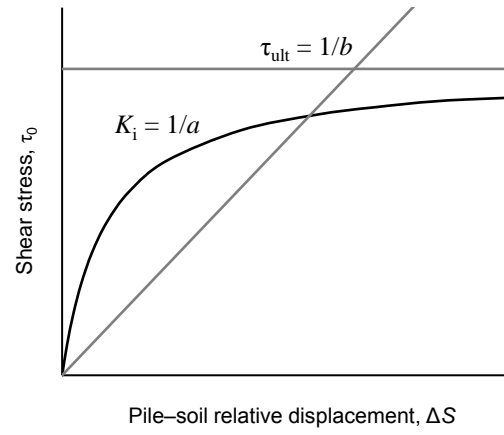
**Fig. 9** Comparison of settlement ratio predictions determined using existing empirical approaches: influence of (a) number of piles with common spacing  $s = 3.0 D$  ( $L/D = 25$ ), (b) pile spacing-to-length ratio for a  $3 \times 3$  group layout ( $L/D = 25$ )



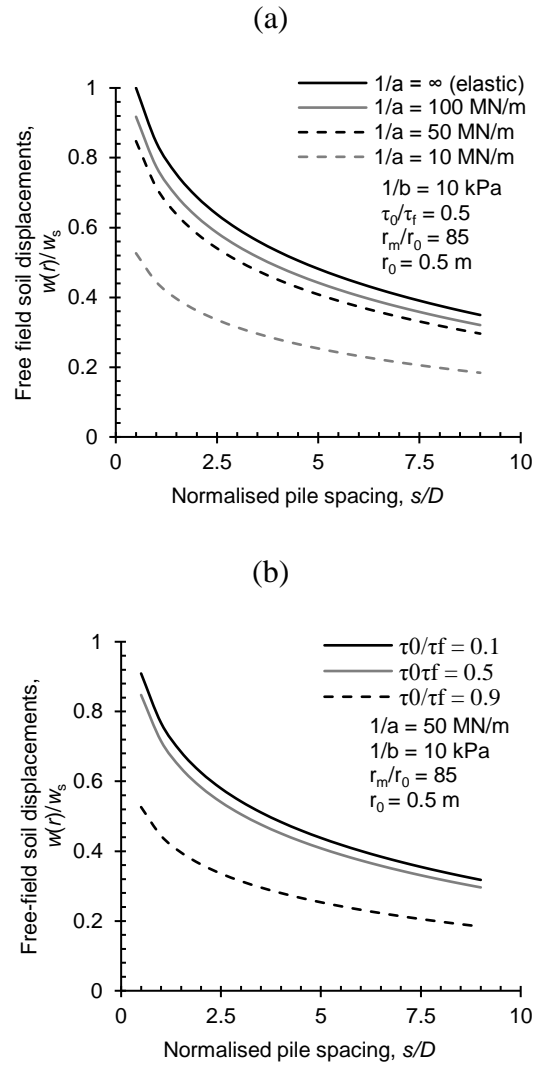
**Fig. 10** Influence of reduced 'near-pile' modulus on  $\alpha$  (after Costanzo and Lancellotta 1998)



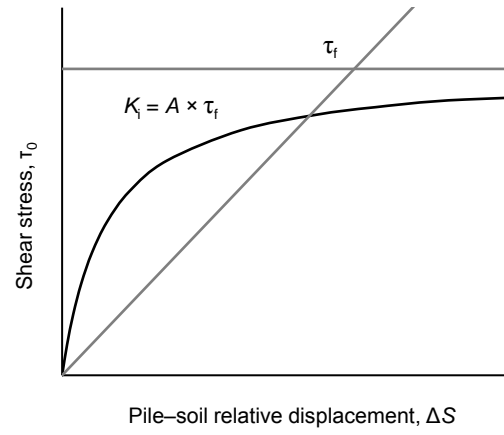
**Fig. 11** Illustration of displacement discontinuity concept adopted by Lee and Xiao (2001)



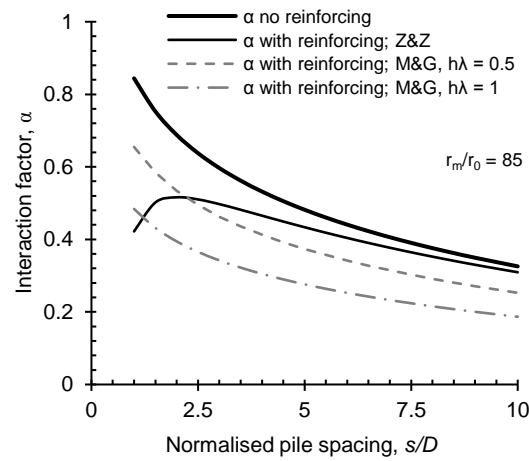
**Fig. 12** Hyperbolic relationship between shear stress and relative displacement at pile-soil interface adopted by Lee and Xiao (2001)



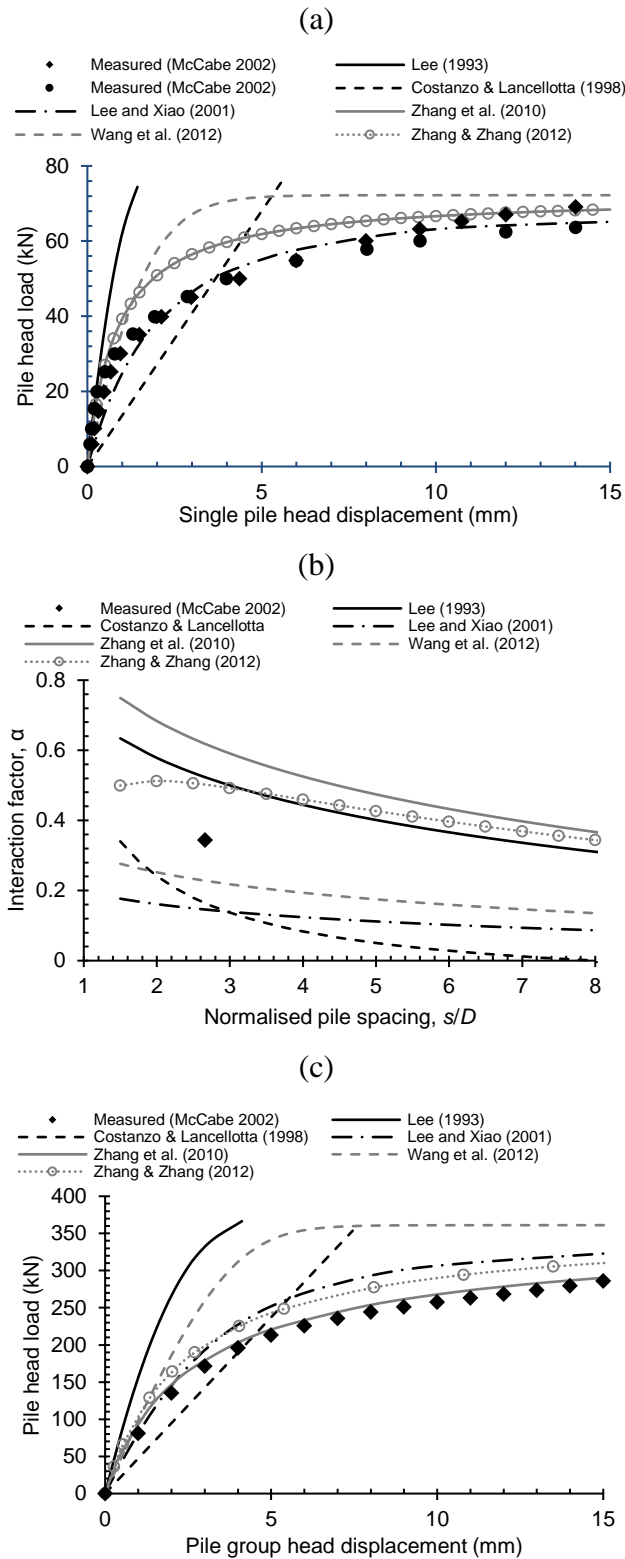
**Fig. 13** Normalised free-field soil displacements surrounding a loaded single pile (after Lee and Xiao 2001): (a) influence of parameter  $a$ , (b) influence of load level



**Fig. 14** BoxLucas1 relationship between shear stress and relative displacement at pile-soil interface adopted by Wang et al. (2012)

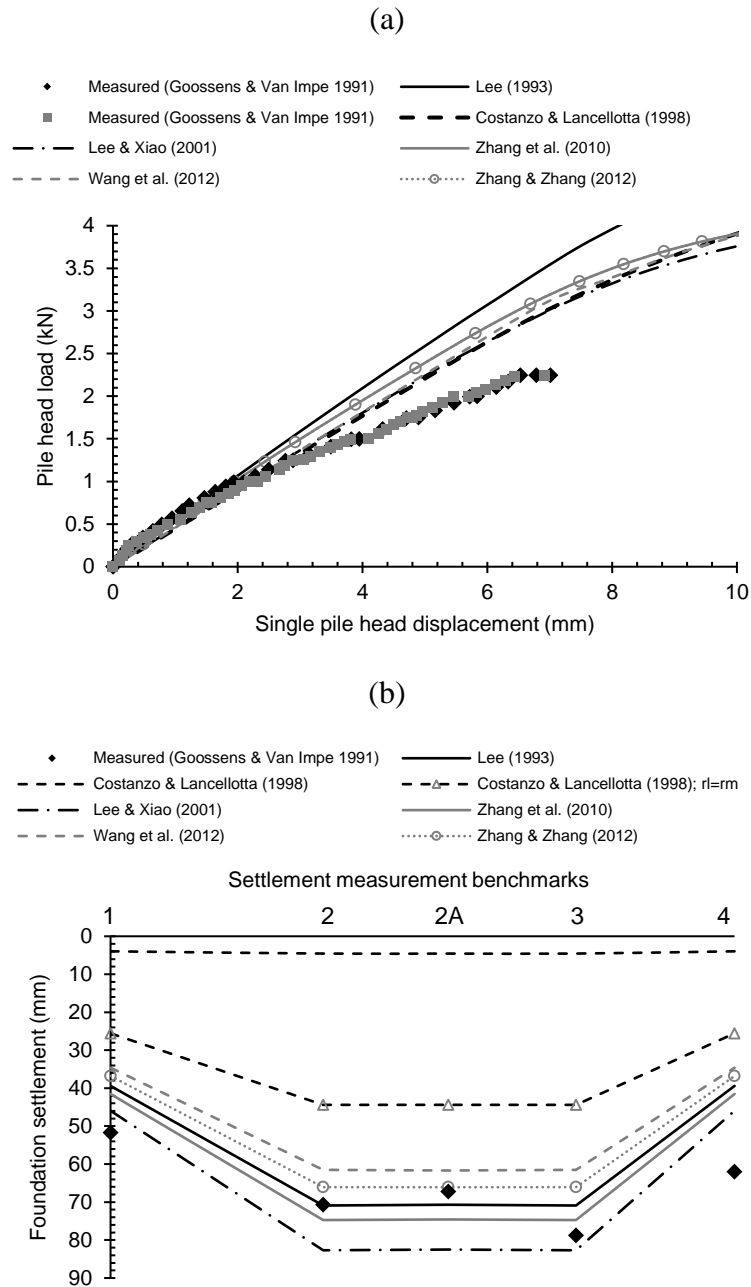


**Fig. 15** Comparison of Zhang and Zhang (2012; ‘Z&Z’) simplified model for receiver pile reinforcing effects to that proposed by Mylonakis and Gazetas (1998, ‘M&G’)

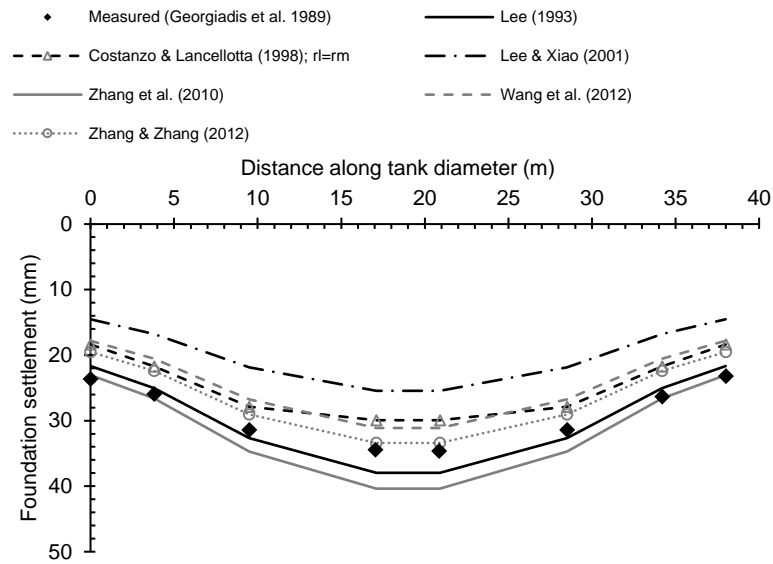


**Fig. 16** Comparison of selected analytical approaches to Belfast case history: (a) single pile load-displacement response, (b) two-pile interaction factors (load factor = 0.5), (c) five-pile group load-displacement response; tension loading





**Fig. 17** Comparison of selected analytical approaches to Ghent silos case history: (a) single pile load test, (b) tank settlement distribution across the length of the foundation two years after construction



**Fig. 18** Comparison of selected analytical approaches to Thessaloniki storage tanks case history: settlement distribution across diameter of foundation