

Supporting Information for ”Combination of decadal predictions and climate projections in time: challenges and potential solutions”

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1. Description of variance inflation method (VINf)

The simple calibration technique, called the variance inflation method (VINf), following Doblas-Reyes, Hagedorn, and Palmer (2005), which has been recently applied to large-ensemble projections (O'Reilly et al., 2020) is used here. The uncalibrated (original) ensemble can be expressed as

$$X_{uncalibrated}(t, m) = X_{ens-mean}(t) + X_{ens-anom}(t, m) \quad (1)$$

In this formula, t and m indicate the dependence on time and ensemble member. A calibrated ensemble $X_{calibrated}$ can be obtain by:

$$X_{calibrated}(t, m) = \alpha X_{ens-mean}(t) + \beta X_{ens-anom}(t, m) \quad (2)$$

with α and β as

$$\alpha = \rho \frac{\sigma_{obs}}{\sigma_{ens-mean}} \quad (3)$$

$$\beta = \sqrt{1 - \rho^2} \frac{\sigma_{obs}}{\sigma_{ensemble}} \quad (4)$$

Here ρ is the linear Pearson correlation coefficient between the observations and the ensemble mean, σ_{obs} the standard deviation of the observations, $\sigma_{ens-mean}$ the standard deviation of the uncalibrated ensemble mean and $\sigma_{ensemble}$ the square root of the mean variance of the uncalibrated ensemble members. The resulting calibrated ensemble is per construction reliable in the sense that the root-mean-square-error matches the en-

semble spread (Fortin et al., 2014). In this study, the VINF method has been applied to the climate projection MME from 1970 to 2014 and separately for each lead year to the decadal prediction MME. The ensemble median of HadCRUT5 is used as a reference/observational dataset, which is a blended product of the CRUTEM5 land-surface air temperature dataset and the HadSST4 sea-surface temperature (SST) dataset (Morice et al., 2021). In accordance with model data, anomalies are calculated to the 1970 until 2014 average.

2. Description of model weighting method

The fundamental idea of model weighting approaches is that a models' future projection is assigned a weight based on the models' ability to reproduce observations in the past (Abramowitz et al., 2019). Applying such weights has been used to quantify model uncertainty for many different applications, including future changes of temperature, precipitation, sea ice, and ozone at different scales from local to global (Massonnet et al., 2012; Knutti et al., 2017; Lorenz et al., 2018; Brunner et al., 2019; Amos et al., 2020; Brunner et al., 2020; Merrifield et al., 2020). Here an adaptation of such a method is described which is used to investigate if weighting can help to reduce inconsistencies when concatenating predictions and projections.

Typically, model weights are based on multiple metrics relevant to the variable of interest to assess if a model is 'fit for purpose' and to avoid overconfident weighting (Lorenz et al., 2018). Here, we generalise the weighting to assign weights not only to model projections but also, lead-year depended, to predictions. The weights are based on five metrics, which are calculated individually for each of the regions investigated. These metrics are

chosen to be generally relevant for our target but not individually tailored to each of the regions, leaving room for improvement. We use (1) the area-weighted mean of the root-mean-squared-distance (RMSD) between model and observation time-series from all grid cells in each region (temperature and precipitation), (2) the area-weighted RMSD of the model and observation standard deviations over time (temperature and precipitation), and (3) the area-weighted RMSD of the model and observation linear trends in time (temperature). The metrics are calculated separately for each prediction lead time and the projections, normalised by the median over all models, and combined to generalised distances. In earlier applications these distances were then translated into weights, for example, by using a Gaussian weighting function scaled by a performance shape parameter (Brunner et al., 2020). However, the use of only seven models in this study means that no perfect model test (which needs several tens of models) can be performed and therefore no objective shape parameter can be established to translate distances to weights. Instead we use the simpler approach of just calculating the weights as the inverse distance as stated in the main manuscript.

Table S1. Decadal prediction (dcppA-hindcasts) and climate projections datasets.

Institution	Model	Member (dcppA)	Member (historical)	Reference
CCCma	CanESM5	20 (i1)	20	Sospedra-Alfonso et al. (2021)
EC-Earth-Consortium	EC-Earth3	10 (i1)	10	Bilbao et al. (2021)
IPSL	IPSL-CM6A-LR	10 (i1)	10	Haarsma et al. (2020)
MIROC	MIROC6	10 (i1)	10	Boucher et al. (2020)
MOHC	HadGEM3-GC31-MM	10 (i1)	4	Kataoka et al. (2020)
MPI-M	MPI-ESM1-2-HR	10 (i1)	10	Tatebe et al. (2019)
NCC	NorCPM1	10 (i1) 10 (i2)	20	Andrews et al. (2020)
				Williams et al. (2018)
				Müller et al. (2018)
				Mauritsen et al. (2019)
				Bethke et al. (2021)

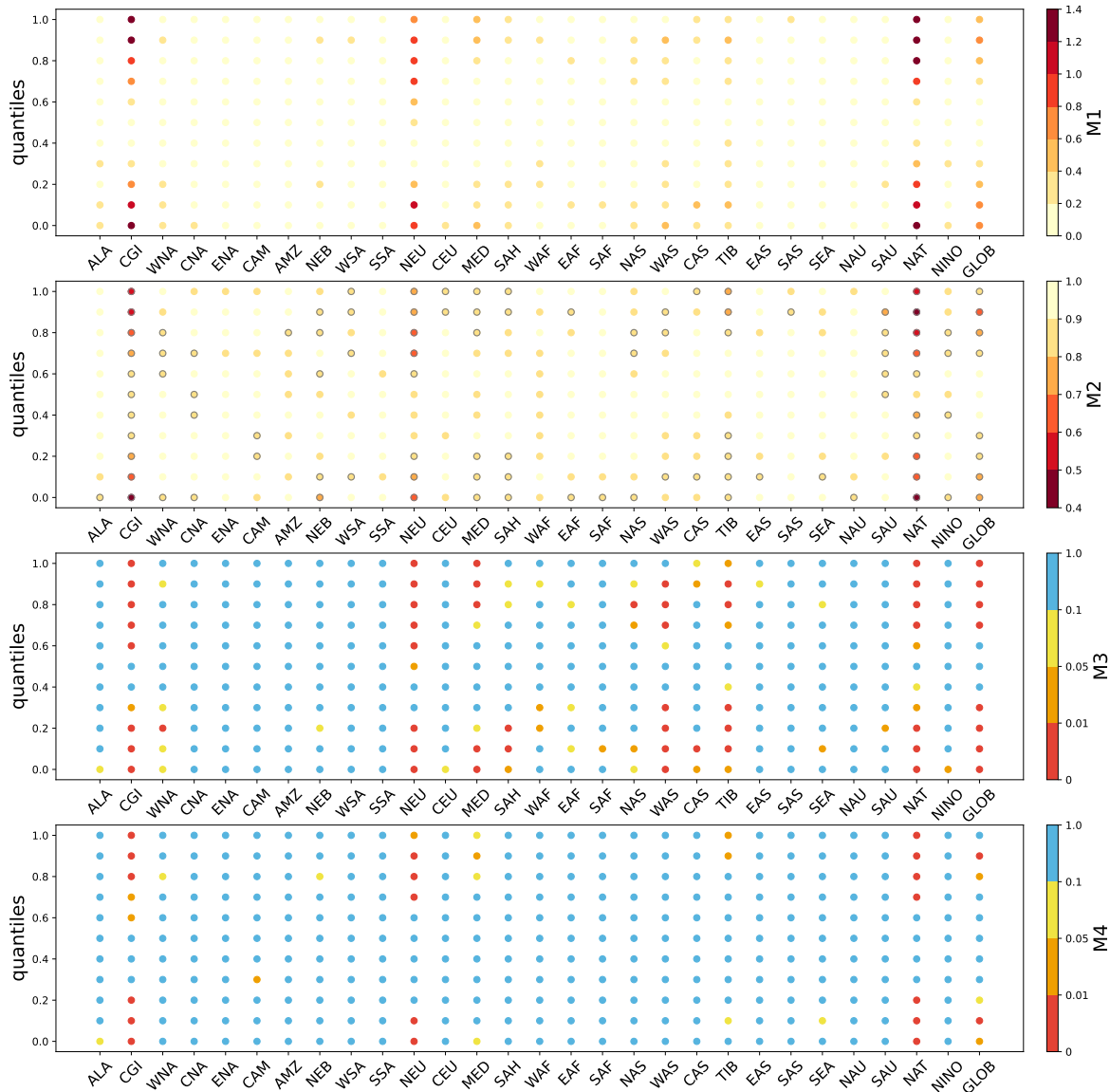


Figure S1. Results for metrics M1 to M4 when concatenating decadal predictions after forecast year ten and climate projections. The circles in M2 indicate those values which are significantly different to the 10th percentile of randomly sampled *baseline* distribution overlaps.

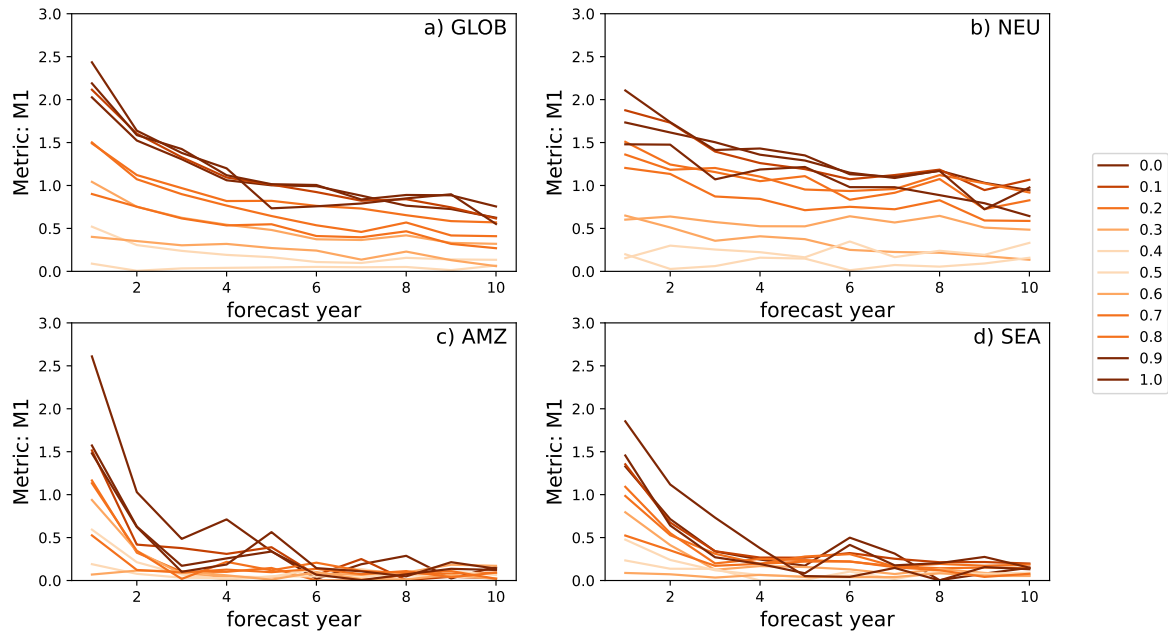


Figure S2. Results for Metric M1 when using different forecast years to concatenate decadal predictions and climate projections for a) global SAT, b) Northern Europe SAT, c) Amazon SAT and d) South East Asia (SEA) SAT. Colors represent different quantiles of the MME.

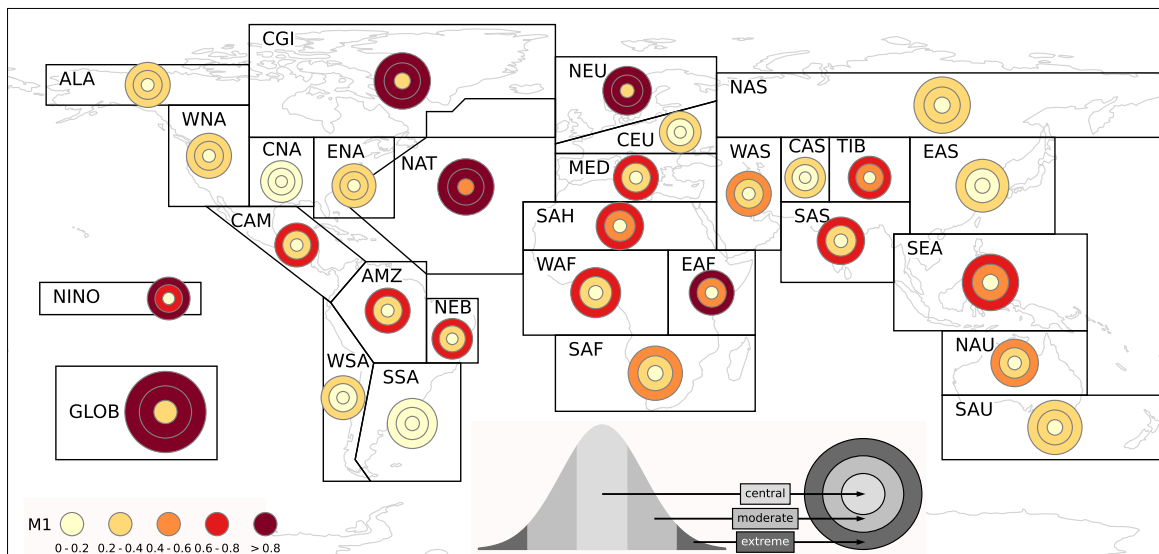


Figure S3. As Figure 3a but when concatenating decadal predictions and climate projections after forecast year 2.

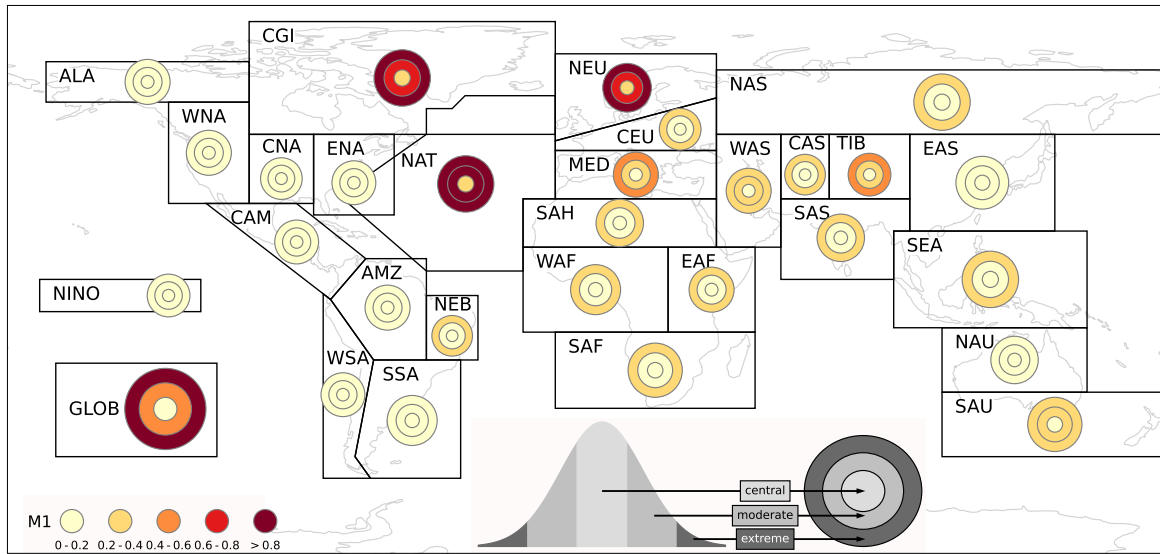


Figure S4. As Figure 3a but when concatenating decadal predictions and climate projections after forecast year 7.

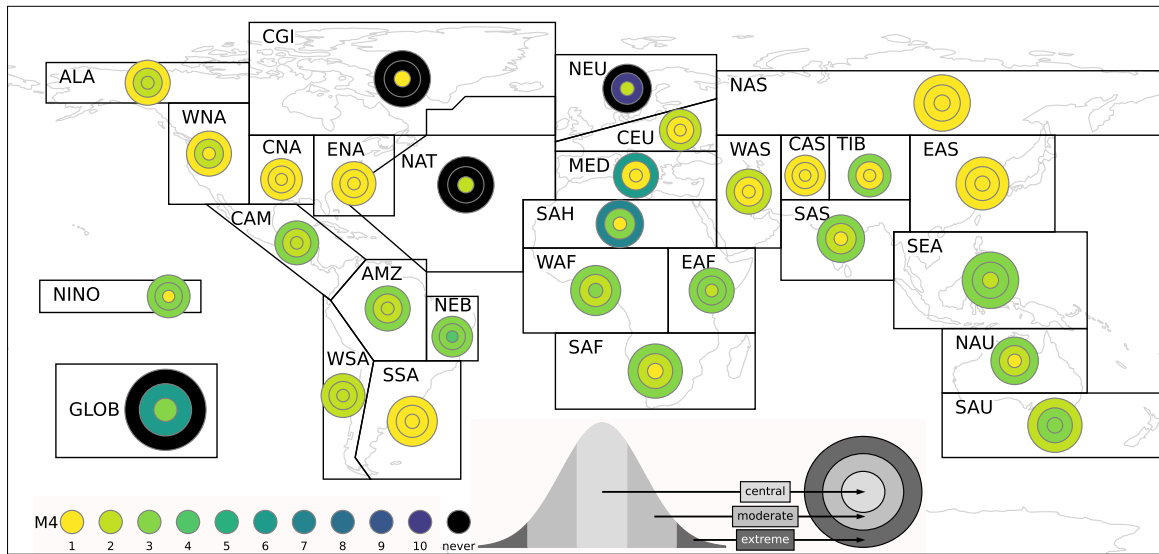


Figure S5. Forecast year at which baseline and merged distributions are indistinguishable based on M4 (ks-test). The first forecast year at which both distributions are non-significantly different from each other has been determined the following: For each forecast year, the percentage of all quantiles with p-values greater than 0.05 is calculated. The value shown is the first year for which at least 50% of all p-values are greater than 0.05 and all following forecast years have at least 50% p-values larger than 0.05. Due to the small sample size this criterion can be violated for one (but not more) subsequent forecast years (meaning that the percentage of p-values greater than 0.05 can be below 50%).

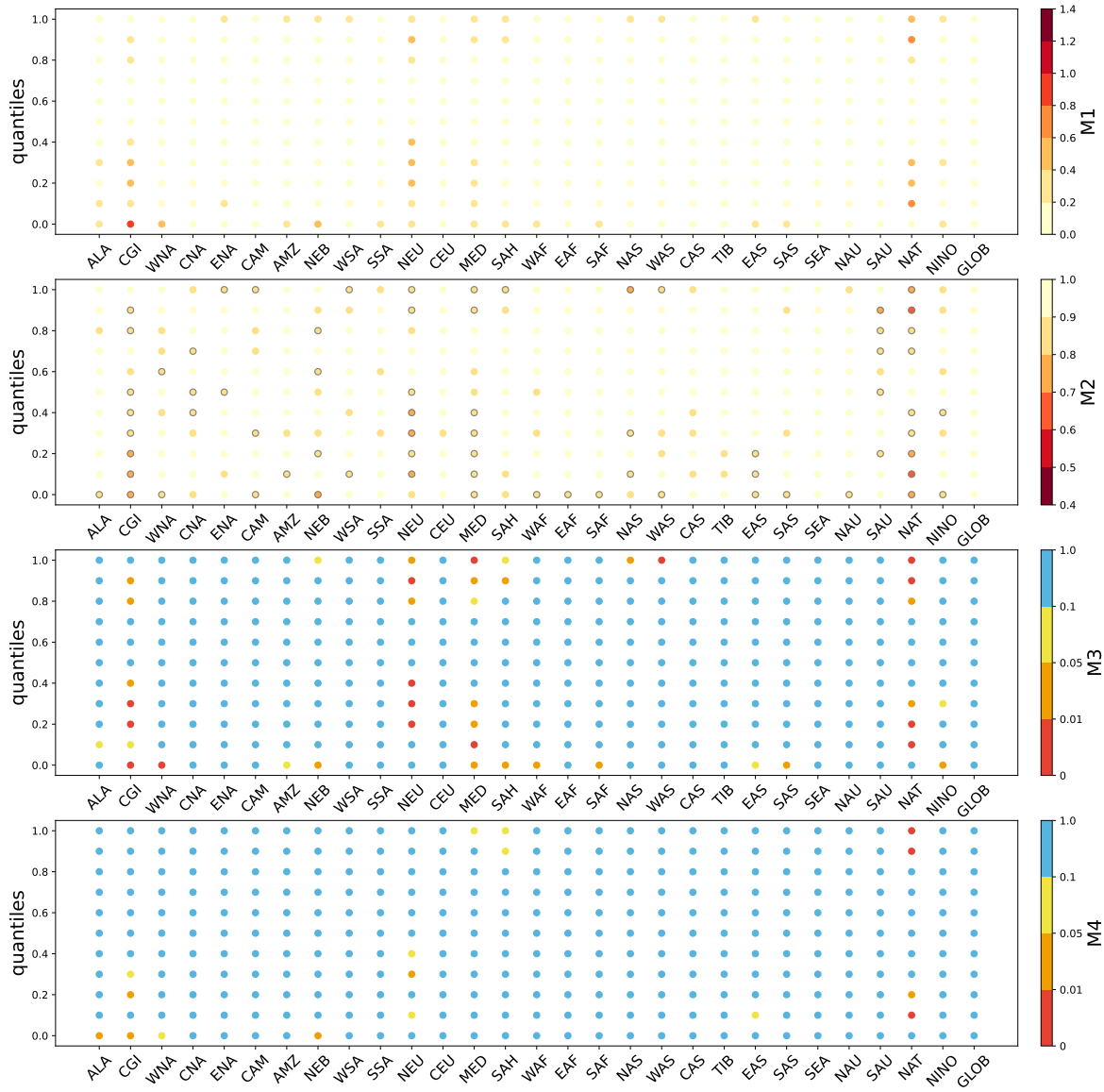


Figure S6. As Fig. S1 but for calibrated decadal predictions and calibrated climate projections.

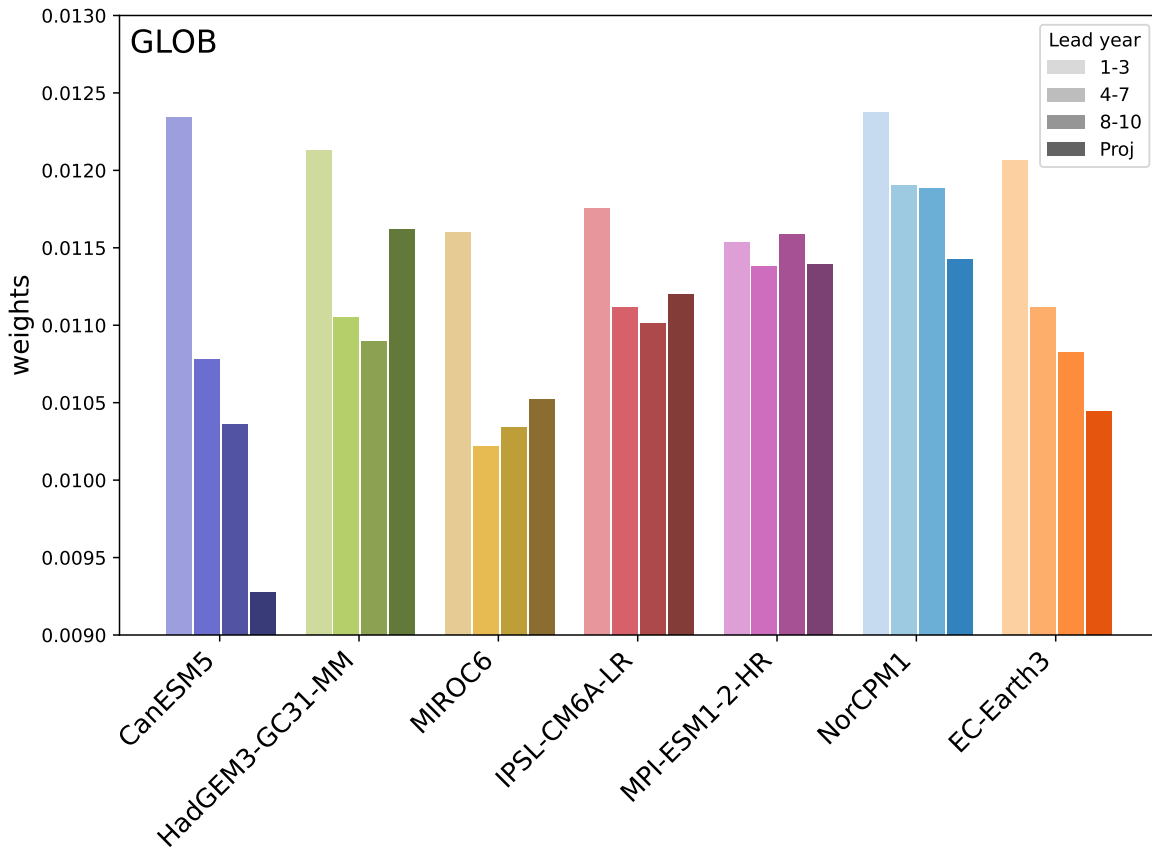


Figure S7. Weights (1/distance) for the global (GLOB) case for the different models used in this study. Weights for the predictions are aggregated for lead-years 1-3, 4-7 and 8-10.

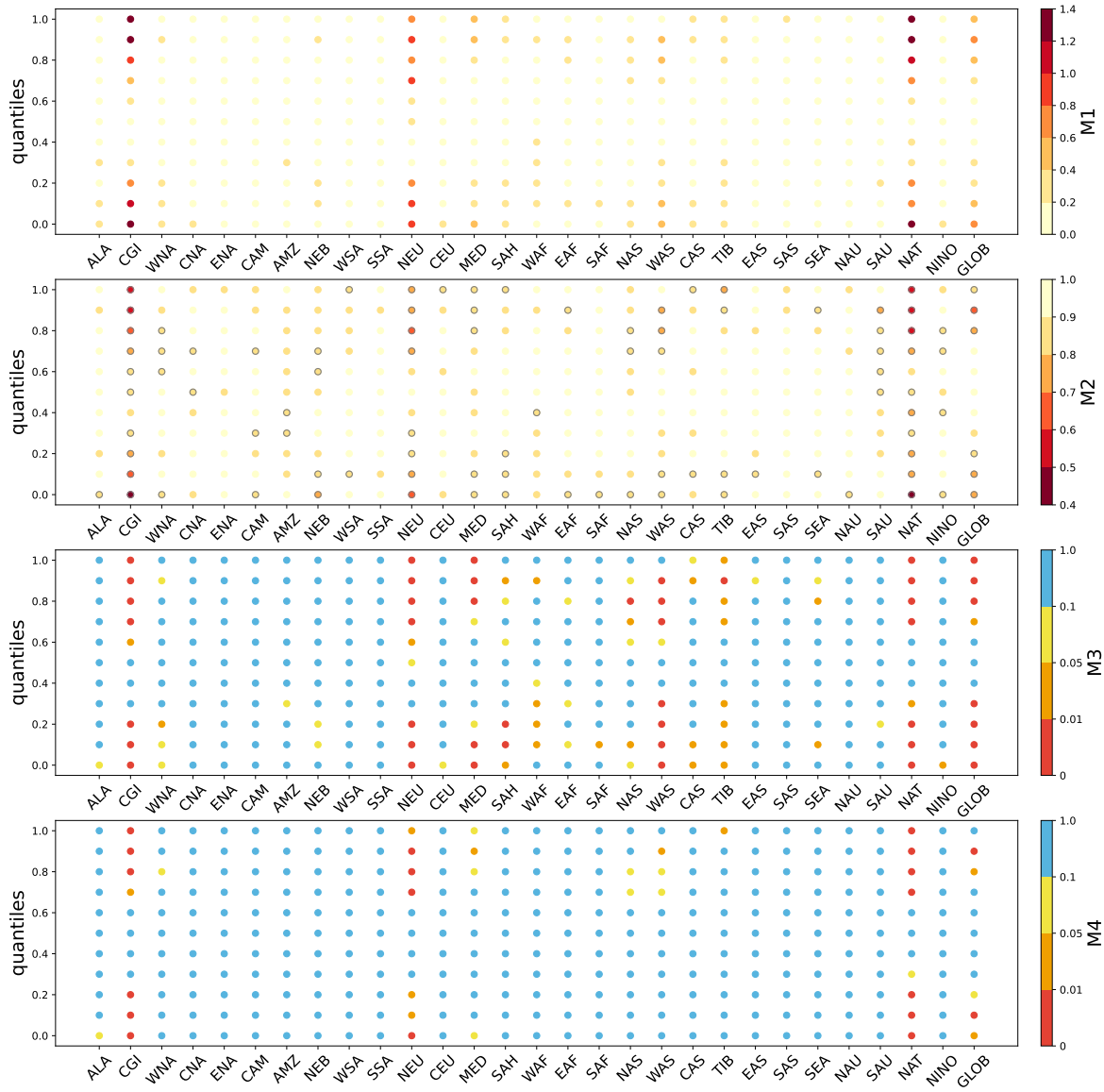


Figure S8. As Fig. S1 but for weighted decadal predictions and weighted climate projections.

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