

1 **COMPUTATIONAL FLUID DYNAMICS AND ITS APPLICATIONS IN**
2 **ECHINODERM PALAEOBIOLOGY**

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10 **ABSTRACT.**—Computational fluid dynamics (CFD), which involves using computers to
11 simulate fluid flow, is emerging as a powerful approach for elucidating the palaeobiology of
12 ancient organisms. Here, I describe its applications for studying fossil echinoderms. When
13 properly configured, CFD simulations can be used to test functional hypotheses in extinct
14 species, informing on aspects such as feeding and stability. They also show great promise for
15 addressing ecological questions related to the interaction between organisms and their
16 environment. CFD has the potential to become an important tool in echinoderm
17 palaeobiology over the coming years.

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19 **KEYWORDS.**—computational fluid dynamics; echinoderms; palaeobiology; function;
20 ecology.
21

22 **INTRODUCTION**

23 Echinoderms exhibit a plethora of morphological and behavioural adaptations to life in
24 moving fluids. For example, the slot-like holes (lunules) that pass through the test in many
25 sand dollars serve to reduce lift and thereby increase resistance to dislodgement (Telford,

26 1983), while at the same time drawing food-laden water up from the substrate (Alexander &
27 Ghiold, 1980). Moreover, stalked crinoids bend the proximal-most part of the stalk and crown
28 downcurrent, with the arms arranged into a fan in order to improve particle capture during
29 suspension feeding (Macurda & Meyer, 1974; Baumiller, 2008). Laboratory experiments and
30 field observations of living organisms enable us to better understand how extant echinoderms
31 interact with fluid flows (e.g. Macurda & Meyer, 1974; Alexander & Ghiold, 1980; Telford,
32 1983; Messing et al., 1988; Baumiller et al., 1991; Loo et al., 1996; Thompson et al., 2005;
33 Holtz & MacDonald, 2009; Cohen-Rengifo et al., 2018), but for fossil taxa, especially those
34 lacking a modern analogue, methods of investigation are more limited. Flume studies have
35 been used to explore the feeding and hydrodynamics of extinct echinoderms based on
36 physical models of fossil organisms, both historically (e.g. Welch, 1978; Baumiller &
37 Plotnick, 1989; Riddle, 1989; Parsley, 1990; Friedrich, 1993; Daley, 1996) and more recently
38 (e.g. Huynh et al., 2015; Parsley, 2015). However, given the increasing availability of three-
39 dimensional, digital models of fossil echinoderms (e.g. Rahman & Zamora, 2009; Zamora &
40 Smith, 2012; Zamora et al., 2012; Waters et al., 2015; Briggs et al., 2017; Clark et al., 2017;
41 Reich et al., 2017; Saulsbury and Zamora, 2019; Bauer et al., 2019; Rahman et al., 2019),
42 virtual modelling approaches have great potential for analysing the palaeobiology of extinct
43 forms.

44 One of the most promising approaches for interrogating function and ecology in
45 ancient organisms is computational fluid dynamics, or CFD. This is a tool for simulating
46 flows of fluids, such as water or air. Computers solve the governing equations that describe
47 fluid motions and their interactions with boundaries. In this way, fluid flows can be simulated
48 for digital models of solid objects. CFD is routinely used in engineering to analyse design and
49 optimize performance for structures and machines. Furthermore, in the past 10–15 years, it
50 has become increasingly important in palaeontology (Rahman, 2017). Among the first to

51 apply CFD to fossils were Rigby & Tabor (2006), who simulated water flow around digital
52 models of graptolites. Shiino and colleagues subsequently applied the technique to
53 brachiopods (Shiino et al., 2009; Shiino & Kuwazuru, 2010, 2011) and trilobites (Shiino et
54 al., 2012, 2014). More recently, CFD has been used to study extinct vertebrates (Bourke et
55 al., 2014, 2018; Kogan et al., 2015; Liu et al., 2015; Wroe et al., 2018; Dec, 2019; Gutarra et
56 al., 2019; Troelsen et al., 2019), Ediacaran organisms (Rahman et al., 2015a; Darroch et al.,
57 2017; Gibson et al., 2019), ammonoids (Hebdon et al., 2020) and fossil echinoderms
58 (Rahman et al., 2015b, in press; Dynowski et al., 2016; Waters et al., 2017).

59 In this paper, I introduce some basic principles of fluid dynamics and describe the key
60 steps in a palaeontological CFD study. I also discuss the applications of CFD to extinct
61 echinoderms, highlighting recent work on cinctans (Rahman et al., 2015b), stalked crinoids
62 (Dynowski et al., 2016) and blastoids (Waters et al., 2017). I end by considering possible
63 future directions in this area, including new avenues of research that could improve our
64 understanding of echinoderm palaeobiology.

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FLUID DYNAMICS

67 The discipline of fluid mechanics is the branch of physics that deals with fluids and the forces
68 acting on them. It can be further subdivided into fluid statics and fluid dynamics, the latter of
69 which is concerned with fluid flows and thus relevant for understanding the interaction
70 between living organisms and moving fluids. Three conservation laws that must be satisfied
71 in fluid dynamics are the conservation of mass, the conservation of momentum and the
72 conservation of energy. Additionally, it is assumed that fluids can be treated as continuous
73 substances (the continuum assumption), rather than being composed of discrete molecules.
74 Applying these laws to the volume through which fluid will flow, by expressing them in

75 terms of mathematical equations, allows us to calculate properties such as flow velocity and
76 pressure as functions of space and time, thereby solving problems in fluid dynamics.

77 Water is treated as an incompressible Newtonian fluid, with density and viscosity
78 assumed to be constant. The fluid velocity is zero at all solid boundaries (no-slip condition)
79 and increases with distance from the boundary, giving a velocity gradient (the boundary
80 layer). Where the viscous forces are relatively large, the fluid flows orderly in parallel layers,
81 with little or no mixing (i.e. laminar flow). In contrast, where the inertial forces dominate,
82 fluid flow is characterized by chaotic motion and the formation of unsteady vortices (i.e.
83 turbulent flow). The dimensionless Reynolds number (Re) describes the ratio of inertial to
84 viscous forces, and is defined as:

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$$86 \quad Re = \frac{\rho UL}{\mu}$$

87

88 where ρ is the density of the fluid, U is the characteristic velocity, L is the characteristic
89 dimension and μ is the dynamic viscosity of the fluid. For flow through closed conduits (e.g.
90 pipes), the characteristic dimension is typically the diameter of the conduit, whereas for flow
91 around objects, it is usually the width or length of the object. Low Re indicates the flow is
92 mostly laminar, while high Re is indicative of predominantly turbulent flow; however, the
93 critical Reynolds numbers over which flow transitions from laminar to turbulent will vary
94 depending on the geometry. Flows with geometrically similar objects (i.e. scaled versions of
95 the same shape in the same orientation) and the same Re are said to have dynamic similarity
96 (assuming the Womersley number, which describes pulsatile flow frequency, is also
97 constant), meaning the fluid flows will be identical.

98 Drag is the force that acts opposite to the relative motion of an object in fluid (i.e.
99 parallel to the flow direction). It is dependent on the properties of the fluid and the geometry

100 of the object. The dimensionless drag coefficient (C_D) relates the drag force to the fluid
101 density, velocity and object geometry, and is defined as:

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$$103 \quad C_D = \frac{2F_D}{\rho U^2 A}$$

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105 where F_D is the drag force exerted by the fluid, ρ is the density of the fluid, U is the
106 characteristic velocity and A is the characteristic area (commonly the projected frontal area,
107 wetted surface area or total surface area of the object). C_D can be used to compare the
108 performance of different geometries at the same Re , assuming the boundary conditions are
109 consistent.

110 Lift is the force that acts perpendicular to the flow direction. Similar to drag, it varies
111 with the fluid properties and object geometry. The lift coefficient (C_L) is defined as:

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$$113 \quad C_L = \frac{2F_L}{\rho U^2 A}$$

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115 where F_L is the lift force exerted by the fluid, ρ is the density of the fluid, U is the
116 characteristic velocity and A is the characteristic area (typically the plan area).

117 The governing equations of fluid flow include the Navier–Stokes equations, which
118 describe the motion of the fluid, and the continuity equation, which represents the
119 conservation of mass. These equations can be simplified to make them easier to solve.

120 Nevertheless, for all but the simplest problems, the equations must be solved numerically on
121 a computer. This can be done by splitting up the flow domain into smaller cells, with the
122 governing equations discretized and solved in each of these cells. This approach is termed
123 computational fluid dynamics.

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STEPS IN COMPUTATIONAL FLUID DYNAMICS

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Computational fluid dynamics dates back to the 1950s and 1960s, when the first computer

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simulations of fluid flows were undertaken (e.g. Evans & Harlow, 1957; Harlow &

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Welch, 1965; Hess & Smith, 1967). It has subsequently been used to address problems in a

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wide range of subjects, including palaeontology (Rahman, 2017). In many cases, the same set

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of steps, outlined below, is followed.

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The first step in a palaeontological CFD study is to construct a digital model of the

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organism of interest. For an increasing number of extinct groups, three-dimensional virtual

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reconstructions of fossil specimens already exist. However, additional work to digitally

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correct taphonomic distortion and restore the original morphology of the organism (e.g.

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Lautenschlager, 2016) might be required. An alternative approach is to create digital models

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through box or NURBS modelling. This allows models to be constructed for taxa where

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complete, three-dimensionally preserved fossil specimens are not available, but is more

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subjective than tomographic or surface-based methods (Rahman & Lautenschlager, 2017).

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In CFD simulations of flow around an organism, the computational domain

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surrounding the modelled organism must also be created. For three-dimensional models, this

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will typically consist of a cuboid or cylinder. The domain should be large enough to ensure

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full development of the flow around the model. A domain that extends three times the length

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of the model upstream, ten times the length of the model downstream and five times the size

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of the model in all other directions can be taken as a starting point. However, the optimal

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domain size will vary on a case-by-case basis, and sensitivity analyses should be undertaken

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to establish the most appropriate size (see below).

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Next, the domain is divided into a number of discrete cells (the mesh; Fig. 1A). The

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mesh is commonly made up of tetrahedral or hexahedral elements, with layers of prismatic

149 elements at the fluid–solid interface to model the boundary layer. Increasing the number of
150 mesh elements can improve the accuracy of the simulation, but will increase the memory
151 requirements and computation time. Similar to the domain size, sensitivity analyses should be
152 carried out to determine the optimal mesh size.

153 The material properties of the fluid, such as density and viscosity, must be specified.
154 The flow model is then selected, which establishes the governing equations that will need to
155 be solved in the simulation. The choice of model depends on the flow regime, which is
156 indicated by the Reynolds number (see above). Laminar flow can be described by the
157 Navier–Stokes equations, but turbulent flows are more complex and so time-averaged
158 equations of fluid motion (the Reynolds-averaged Navier–Stokes, or RANS, equations) and a
159 turbulence closure model are generally used. Various turbulence models exist, with the k - ϵ
160 and shear stress transport (SST) models the most widely used in palaeontological CFD
161 analyses.

162 Following selection of the flow model, boundary conditions representing the flow
163 variables are specified (Fig. 1B, C). These include an inlet describing how flow enters the
164 domain and an outlet that defines how it exits. Commonly, a velocity inlet and zero pressure
165 outlet are used. For simulations of flow around a stationary organism, the inlet conditions will
166 be informed by the current velocity, which can be inferred based on sedimentological
167 characteristics (e.g. Stow et al., 2009) and/or direct measurements made in analogous modern
168 environments (e.g. Emelyanov, 2005; Siedler et al., 2013). A no-slip boundary condition is
169 often assigned to all solid surfaces (e.g. the model of the organism and the seafloor), meaning
170 the fluid has zero velocity relative to the boundary. A slip boundary condition can be used for
171 the remaining edges of the domain, allowing the flow to pass along these boundaries without
172 friction.

173 When all the aforementioned steps have been completed, fluid flow is simulated by
174 solving the discretized equations. This can be done using direct solvers, which are
175 computationally expensive, or (more frequently) iterative solvers, which use less memory and
176 can therefore reduce computation time. For steady flows, which do not vary temporally, a
177 stationary solver is used to obtain a solution. However, for unsteady flows, where the flow
178 properties change over time, a computationally much more expensive time-dependent solver
179 must be used.

180 CFD results are visualized and analysed in various ways. For example, plots of
181 velocity magnitude supplemented with streamlines can be produced to study patterns of fluid
182 flow around the modelled organism (Fig. 1D, E). Furthermore, drag and lift forces and their
183 coefficients (see above) can be calculated to evaluate the forces exerted by the fluid on the
184 organism. Testing the sensitivity of these results to simulation parameters, in particular the
185 domain and mesh sizes, is a key part of the study. The size of the domain should be varied to
186 determine the smallest possible domain that produces results matching theoretical
187 expectations of flow development. Similarly, mesh independence must be established by
188 undertaking simulations with different mesh sizes and identifying the coarsest mesh that did
189 not substantially alter the results.

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191 **EXAMPLES IN ECHINODERM PALAEOBIOLOGY**

192 Prior to CFD becoming part of the palaeontologist's toolkit, studies of the hydrodynamics of
193 fossil echinoderms relied primarily on experiments in flume tanks. Crinoids were an initial
194 focus of this work. Welch (1978) introduced life-size models of the Carboniferous camerate
195 *Pterotocrinus* into a flume, performing experiments with models at three different
196 orientations to the current. The results demonstrated that redirection of water flow to the
197 filtration fan was strongest when the models were orientated with the fan perpendicular to the

198 current direction and the ambulacral side downcurrent (Fig. 2A), similar to the feeding
199 posture of extant stalked crinoids. Building on this, Baumiller & Plotnick (1989) carried out
200 experiments for models of *Pterotocrinus* with and without the wing-like tegminal
201 appendages. This showed that the models with wing plates rotated into a position with the
202 ambulacral side of the fan pointed downcurrent. Riddle (1989) placed fossil specimens and
203 models of crinoid columns in a recirculating flow tank. He found that the models with
204 helically-twisted columns, as seen in some platycrinids, deflected water strongly upwards
205 (Fig. 2B), towards where the filtration apparatus would have been located in the living
206 animal. Baumiller (1990) conducted experiments using models of batocrinids with and
207 without an anal tube. This revealed that the models with an anal tube reduced flow from the
208 anus to the feeding appendages.

209 This experimental approach was also extended to other extinct echinoderm groups.
210 Parsley (1990) studied flow around models of the diploporitan *Aristocystites*, orientated with
211 the aboral end of the theca facing into the current. He was able to show that vortices were
212 generated downcurrent of the oral end, transporting particles to the ambulacra. A similar
213 pattern was documented for cinctans by Friedrich (1993), who found that the models
214 orientated with the stele facing upcurrent created back eddies that brought particles towards
215 the mouth and marginal grooves. Daley (1996) undertook flume experiments using a model
216 of the solute *Coleicarpus sprinklei*, which revealed that turbulence was created around the
217 single feeding appendage when the model was positioned close to the substrate. Fluid flow in
218 blastoid respiratory structures was investigated by Huynh et al. (2015) using a 72x scale
219 model of part of the hydrospire of *Pentremites rusticus*. They observed that there was no
220 mixing of water taken in through incurrent hydrospire pores within the associated hydrospire
221 folds (Fig. 2C). Most recently, Parsley (2015) examined flow around models of the
222 eocrinoids *Globoeocrinus*, *Guizhoueocrinus* and *Sinoeocrinus* in a flume tank. The results

223 showed that the modelled brachioles were distally bent downcurrent by the flow, forming an
224 open fan.

225 CFD has considerable potential for expanding on this existing base of experimental
226 work, enabling analyses of a wider range of model geometries and flow conditions. However,
227 to date, only a few studies have applied the technique to fossil echinoderms. Rahman et al.
228 (2015b) used the approach to explore the hydrodynamics of feeding in cinctans. Owing to
229 their highly unusual body plan, which has no analogue among extant taxa, it is debated
230 whether cinctans were passive suspension feeders (e.g. Parsley, 1999; David et al., 2000) or
231 active filter feeders (e.g. Smith, 2005; Zamora & Smith, 2008). CFD was used to test between
232 these competing hypotheses. A digital model of the cinctan *Protocinctus mansillaensis*,
233 created from an X-ray microtomography scan of the holotype (Rahman & Zamora, 2009),
234 was placed in a virtual flume tank. Computer simulations of water flow were performed at
235 inlet velocities of 0.05, 0.1 and 0.2 m/s, chosen to represent typical current velocities in the
236 offshore environments inhabited by *Protocinctus* (Álvaro & Vennin, 1997). Models were
237 positioned at different orientations and burial depths, and passive and active feeding
238 scenarios were simulated by varying the boundary conditions at the main body openings. The
239 results showed that in all cases the models positioned with the mouth downcurrent and the
240 ventral swelling buried generated the least drag and lift, suggesting this position was optimal
241 for enhancing stability. Moreover, in this orientation there was very little flow to the mouth
242 and associated marginal groove in the simulations of passive feeding, demonstrating that such
243 a feeding strategy would have been an ineffective way of obtaining nutrients. Conversely,
244 there was strong flow to the mouth in the simulations of active feeding (Fig. 3A), indicating
245 that this was the most probable feeding mode and supporting previous interpretations of
246 cinctans as pharyngeal filter feeders (e.g. Smith, 2005; Zamora & Smith, 2008).

247 Dynowski et al. (2016) examined flow patterns for the Triassic stalked crinoid
248 *Encrinus liliiformis*. *Encrinus* had 10 relatively short and stiff arms, which are thought to
249 have been less flexible than extant forms, necessitating a different feeding posture (Ausich et
250 al., 1999). The functionality of this posture was investigated with CFD. First, digital models
251 with varied arm configurations were constructed. These were then used in computer
252 simulations of inlet velocities of 0.03, 0.14 and 0.5 m/s with models at different orientations
253 to flow, thereby approximating a shallow marine environment with rapidly changing current
254 velocities and directions, as inferred for *Encrinus* (Hagdorn, 1999). Lagrangian particle
255 tracking was used to simulate the trajectories of sub-millimetre particles suspended in the
256 flow, which were taken as representative of planktonic organisms. For validation, flow
257 around a physical model of the base geometry was evaluated in a recirculating flow tank
258 using particle image velocimetry. Comparison of CFD and flume experiments revealed only
259 small differences in the results, establishing the accuracy of the computer simulations. CFD
260 results for simulations of flow from the aboral side showed a zone of recirculation developed
261 downcurrent of the models, which transported particles back into the crown (Fig. 3B). In
262 contrast, simulations of flow from the oral and lateral sides did not create recirculation, but
263 instead resulted in direct transportation of particles into the crown. Thus, the feeding posture
264 of *Encrinus liliiformis* ensured it was able to feed effectively in environments characterised
265 by frequently changing flow conditions.

266 Waters et al. (2017) analysed the function of blastoid hydrospires. Previous studies of
267 fluid flow through these structures proposed that they were effective gas exchange surfaces
268 (Schmidtling & Marshall, 2010; Huynh et al. 2015), but this work assumed the hydrospires
269 were orientated vertically in life; instead, a posture with the hydrospires orientated
270 horizontally has been suggested to be the most common feeding strategy in blastoids
271 (Breimer & Macurda, 1972). Thus, CFD was used to evaluate hydrospire function in this

272 alternative reconstruction of blastoid living position. A digital model of the blastoid
273 *Monoschizoblastus rofei* was produced, with a legacy dataset of serial acetate peels used to
274 reconstruct the internal anatomy. Water flows with inlet velocities of 0.005, 0.02, 0.05 and
275 0.1 m/s were simulated around the model, which was orientated with the stem and theca bent
276 downcurrent and the hydrospires horizontal. Both passive and active flow through the
277 hydrospires were simulated by assigning different exit velocities to the excurrent orifice
278 (spiracle). The results showed that the simulations of passive flow resulted in significant
279 respiratory leakage, with most water exiting through the adoral-most hydrospire pores, rather
280 than the spiracle. However, in the simulations of active flow with excurrent velocities around
281 50% of the inlet velocity, flow largely exited through the spiracle with little leakage in other
282 parts of the hydrospires (Fig. 3C). This suggests that active cilia-driven water flow through
283 the hydrospires was important for efficient gas exchange, particularly in environments with
284 variable current velocities.

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286 **EMERGING APPLICATIONS AND FUTURE DIRECTIONS**

287 As noted above, CFD is not yet widely used in echinoderm palaeobiology. The case studies
288 outlined in the previous section exemplify the types of questions that can be addressed with
289 this approach (see Rahman, 2017 for further examples), demonstrating its potential utility.
290 Moreover, the availability of increasingly powerful computer hardware and software,
291 together with the growing number of virtual models of fossil echinoderms, provides a strong
292 foundation for conducting functional analysis using CFD. However, a solid understanding of
293 fluid mechanics is essential for those wishing to undertake this work, and close collaboration
294 with experts in the field will be beneficial for ensuring the accuracy of analyses.

295 Replicating and extending existing experimental studies represents a good starting
296 point for palaeontological CFD analyses. Where there is close agreement between the results

297 of laboratory experiments and CFD, this provides greater confidence in the accuracy of the
298 computer simulations. Additionally, because computer simulations are typically cheaper,
299 faster and more flexible than experiments in flume tanks, they can be used to expand such
300 studies to include a wider variety of flow parameters and model orientations. For example,
301 Waters et al. (2017) established the validity of their computational analyses by digitally
302 recreating the experiment performed by Huynh et al. (2015). They then extended this work by
303 carrying out simulations for a full model of the animal in an alternative living posture, using a
304 range of inlet velocities and different assumptions regarding passive and active flow rates.
305 Drawing inspiration from laboratory experiments in this manner will help demonstrate the
306 accuracy of CFD in palaeontology, while at the same time enhancing understanding of how
307 extinct echinoderms interacted with moving fluids.

308 CFD also offers great potential for testing functional hypotheses in fossil taxa.
309 Suspension feeding is especially amenable to this approach because it relies on flow to
310 feeding structures; the effectiveness of hypothesized feeding strategies in varied
311 environmental conditions can be evaluated by visualizing flow patterns for simulations of
312 different inlet velocities and model orientations (e.g. Shiino et al., 2009; Rahman et al.,
313 2015a, b; Dynowski et al., 2016; Darroch et al., 2017; Gibson et al., 2019). Alternatively,
314 hypotheses regarding the stability of an organism on the seafloor could be tested by
315 quantifying drag and lift forces experienced by models in different positions (e.g. Rahman et
316 al., 2015b; Darroch et al., 2017; Gibson et al., 2019). This hypothesis testing framework can
317 be extended further through comparative analyses of multiple taxa, both within and among
318 groups, thereby enabling the assessment of evolutionary patterns (e.g. Wroe et al., 2018;
319 Gutarra et al., 2019; Troelsen et al., 2019; Hebdon et al., 2020; Rahman et al., in press).
320 Furthermore, models of hypothetical morphologies could be created to investigate the
321 function of specific characters (e.g. Shiino & Kuwazuru, 2010; Shiino et al., 2012; Rahman et

322 al., 2015a; Darroch et al., 2017; Gutarra et al., 2019; Hebdon et al., 2020). Thus, previously
323 untestable hypotheses are now open to interrogation using CFD, facilitating more rigorous
324 studies of the relationship between form, function and evolution in fossil echinoderms.

325 Particle tracking is another area of considerable promise. This entails simulating the
326 motion of small particles within the flow, broadly equivalent to determining the trajectories
327 of seeding particles in experimental fluid mechanics. The technique provides a more accurate
328 representation of the path of individual particles than can be obtained with plots of flow
329 vectors and streamlines, and can be used to trace the movement of, for example, planktonic
330 organisms suspended in water (e.g. Dynowski et al., 2016). Virtually tracking particles in this
331 way could be particularly useful for investigating mechanisms of particle capture involved in
332 suspension feeding, or for exploring the dispersal of gametes and larvae.

333 Thus far, studies applying CFD to fossil echinoderms have used a smooth flat
334 boundary to represent the sediment surface, but this does not accurately reflect the
335 morphology of the seafloor. Bottom roughness, for instance, varies depending on the nature
336 of the substrate, and will influence flow close to the sediment–water interface (Souza &
337 Friedrichs, 2005). Future work could address this by incorporating values of surface
338 roughness into the no-slip boundary condition assigned to the lower surface of the domain
339 (e.g. Fig. 4A, B). Alternatively, seafloor morphology could be digitally modelled by using a
340 textured surface as the domain floor. This would allow for examination of how changes in
341 substrate type (e.g. those linked to the Cambrian substrate revolution; Bottjer et al., 2000;
342 Dornbos, 2006) influenced fluid flow within the boundary layer, providing insight into the
343 function and ecology of extinct species.

344 Lastly, with increasing computer power, CFD simulations incorporating multiple
345 models are becoming more feasible, opening up the possibility to investigate the
346 palaeoecology of populations and communities (e.g. Gibson et al., 2019). For example, the

347 possible advantages of aggregation (Lefebvre, 2007) could be evaluated through computer
348 simulations of flow around closely-spaced models (e.g. Fig. 4C). In addition, the importance
349 of tiering (Bottjer & Ausich, 1986; Dornbos, 2008) could be assessed using models reaching
350 different heights above the floor of the domain. While computationally challenging,
351 extending palaeontological CFD analyses to encompass virtual populations and communities
352 will be key for uncovering the complexity of past ecosystems.

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CONCLUSIONS

355 Echinoderm palaeontologists have always been interested in understanding how ancient
356 animals were adapted to life in moving fluids. Historically, experiments in flume tanks were
357 used to study the hydrodynamics of fossil forms. However, the recent growth of CFD in
358 palaeontology provides new opportunities for computational functional analysis. This
359 approach is enabling rigorous tests of long-standing hypotheses in extinct echinoderms, with
360 important ecological and evolutionary implications. Future improvements in computer power
361 will allow us to tackle increasingly complex questions, shedding light not only on the
362 palaeobiology of individual taxa, but also entire communities and ecosystems.

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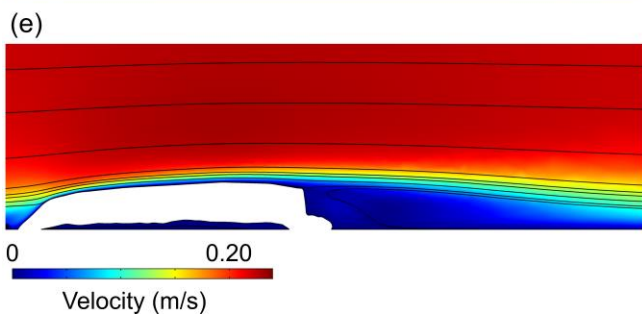
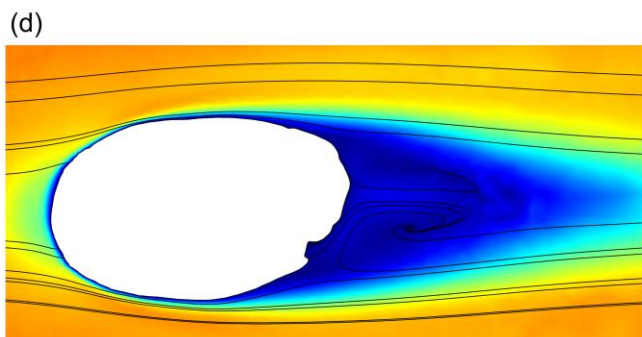
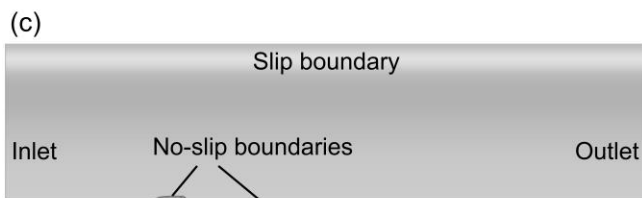
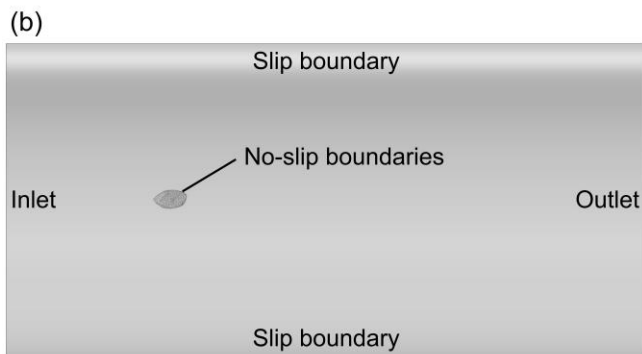
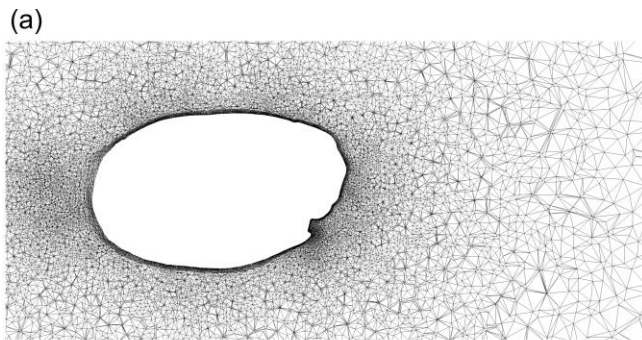
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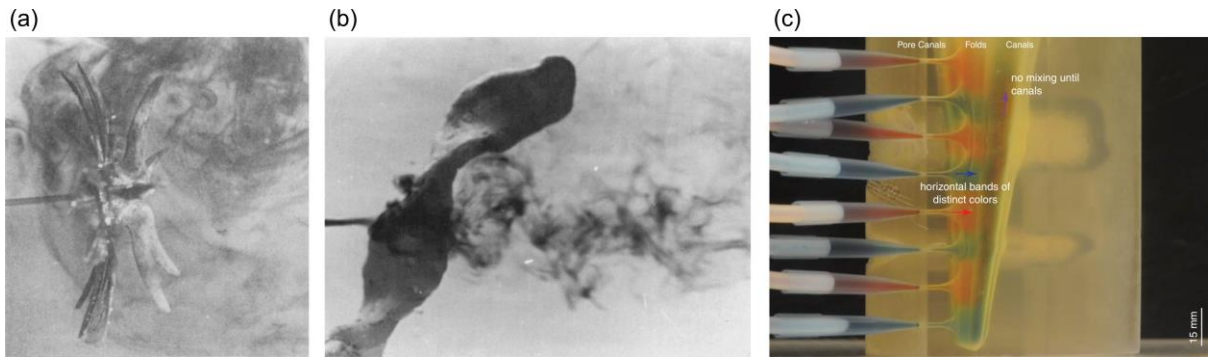
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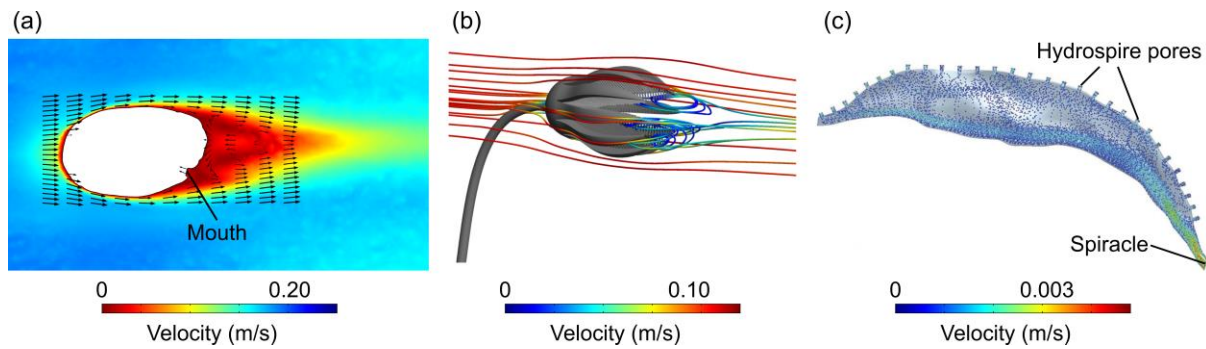
584 Figure 1. Steps in a palaeontological CFD study. Simulation of water flow around a model of
585 the cinctan *Protocinctus mansillaensis*. A, Two-dimensional plot (horizontal cross-section) of
586 the mesh. B, C, Computational domain (top-down and side-on views, respectively) showing

587 boundary conditions. D, E, Two-dimensional plots (horizontal and vertical cross-sections,
588 respectively) of flow velocity with streamlines. Direction of ambient flow from left to right.



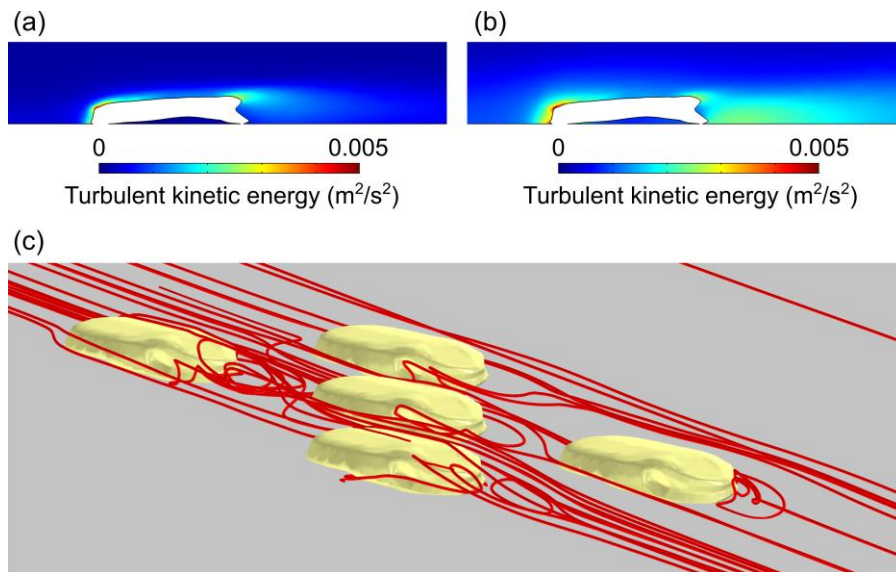
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590 Figure 2. Flume experiments of fossil echinoderms. A, Water flow around a model of the
591 crinoid *Pterotocrinus*. Modified from Welch (1978, fig. 3A), reproduced with permission
592 from Cambridge University Press. B, Water flow around a model of the column of the crinoid
593 *Platycrinites*. Modified from Riddle (1989, fig. 1.3), reproduced with permission from
594 Cambridge University Press. C, Water flow within a model of part of the hydropore of the
595 blastoid *Pentremites rusticus*. Modified from Huynh et al. (2015, fig. 4), reproduced under a
596 CC BY-NC-SA 4.0 license.



597

598 Figure 3. CFD analyses of fossil echinoderms. A, Two-dimensional plot (horizontal cross-
 599 section) of flow velocity with vectors from simulation of water flow around a model of the
 600 cinctan *Protocinctus mansillaensis* orientated with the mouth downcurrent, assuming active
 601 feeding. Direction of ambient flow from left to right. Modified from Rahman et al. (2015, fig.
 602 2i), reproduced with permission from the Royal Society. B, Three-dimensional plot with
 603 pathlines from simulation of water flow around a model of the crinoid *Encrinus liliiformis*
 604 orientated with the stalk and crown bent downcurrent. Direction of ambient flow from left to
 605 right. Modified from Dynowski et al. (2016, fig. 10A), reproduced under a CC BY 4.0
 606 license. C, Three-dimensional plot of flow velocity within the hydrospire from a simulation
 607 of water flow around a model of the blastoid *Monoschizoblastus rofei* orientated with the
 608 stem and theca bent downcurrent, assuming active flow. Direction of ambient flow from left
 609 to right. Modified from Waters et al. (2017, fig. 5.5), reproduced with permission from
 610 Cambridge University Press.



611

612 Figure 4. Future directions in CFD analyses. A, B, Two-dimensional plots (vertical cross-
 613 sections) of turbulent kinetic energy from simulations of water flow around a model of the
 614 cinctan *Protocinctus mansillaensis*, with equivalent sand roughness heights of 0 (A) and 0.01
 615 m (B) applied to the lower surface of the domain. Direction of ambient flow from left to
 616 right. C, Three-dimensional plot with streamlines from simulation of water flow around five
 617 closely-spaced models of the cinctan *Protocinctus mansillaensis*. Direction of ambient flow
 618 from top left to bottom right.